

# Timed CTL

## Lecture #15 of Advanced Model Checking

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## Timelock, time-divergence and Zenoness

- A path is *time-divergent* if its execution time is infinite

$$ExecTime(s_0 \xrightarrow{d_0} s_1 \xrightarrow{d_1} \dots) = \sum_{i=0} d_i = \infty$$

- $TA$  is *timelock-free* if no state in  $Reach(TS(TA))$  contains a timelock  
a state contains a timelock whenever no time-divergent paths emanate from it
- $TA$  is *non-Zeno* if there does not exist an initial Zeno path in  $TS(TA)$   
a path is Zeno if it is time-convergent and performs infinitely many actions

## Timed CTL

Syntax of TCTL *state-formulas* over  $AP$  and set  $C$ :

$$\Phi ::= \text{true} \mid a \mid g \mid \Phi \wedge \Phi \mid \neg \Phi \mid \exists \varphi \mid \forall \varphi$$

where  $a \in AP$ ,  $g \in ACC(C)$  and  $\varphi$  is a path-formula defined by:

$$\varphi ::= \diamond^J \Phi$$

where  $J \subseteq \mathbb{R}_{\geq 0}$  is an interval whose bounds are naturals

$\diamond^J \Phi$  asserts that a  $\Phi$ -state is reached at time instant  $t \in J$

Forms of  $J$ :  $[n, m]$ ,  $(n, m]$ ,  $[n, m)$  or  $(n, m)$  for  $n, m \in \mathbb{N}$  and  $n \leq m$

for right-open intervals,  $m = \infty$  is also allowed

## Some abbreviations

“Always” is obtained in the following way:

$$\exists \square^J \Phi = \neg \forall \diamond^J \neg \Phi \quad \text{and} \quad \forall \square^J \Phi = \neg \exists \diamond^J \neg \Phi$$

$\exists \square^J \Phi$  asserts that for some path during the interval  $J$ ,  $\Phi$  holds

$\forall \square^J \Phi$  requires this to hold for all paths

Standard  $\square$  and  $\diamond$ -operator are obtained as follows:

$$\diamond \Phi = \diamond^{[0, \infty)} \Phi \quad \text{and} \quad \square \Phi = \square^{[0, \infty)} \Phi$$

# Timed properties in TCTL

## Semantics of TCTL

For state  $s = \langle \ell, \eta \rangle$  in  $TS(TA)$  the satisfaction relation  $\models$  is defined by:

$$s \models \text{true}$$

$$s \models a \quad \text{iff} \quad a \in L(\ell)$$

$$s \models g \quad \text{iff} \quad \eta \models g$$

$$s \models \neg \Phi \quad \text{iff} \quad \text{not } s \models \Phi$$

$$s \models \Phi \wedge \Psi \quad \text{iff} \quad (s \models \Phi) \text{ and } (s \models \Psi)$$

$$s \models \exists \varphi \quad \text{iff} \quad \pi \models \varphi \text{ for some } \pi \in \text{Paths}_{\text{div}}(s)$$

$$s \models \forall \varphi \quad \text{iff} \quad \pi \models \varphi \text{ for all } \pi \in \text{Paths}_{\text{div}}(s)$$

path quantification over time-divergent paths only

## The $\Longrightarrow$ relation

For infinite path fragments in  $TS(TA)$  performing  $\infty$  many actions let:

$$s_0 \xrightarrow{d_0} s_1 \xrightarrow{d_1} s_2 \xrightarrow{d_2} \dots \quad \text{with } d_0, d_1, d_2 \dots \geq 0$$

denote the equivalence class containing all infinite path fragments induced by execution fragments of the form:

