

Compiler Construction

Lecture 16: Code Generation I (Intermediate Code)

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(Software Modeling and Verification)

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Summer Semester 2012

Online Registration for Seminars and Practical Courses (Praktika) in Winter Term 2012/13

Who?

- Students of:
- Master Courses
 - Bachelor Informatik (~~Pro~~Seminar!)

Where?

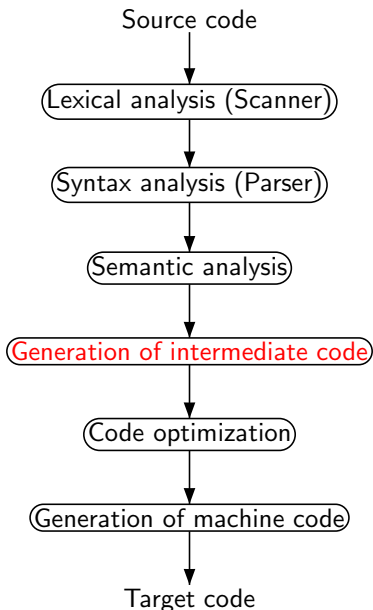
web-info8.informatik.rwth-aachen.de/apse

When?

18.06.2012 - 01.07.2012

- 1 Generation of Intermediate Code
- 2 The Example Programming Language EPL
- 3 Semantics of EPL
- 4 Intermediate Code for EPL
- 5 The Procedure Stack

Conceptual Structure of a Compiler



Modularization of Code Generation I

Splitting of code generation for programming language PL:

$$PL \xrightarrow{\text{trans}} IC \xrightarrow{\text{code}} MC$$

Frontend: **trans** generates **machine-independent intermediate code** (IC)
for abstract (stack) machine

Backend: **code** generates **actual machine code** (MC)

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Advantages: IC machine independent \implies

Portability: much easier to write IC compiler/interpreter for a new machine (as opposed to rewriting the whole compiler)

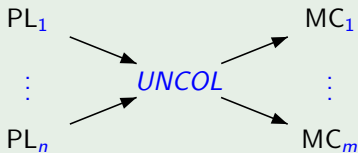
Fast compiler implementation: generating IC much easier than generating MC

Code size: IC programs usually smaller than corresponding MC programs

Code optimization: division into machine-independent and machine-dependent parts

Example 16.1

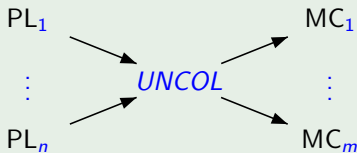
- ① UNiversal Computer-Oriented Language (UNCOL; \approx 1960;
<http://en.wikipedia.org/wiki/UNCOL>):
universal intermediate language for compilers (never fully specified or
implemented; too ambitious)



only $n + m$ translations
(in place of $n \cdot m$)

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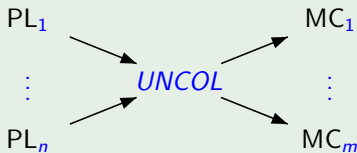


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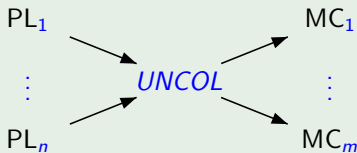


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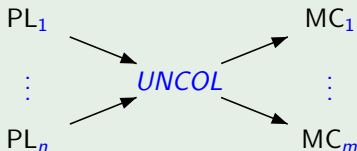


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- 5 Common Intermediate Language (CIL; Microsoft .NET; \approx 2002;
http://en.wikipedia.org/wiki/Common_Intermediate_Language)

Structures in high-level programming languages:

- Basic data types and basic operations
- Static and dynamic data structures
- Expressions and assignments
- Control structures (sequences, branching statements, loops, ...)
- Procedures and functions
- Modularity: blocks, modules, and classes

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Use of procedures and blocks:

- FORTRAN: non-recursive and non-nested procedures
 - ⇒ **static** memory management (requirements determined at compile time)
- C: recursive and non-nested procedures
 - ⇒ dynamic memory management using **runtime stack** (requirements only known at runtime), no static links
- Algol-like languages (Pascal, Modula): recursive and nested procedures
 - ⇒ dynamic memory management using **runtime stack with static links**
- Object-oriented languages (C++, Java): object creation and removal
 - ⇒ dynamic memory management using **heap**

Structures in machine code: (von Neumann/SISD)

Memory hierarchy: accumulators, registers, cache, main memory, background storage

Instruction types: arithmetic/Boolean/... operation, test/jump instruction, transfer instruction, I/O instruction, ...

