

Concurrency Theory

Lecture 3: Hennessy-Milner Logic

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Lehrstuhl für Informatik 2
(Software Modeling and Verification)



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Winter Semester 2013/14

- ① Friday, 21.02.2014, 11:30–14:00, AH 2
- ② Tuesday, 25.03.2014, 10:00–12:30, AH 1

Online registration via CampusOffice is enabled.



- D-MiLS research project (<http://www.d-mils.org/>)
 - architectural specification of secure systems
 - modular high-assurance platform
 - framework for the certification of systems
 - basis: MILS-AADL specification language
- Task: implementation of compiler frontend
 - parser
 - semantic checker
 - based on ANTLR 3 definition of SLIM specification language (COMPASS project)
 - estimated effort: 10 h/week

1 Recap: Calculus of Communicating Systems

2 Infinite State Spaces

3 Process Traces

4 Hennessy-Milner Logic

5 Closure under Negation

Definition (Syntax of CCS)

- Let A be a set of (action) names.
- $\bar{A} := \{\bar{a} \mid a \in A\}$ denotes the set of co-names.
- $Act := A \cup \bar{A} \cup \{\tau\}$ is the set of actions where τ denotes the silent (or: unobservable) action.
- Let Pid be a set of process identifiers.
- The set Prc of process expressions is defined by the following syntax:

$P ::=$	nil	(inaction)
	$\alpha.P$	(prefixing)
	$P_1 + P_2$	(choice)
	$P_1 \parallel P_2$	(parallel composition)
	$P \setminus L$	(restriction)
	$P[f]$	(relabelling)
	C	(process call)

where $\alpha \in Act$, $L \subseteq A$, $C \in Pid$, and $f : Act \rightarrow Act$ such that $f(\tau) = \tau$ and $f(\bar{a}) = \bar{f(a)}$ for each $a \in A$.

Definition (continued)

- A **(recursive) process definition** is an equation system of the form

$$(C_i = P_i \mid 1 \leq i \leq k)$$

where $k \geq 1$, $C_i \in Pid$ (pairwise distinct), and $P_i \in Prc$ (with process identifiers from $\{C_1, \dots, C_k\}$).

Notational Conventions:

- \bar{a} means a
- $\sum_{i=1}^n P_i$ ($n \in \mathbb{N}$) means $P_1 + \dots + P_n$ (where $\sum_{i=1}^0 P_i := \text{nil}$)
- $P \setminus a$ abbreviates $P \setminus \{a\}$
- $[a_1 \mapsto b_1, \dots, a_n \mapsto b_n]$ stands for $f : Act \rightarrow Act$ with $f(a_i) = b_i$ ($i \in [n]$) and $f(\alpha) = \alpha$ otherwise
- restriction and relabelling bind stronger than prefixing, prefixing stronger than composition, composition stronger than choice:

$$P \setminus a + b.Q \parallel R \quad \text{means} \quad (P \setminus a) + ((b.Q) \parallel R)$$

Goal: represent behaviour of system by (infinite) graph

- nodes = system states
- edges = transitions between states

Definition (Labelled transition system)

A **(Act-)labelled transition system (LTS)** is a triple (S, Act, \rightarrow) consisting of

- a set S of **states**
- a set Act of **(action) labels**
- a **transition relation** $\rightarrow \subseteq S \times Act \times S$

For $(s, \alpha, s') \in \rightarrow$ we write $s \xrightarrow{\alpha} s'$. An LTS is called **finite** if S is so.

Remarks:

- sometimes an **initial state** $s_0 \in S$ is distinguished ("LTS(s_0)")
- (finite) LTSs correspond to (finite) **automata** without final states

Definition (Semantics of CCS)