$$s_0 \underbrace{\xrightarrow{d_0^1} \dots \xrightarrow{d_0^{k_0}}}_{\substack{\text{time passage of} \\ d_0 \text{ time-units}}} s_0 + d_0 \xrightarrow{\alpha_1} s_1 \underbrace{\xrightarrow{d_1^1} \dots \xrightarrow{d_1^{k_1}}}_{\substack{\text{time passage of} \\ d_1 \text{ time-units}}} s_1 + d_1 \xrightarrow{\alpha_2} s_2 \underbrace{\xrightarrow{d_2^1} \dots \xrightarrow{d_2^{k_2}}}_{\substack{\text{time passage of} \\ d_2 \text{ time-units}}} s_2 + d_2 \xrightarrow{\alpha_3} \dots$$

where  $k_i \in \mathbb{N}$ ,  $d_i \in \mathbb{R}_{\geq 0}$  and  $\alpha_i \in Act$  such that  $\sum_{j=1}^{k_i} d_i^j = d_i$ .

For  $\pi \in s_0 \xrightarrow{d_0} s_1 \xrightarrow{d_1} \dots$  we have  $ExecTime(\pi) = \sum_{i \geq 0} d_i$

## Semantics of TCTL

For time-divergent path  $\pi \in s_0 \xRightarrow{d_0} s_1 \xRightarrow{d_1} \dots$ , we have

$\pi \models \Phi \cup^J \Psi$  iff  $\exists i \geq 0. s_i + d \models \Psi$  for some  $d \in [0, d_i]$  with

$$\sum_{k=0}^{i-1} d_k + d \in J \quad \text{and}$$

$\forall j \leq i. s_j + d' \models \Phi \vee \Psi$  for any  $d' \in [0, d_j]$  with

$$\sum_{k=0}^{j-1} d_k + d' \leq \sum_{k=0}^{i-1} d_k + d$$

where for  $s_i = \langle \ell_i, \eta_i \rangle$  and  $d \geq 0$  we have  $s_i + d = \langle \ell_i, \eta_i + d \rangle$



## TCTL-semantics for timed automata

- Let  $TA$  be a timed automaton with clocks  $C$  and locations  $Loc$
- For TCTL-state-formula  $\Phi$ , the *satisfaction set*  $Sat(\Phi)$  is defined by:

$$Sat(\Phi) = \{ s \in Loc \times Eval(C) \mid s \models \Phi \}$$

- $TA$  satisfies TCTL-formula  $\Phi$  iff  $\Phi$  holds in all initial states of  $TA$ :

$$TA \models \Phi \quad \text{if and only if} \quad \forall \ell_0 \in Loc_0. \langle \ell_0, \eta_0 \rangle \models \Phi$$

where  $\eta_0(x) = 0$  for all  $x \in C$

# Example

## Timed CTL versus CTL

- Due to ignoring time-convergent paths in TCTL semantics possibly:

$$\underbrace{TS(TA) \models_{\text{TCTL}} \forall \varphi}_{\text{TCTL semantics}} \quad \text{but} \quad \underbrace{TS(TA) \not\models_{\text{CTL}} \forall \varphi}_{\text{CTL semantics}}$$

- CTL semantics considers all paths, timed CTL only time-divergent paths

- For  $\Phi = \forall \square (on \longrightarrow \forall \diamond off)$  and the light switch

$$TS(Switch) \models_{\text{TCTL}} \Phi \quad \text{whereas} \quad TS(TA) \not\models_{\text{CTL}} \Phi$$

- there are time-convergent paths on which location *on* is never left

## Characterizing timelock

- TCTL semantics is also well-defined for  $TA$  with timelock
- A state contains a timelock whenever no time-divergent paths emanate from it
- A state is *timelock-free* if and only if it satisfies  $\exists \Box \text{true}$ 
  - some time-divergent path satisfies  $\Box \text{true}$ , i.e., there is  $\geq 1$  time-divergent path
  - note: for fair CTL, the states in which a fair path starts also satisfy  $\exists \Box \text{true}$
- $TA$  is timelock-free iff  $\forall s \in \text{Reach}(TS(TA)): s \models \exists \Box \text{true}$
- Timelocks can thus be checked by a timed CTL formula

