

# On-The-Fly Partial Order Reduction

## Lecture #11 of Advanced Model Checking

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## Outline of partial-order reduction

- During state space generation obtain  $\widehat{TS}$ 
  - a *reduced version* of transition system  $TS$  such that  $\widehat{TS} \triangleq TS$
  - $\Rightarrow$  this preserves all stutter sensitive LT properties, such as  $LTL_{\setminus O}$
  - at state  $s$  select a (small) subset of enabled actions in  $s$
  - different approaches on how to select such set: consider Peled's *ample sets*
- *Static* partial-order reduction
  - obtain a high-level description of  $\widehat{TS}$  (without generating  $TS$ )
  - $\Rightarrow$  POR is preprocessing phase of model checking
- *Dynamic (or: on-the-fly)* partial-order reduction
  - construct  $\widehat{TS}$  during  $LTL_{\setminus O}$  model checking
  - if accept cycle is found, there is no need to generate entire  $\widehat{TS}$

## Ample-set conditions for LTL

(A1) **Nonemptiness condition**

$$\emptyset \neq \text{ample}(s) \subseteq \text{Act}(s)$$

(A2) **Dependency condition**

Let  $s \xrightarrow{\beta_1} \dots \xrightarrow{\beta_n} s_n \xrightarrow{\alpha} t$  be a finite execution fragment in  $TS$  such that  $\alpha$  depends on  $\text{ample}(s)$ . Then:  $\beta_i \in \text{ample}(s)$  for some  $0 < i \leq n$ .

(A3) **Stutter condition**

If  $\text{ample}(s) \neq \text{Act}(s)$  then any  $\alpha \in \text{ample}(s)$  is a stutter action.

(A4) **Cycle condition**

For any cycle  $s_0 s_1 \dots s_n$  in  $\widehat{TS}$  and  $\alpha \in \text{Act}(s_i)$ , for any  $0 < i \leq n$ , there exists  $j \in \{1, \dots, n\}$  such that  $\alpha \in \text{ample}(s_j)$ .

## Correctness theorem

For action-deterministic, finite  $TS$  without terminal states:  
if conditions (A1) through (A4) are satisfied, then  $\widehat{TS} \triangleq TS$ .

## Strong cycle condition

### (A4') Strong cycle condition

On any cycle  $s_0 s_1 \dots s_n$  in  $\widehat{TS}$ ,  
there exists  $j \in \{1, \dots, n\}$  such that  $ample(s_j) = Act(s_j)$ .

- If (A1) through (A3) hold: (A4') implies the cycle condition (A4)
- (A4') can be checked easily in DFS when backward edge is found

## The branching-time ample approach

- Linear-time ample approach:

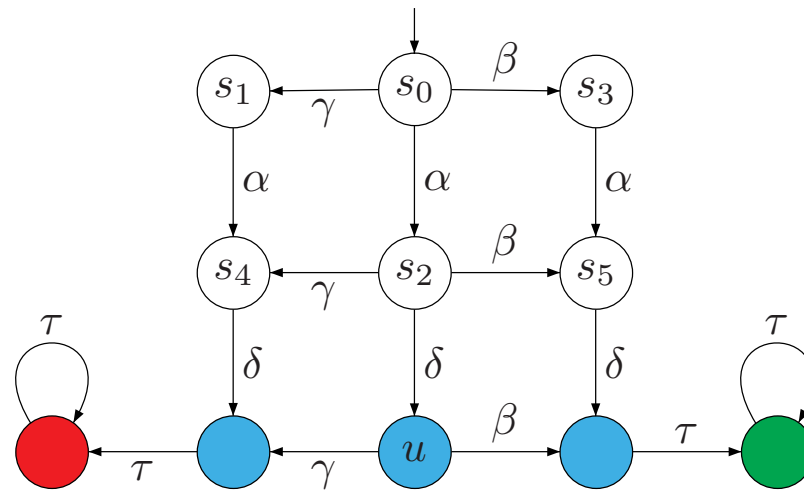
- during state space generation obtain  $\widehat{TS}$  such that  $\widehat{TS} \triangleq TS$
- $\Rightarrow$  this preserves all stutter sensitive LT properties, such as  $LTL_{\setminus \circ}$
- static partial order reduction: generate  $\widehat{TS}$  prior to verification
- on-the-fly partial order reduction: generate  $\widehat{TS}$  during the verification
- generation of  $\widehat{TS}$  by means of static analysis of program graphs

- Branching-time ample approach

- during state space generation obtain  $\widehat{TS}$  such that  $\widehat{TS} \approx^{div} TS$
- $\Rightarrow$  this preserves all  $CTL_{\setminus \circ}$  and  $CTL_{\setminus \circ}^*$  formulas
- static partial order reduction only