Addressing modes: direct/indirect, absolute/relative, ...

Architectures: RISC (few [fast but simple] instructions, many registers), CISC (many [complex but slow] instructions, few registers)

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Structures in intermediate code:

- **Data types and operations** like PL
- **Data stack** with basic operations
- **Jumping instructions** for control structures
- **Runtime stack** for blocks, procedures, and static data structures
- **Heap** for dynamic data structures

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Structures of EPL:

- Only integer and Boolean **values**
- Arithmetic and Boolean **expressions** with strict and non-strict semantics
- **Control structures**: sequence, branching, iteration
- Nested **blocks** and recursive **procedures** with local and global variables (\Rightarrow dynamic memory management using runtime stack with static links)
- (not considered: procedure **parameters** and [dynamic] **data structures**)

Definition 16.2 (Syntax of EPL)

The **syntax of EPL** is defined as follows:

$\mathbb{Z} :$ z (* z is an integer *)

$Ide :$ I (* I is an identifier *)

$AExp :$ $A ::= z \mid I \mid A_1 + A_2 \mid \dots$

$BExp :$ $B ::= A_1 < A_2 \mid \text{not } B \mid B_1 \text{ and } B_2 \mid B_1 \text{ or } B_2$

$Cmd :$ $C ::= I := A \mid C_1 ; C_2 \mid \text{if } B \text{ then } C_1 \text{ else } C_2 \mid$
 $\text{while } B \text{ do } C \mid I()$

$Dcl :$ $D ::= D_C D_V D_P$

$D_C ::= \varepsilon \mid \text{const } l_1 := z_1, \dots, l_n := z_n;$

$D_V ::= \varepsilon \mid \text{var } l_1, \dots, l_n;$

$D_P ::= \varepsilon \mid \text{proc } l_1; K_1; \dots; \text{proc } l_n; K_n;$

$Blk :$ $K ::= D C$

$Pgm :$ $P ::= \text{in/out } l_1, \dots, l_n; K.$

Example 16.3 (Factorial function)

```
in/out x;  
var y;  
proc F;  
    if x > 1 then  
        y := y * x;  
        x := x - 1;  
        F()  
    y := 1;  
    F();  
    x := y.
```

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- **Multiple declarations** of an identifier in different blocks are possible. Each usage in a command C refers to the **“innermost” declaration**.
- **Static scoping**: the usage of an identifier in the body of a called procedure refers to its declaration environment (and not to its calling environment).