## TCTL model checking

- TCTL model-checking problem:  $TA \models \Phi$  for non-zeno  $TA$

$$\underbrace{TA \models \Phi}_{\text{timed automaton}} \quad \text{iff} \quad \underbrace{TS(TA) \models \Phi}_{\text{infinite transition system}}$$

- timelocks in  $TA$  are irrelevant as their presence can be checked
- Idea: consider a finite quotient of  $TS(TA)$  wrt. a bisimulation
  - $TS(TA) / \cong$  is a *region* transition system and denoted  $RTS(TA)$
  - dependence on  $\Phi$  is ignored for the moment . . .
- Transform TCTL formula  $\Phi$  into an “equivalent” CTL-formula  $\hat{\Phi}$
- Then:  $TA \models_{\text{TCTL}} \Phi$  iff  $\underbrace{RTS(TA)}_{\text{finite transition system}} \models_{\text{CTL}} \hat{\Phi}$

## Eliminating timing parameters

- Eliminate all intervals  $J \neq [0, \infty)$  from TCTL formulas
  - introduce a fresh clock,  $z$  say, that does not occur in  $TA$
  - $s \models \exists \Diamond^J \Phi$  iff reset  $z$  in  $s \models z \in J \wedge \Phi$
  - deal with  $\exists \Box^J \Phi$ ,  $\forall \Diamond^J \Phi$ , and  $\forall \Box^J \Phi$  in a similar way
- Formally: for any state  $s$  of  $TS(TA)$  it holds:

$$s \models \exists \Diamond^J \Phi \quad \text{iff} \quad \underbrace{s\{z := 0\}}_{\text{state in } TS(TA \oplus z)} \models \exists \Diamond((z \in J) \wedge \Phi)$$

- where  $TA \oplus z$  is  $TA$  (over  $C$ ) extended with  $z \notin C$
- E.g.,  $\exists \Box^{\leq 2} \Phi$  yields  $\exists \Box((z \leq 2) \rightarrow \Phi)$

atomic clock constraints are atomic propositions, i.e., a CTL formula results

## Clock equivalence

Impose an equivalence, denoted  $\cong$ , on the clock valuations such that:

- (A) Equivalent clock valuations satisfy the same clock constraints  $g$  in  $TA$  and  $\Phi$ :

$$\eta \cong \eta' \Rightarrow (\eta \models g \text{ iff } \eta' \models g)$$

- **no** diagonal clock constraints are considered
- all the constraints in  $TA$  and  $\Phi$  are thus either of the form  $x \leq c$  or  $x < c$

- (B) Time-divergent paths emanating from equivalent states are “equivalent”

- this property guarantees that equivalent states satisfy the same path formulas

- (C) The number of equivalence classes under  $\cong$  is finite

## Clock equivalence

- Correctness criteria (A) and (B) are ensured if equivalent states:
  - agree on the integer parts of all clock values, and
  - agree on the ordering of the fractional parts of all clocks

⇒ This yields a denumerable infinite set of equivalence classes

- Observe that:
  - if clocks exceed the maximal constant with which they are compared their precise value is not of interest

⇒ The number of equivalence classes is then finite (C)



## Basic recipe of TCTL model checking

*Input:* timed automaton  $TA$  and TCTL formula  $\Phi$  (both over  $AP$  and  $C$ )

*Output:*  $TA \models \Phi$

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$\hat{\Phi} :=$  eliminate the timing parameters from  $\Phi$ ;

determine the equivalence classes under  $\cong$ ;

construct the region transition system  $TS = RTS(TA)$ ;

apply the CTL model-checking algorithm to check  $TS \models \hat{\Phi}$ ;

$TA \models \Phi$  if and only if  $TS \models \hat{\Phi}$

how does clock equivalence look like?