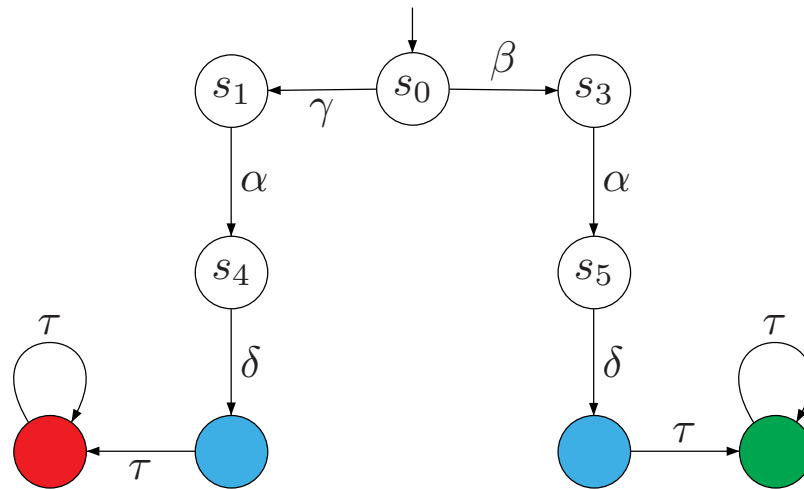
as  $\approx^{div}$  is strictly finer than  $\triangleq$ , try (A1) through (A4)

# Example



transition system  $TS$

## Conditions (A1)-(A4) are insufficient



$\widehat{TS} \models \forall \square \left( a \rightarrow (\forall \diamond b \vee \forall \diamond c) \right)$  but  $TS$  does not and thus  $\widehat{TS} \not\approx^{div} TS$

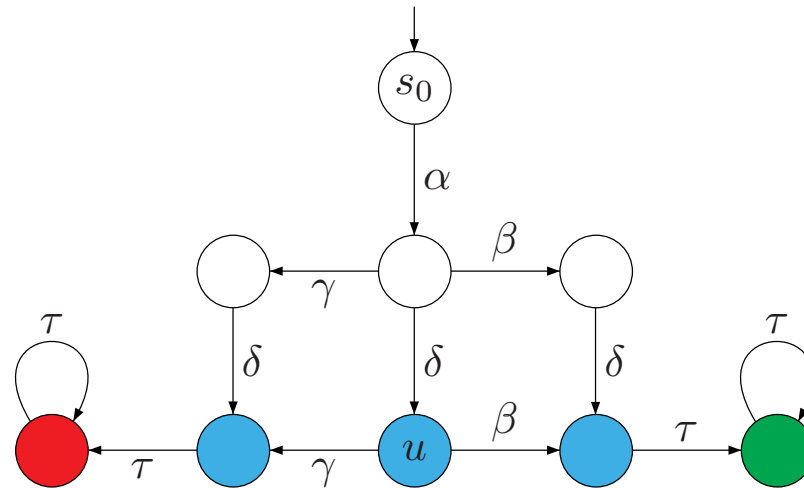


## Branching condition

**(A5)**

If  $\text{ample}(s) \neq \text{Act}(s)$  then  $|\text{ample}(s)| = 1$

## A sound reduction for $CTL_{\setminus O}^*$



$\widehat{TS} \not\models \forall \square \left( a \rightarrow (\forall \diamond b \vee \forall \diamond c) \right)$  and  $TS$  does not ; in fact  $\widehat{TS} \approx^{div} TS$

## Correctness theorem

For action-deterministic, finite  $TS$  without terminal states:  
if conditions (A1) through (A5) are satisfied, then  $\widehat{TS} \approx^{div} TS$ .

recall that this implies that  $\widehat{TS}$  and  $TS$  are  $CTL_{\setminus O}^*$ -equivalent

## Ample-set conditions for CTL\*

(A1) **Nonemptiness condition**

$$\emptyset \neq ample(s) \subseteq Act(s)$$

(A2) **Dependency condition**

Let  $s \xrightarrow{\beta_1} \dots \xrightarrow{\beta_n} s_n \xrightarrow{\alpha} t$  be a finite execution fragment in  $TS$  such that  $\alpha$  depends on  $ample(s)$ . Then:  $\beta_i \in ample(s)$  for some  $0 < i \leq n$ .

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If  $ample(s) \neq Act(s)$  then any  $\alpha \in ample(s)$  is a stutter action.

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For any cycle  $s_0 s_1 \dots s_n$  in  $\widehat{TS}$  and  $\alpha \in Act(s_i)$ , for some  $0 < i \leq n$ , there exists  $j \in \{1, \dots, n\}$  such that  $\alpha \in ample(s_j)$ .

(A5) **Branching condition**

If  $ample(s) \neq Act(s)$  then  $|ample(s)| = 1$