Example 16.4

```
in/out x;  
const c = 10;  
var y;  
proc P;  
    var y, z;  
    proc Q;  
        var x, z;  
        [... z := 1; P() ...]  
    [... P() ... R() ...]  
proc R;  
    [... P() ...]  
[... x := 0; P() ...] .
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- “Innermost” principle

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- “Innermost” principle
- **Static scoping**: body of P can refer to x, y, z

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- “Innermost” principle
- Static scoping: body of **P** can refer to **x**, **y**, **z**
- **Later declaration**: call of **R** in **P** followed by declaration (in Pascal: **forward** declarations for one-pass compilation)

(omitting the details)

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 - composition $C_1; C_2$: sequential execution
 - branching **if** B **then** C_1 **else** C_2 : test of B , followed by jump to respective branch
 - iteration **while** B **do** C : execution of C as long as B is true
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- Consequently, an EPL program $P = \text{in/out } I_1, \dots, I_n; K. \in Pgm$ has as **semantics** a function

$$\mathfrak{M}[P] : \mathbb{Z}^n \dashrightarrow \mathbb{Z}^n$$

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Example 16.5 (Factorial function; cf. Example 16.3)

here $n = 1$ and $\mathfrak{M}[P](x) = x!$ (where $x! := 1$ for $x \leq 1$)

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Definition 16.6 (Abstract machine for EPL)

The **abstract machine for EPL (AM)** is defined by the **state space**

$$S := PC \times DS \times PS$$

with

- the **program counter** $PC := \mathbb{N}$,
- the **data stack** $DS := \mathbb{Z}^*$ (top of stack to the right), and
- the **procedure stack** (or: **runtime stack**) $PS := \mathbb{Z}^*$ (top of stack to the left).

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Thus a state $s = (l, d, p) \in S$ is given by

- a program label $l \in PC$,
- a data stack $d = d.r : \dots : d.1 \in DS$, and
- a procedure stack $p = p.1 : \dots : p.t \in PS$.

Definition 16.7 (AM instructions)

The set of **AM instructions** is divided into

arithmetic instructions: `ADD`, `MULT`, ...

Boolean instructions: `NOT`, `AND`, `OR`, `LT`, ...

jumping instructions: `JMP(ca)`, `JFALSE(ca)` ($ca \in PC$)

procedure instructions: `CALL(ca, dif, loc)` ($ca \in PC$, $dif, loc \in \mathbb{N}$), `RET`

transfer instructions: `LOAD(dif, off)`, `STORE(dif, off)` ($dif, off \in \mathbb{N}$),
`LIT(z)` ($z \in \mathbb{Z}$)

Definition 16.8 (Semantics of AM instructions (1st part))

The **semantics of an AM instruction** O

$$\llbracket O \rrbracket : S \dashrightarrow S$$

is defined as follows:

$$\llbracket \text{ADD} \rrbracket(l, d : z_1 : z_2, p) := (l + 1, d : z_1 + z_2, p)$$

$$\llbracket \text{NOT} \rrbracket(l, d : b, p) := (l + 1, d : \neg b, p) \quad \text{if } b \in \{0, 1\}$$

$$\llbracket \text{AND} \rrbracket(l, d : b_1 : b_2, p) := (l + 1, d : b_1 \wedge b_2, p) \quad \text{if } b_1, b_2 \in \{0, 1\}$$

$$\llbracket \text{OR} \rrbracket(l, d : b_1 : b_2, p) := (l + 1, d : b_1 \vee b_2, p) \quad \text{if } b_1, b_2 \in \{0, 1\}$$

$$\llbracket \text{LT} \rrbracket(l, d : z_1 : z_2, p) := \begin{cases} (l + 1, d : 1, p) & \text{if } z_1 < z_2 \\ (l + 1, d : 0, p) & \text{if } z_1 \geq z_2 \end{cases}$$

$$\llbracket \text{JMP}(ca) \rrbracket(l, d, p) := (ca, d, p)$$

$$\llbracket \text{JFALSE}(ca) \rrbracket(l, d : b, p) := \begin{cases} (ca, d, p) & \text{if } b = 0 \\ (l + 1, d, p) & \text{if } b = 1 \end{cases}$$

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Structure of Procedure Stack I

The semantics of procedure and transfer instructions requires a particular structure of the procedure stack $p \in PS$: it must be composed of **frames** (or: **activation records**) of the form

$$sl : dl : ra : v_1 : \dots : v_k$$

where

static link sl : points to frame of surrounding declaration environment
 \Rightarrow used to access non-local variables

dynamic link dl : points to previous frame (i.e., of calling procedure)
 \Rightarrow used to remove topmost frame after termination of procedure call

return address ra : program label after termination of procedure call
 \Rightarrow used to continue program execution after termination of procedure call

local variables v_i : values of locally declared variables

- Frames are **created** whenever a procedure call is performed
- Two **special frames**:
 - I/O frame: for keeping values of **in/out** variables
($sl = dl = ra = 0$)
 - MAIN frame: for keeping values of top-level block
($sl = dl = \text{I/O frame}$)

Example 16.9 (cf. Example 16.4)

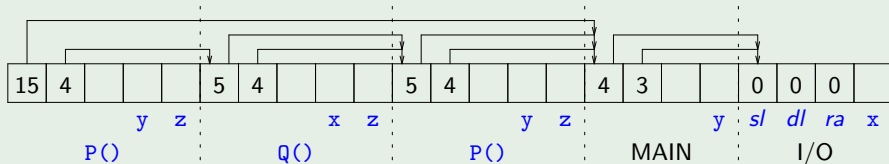
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proc R;  
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Structure of Procedure Stack III

Example 16.9 (cf. Example 16.4)

```
in/out x;  
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```

Procedure stack after second call of **P**:



Structure of Procedure Stack IV

Observation:

- The usage of a variable in a procedure body refers to its **innermost declaration**.
- If the level difference between the usage and the declaration is **dif**, then a **chain of dif static links** has to be followed to access the corresponding frame.