## First observation

- $\eta \models x < c$  whenever  $\eta(x) < c$ , or equivalently,  $\lfloor \eta(x) \rfloor < c$ 
  - $\lfloor d \rfloor = \max\{c \in \mathbb{N} \mid c \leq d\}$  and  $\text{frac}(d) = d - \lfloor d \rfloor$
- $\eta \models x \leq c$  whenever  $\lfloor \eta(x) \rfloor < c$  or  $\lfloor \eta(x) \rfloor = c$  and  $\text{frac}(x) = 0$

$\Rightarrow \eta \models g$  only depends on  $\lfloor \eta(x) \rfloor$ , and whether  $\text{frac}(\eta(x)) = 0$

- Initial suggestion: clock valuations  $\eta$  and  $\eta'$  are equivalent if:

$$\lfloor \eta(x) \rfloor = \lfloor \eta'(x) \rfloor \quad \text{and} \quad \text{frac}(\eta(x)) = 0 \text{ iff } \text{frac}(\eta'(x)) = 0$$

- **Note:** it is crucial that in  $x < c$  and  $x \leq c$ ,  $c$  is a natural

# Example

## Second observation

- Consider location  $\ell$  with  $Inv(\ell) = \text{true}$  and only outgoing transitions:
  - one guarded with  $x \geq 2$  (action  $\alpha$ ) and  $y > 1$  (action  $\beta$ )
- Let state  $s = \langle \ell, \eta \rangle$  with  $1 < \eta(x) < 2$  and  $0 < \eta(y) < 1$ 
  - $\alpha$  and  $\beta$  are disabled, only time may elapse
- Transition that is enabled next depends on  $x < y$  or  $x \geq y$ 
  - e.g., if  $\text{frac}(\eta(x)) \geq \text{frac}(\eta(y))$ , action  $\alpha$  is enabled first
- Suggestion for strengthening of initial proposal for all  $x, y \in C$  by:

$$\text{frac}(\eta(x)) \leq \text{frac}(\eta(y)) \quad \text{if and only if} \quad \text{frac}(\eta'(x)) \leq \text{frac}(\eta'(y))$$

# Example

## Final observation

- So far, clock equivalence yield a denumerable though not finite quotient
  - For  $TA \models \Phi$  only the clock constraints in  $TA$  and  $\Phi$  are relevant
    - let  $c_x \in \mathbb{N}$  the *largest constant* with which  $x$  is compared in  $TA$  or  $\Phi$
- $\Rightarrow$  If  $\eta(x) > c_x$  then the actual value of  $x$  is irrelevant
- constraints on  $\cong$  so far are only relevant for clock values of  $x$  ( $y$ ) up to  $c_x$  ( $c_y$ )

## Clock equivalence

Clock valuations  $\eta, \eta' \in Eval(C)$  are *equivalent*, denoted  $\eta \cong \eta'$ , if:

(1) for any  $x \in C$ :  $(\eta(x) > c_x) \wedge (\eta'(x) > c_x)$  or  $(\eta(x) \leq c_x) \wedge (\eta'(x) \leq c_x)$

(2) for any  $x \in C$ : if  $\eta(x), \eta'(x) \leq c_x$  then:

$$\lfloor \eta(x) \rfloor = \lfloor \eta'(x) \rfloor \quad \text{and} \quad frac(\eta(x)) = 0 \text{ iff } frac(\eta'(x)) = 0$$

(3) for any  $x, y \in C$ : if  $\eta(x), \eta'(x) \leq c_x$  and  $\eta(y), \eta'(y) \leq c_y$ , then:

$$frac(\eta(x)) \leq frac(\eta(y)) \quad \text{iff} \quad frac(\eta'(x)) \leq frac(\eta'(y)).$$

$$s \cong s' \quad \text{iff} \quad \ell = \ell' \quad \text{and} \quad \eta \cong \eta'$$

## Regions

- The *clock region* of  $\eta \in Eval(C)$ , denoted  $[\eta]$ , is defined by:

$$[\eta] = \{ \eta' \in Eval(C) \mid \eta \cong \eta' \}$$

- The *state region* of  $s = \langle \ell, \eta \rangle \in TS(TA)$  is defined by:

$$[s] = \langle \ell, [\eta] \rangle = \{ \langle s, \eta' \rangle \mid \eta' \in [\eta] \}$$



# Example