Structure of Procedure Stack IV

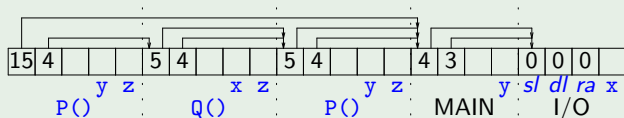
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  var y, z;  
  proc Q;  
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Procedure stack after second call of P:



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in/out x;
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const c = 10;
```

```
var y;
```

```
proc P;
```

```
    var y, z;
```

```
    proc Q;
```

```
        var x, z;
```

```
        [... P() ...]
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```
        [... x ... y ... Q() ...]
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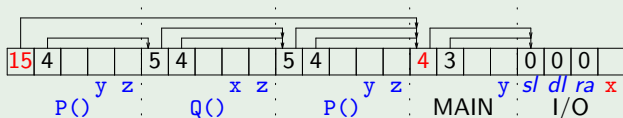
P uses x \Rightarrow **dif = 2**

```
proc R;
```

```
    [... P() ...]
```

```
    [... P() ...].
```

Procedure stack after second call of P:



Structure of Procedure Stack IV

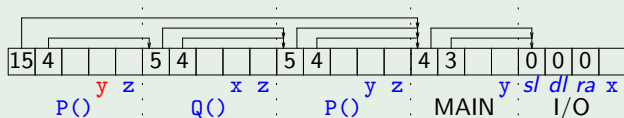
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Procedure stack after second call of P:



P uses y \Rightarrow dif = 0

The base Function

Upon procedure call, the static link information is computed by the following auxiliary function which, given a procedure stack and a level difference, determines the begin of the corresponding frame.

Definition 16.11 (base function)

The function

$$\text{base} : PS \times \mathbb{N} \dashrightarrow \mathbb{N}$$

is given by

$$\begin{aligned} \text{base}(p, 0) &:= 1 \\ \text{base}(p, dif + 1) &:= \text{base}(p, dif) + p.\text{base}(p, dif) \end{aligned}$$

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Example 16.12 (cf. Example 16.10)

In the second call of P (from Q): $\text{dif} = 2$

$$\text{base}(p, 0) = 1$$

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In the second call of P (from Q): $dif = 2$

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$$\begin{aligned} \text{base}(p, 0) &= 1 \\ \implies \text{base}(p, 1) &= 1 + p.1 = 6 \\ \implies \text{base}(p, 2) &= 6 + p.6 = 11 \end{aligned}$$

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Upon procedure call, the static link information is computed by the following auxiliary function which, given a procedure stack and a level difference, determines the begin of the corresponding frame.

Definition 16.11 (base function)

The function

$$\text{base} : PS \times \mathbb{N} \dashrightarrow \mathbb{N}$$

is given by

$$\begin{aligned} \text{base}(p, 0) &:= 1 \\ \text{base}(p, \text{dif} + 1) &:= \text{base}(p, \text{dif}) + p.\text{base}(p, \text{dif}) \end{aligned}$$

Example 16.12 (cf. Example 16.10)

In the second call of P (from Q): $\text{dif} = 2$

$$\begin{aligned} \text{base}(p, 0) &= 1 \\ \Rightarrow \text{base}(p, 1) &= 1 + p.1 = 6 \\ \Rightarrow \text{base}(p, 2) &= 6 + p.6 = 11 \end{aligned}$$

$$\Rightarrow sl = \text{base}(p, 2) + \underbrace{2}_{y,z} + \underbrace{2}_{ra,dl} = 15$$