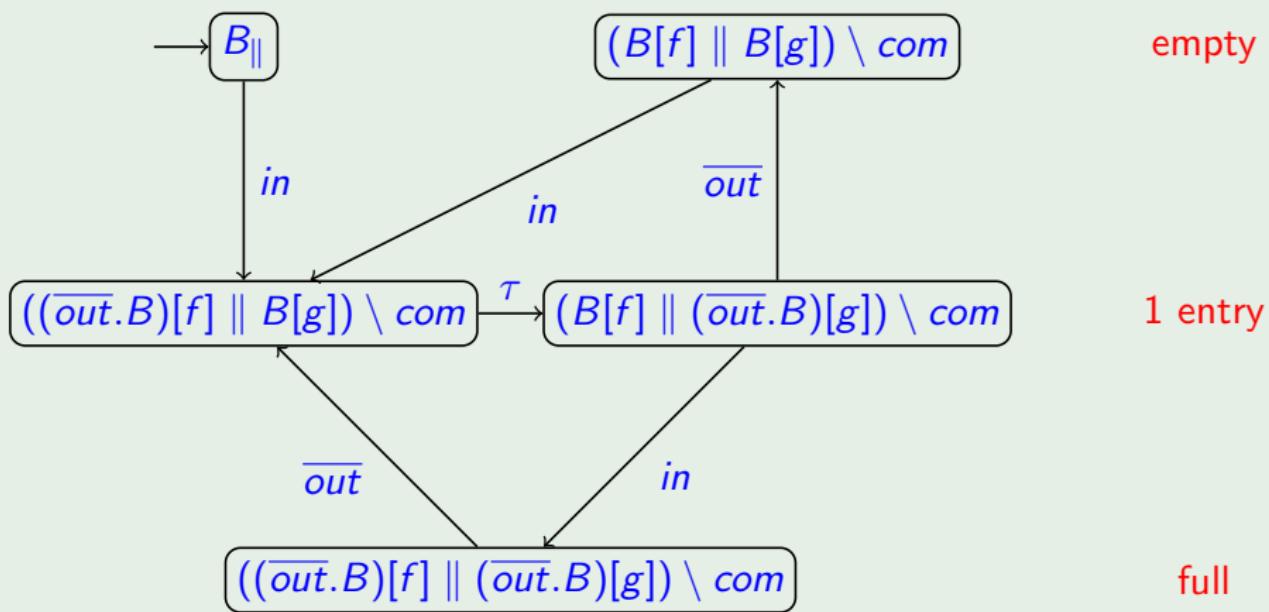
A process definition $(C_i = P_i \mid 1 \leq i \leq k)$ determines the LTS (Prc, Act, \rightarrow) whose transitions can be inferred from the following rules $(P, P', Q, Q' \in Prc, \alpha \in Act, \lambda \in A \cup \bar{A}, a \in A)$:

$$\begin{array}{c}
 \text{(Act)} \frac{}{\alpha.P \xrightarrow{\alpha} P} \\
 \text{(Sum}_1\text{)} \frac{P \xrightarrow{\alpha} P'}{P + Q \xrightarrow{\alpha} P'} \qquad \text{(Sum}_2\text{)} \frac{Q \xrightarrow{\alpha} Q'}{P + Q \xrightarrow{\alpha} Q'} \\
 \text{(Par}_1\text{)} \frac{P \xrightarrow{\alpha} P'}{P \parallel Q \xrightarrow{\alpha} P' \parallel Q} \qquad \text{(Par}_2\text{)} \frac{Q \xrightarrow{\alpha} Q'}{P \parallel Q \xrightarrow{\alpha} P \parallel Q'} \\
 \text{(Com)} \frac{P \xrightarrow{\lambda} P' \quad Q \xrightarrow{\bar{\lambda}} Q'}{P \parallel Q \xrightarrow{\tau} P' \parallel Q'} \\
 \text{(Rel)} \frac{P \xrightarrow{\alpha} P'}{P[f] \xrightarrow{f(\alpha)} P'[f]} \qquad \text{(Res)} \frac{P \xrightarrow{\alpha} P' \quad (\alpha, \bar{\alpha} \notin L)}{P \setminus L \xrightarrow{\alpha} P' \setminus L} \\
 \text{(Call)} \frac{P \xrightarrow{\alpha} P' \quad (C = P)}{C \xrightarrow{\alpha} P'}
 \end{array}$$

Example

Parallel two-place buffer: $B_{\parallel} = (B[f] \parallel B[g]) \setminus com$
 $B = in.\overline{out}.B$

where $f := [out \mapsto com]$ and $g := [in \mapsto com]$



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The Power of Recursive Definitions

So far: only **finite** state spaces

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Example 3.1 (Counter)

$$C = up.(C \parallel down.nil)$$

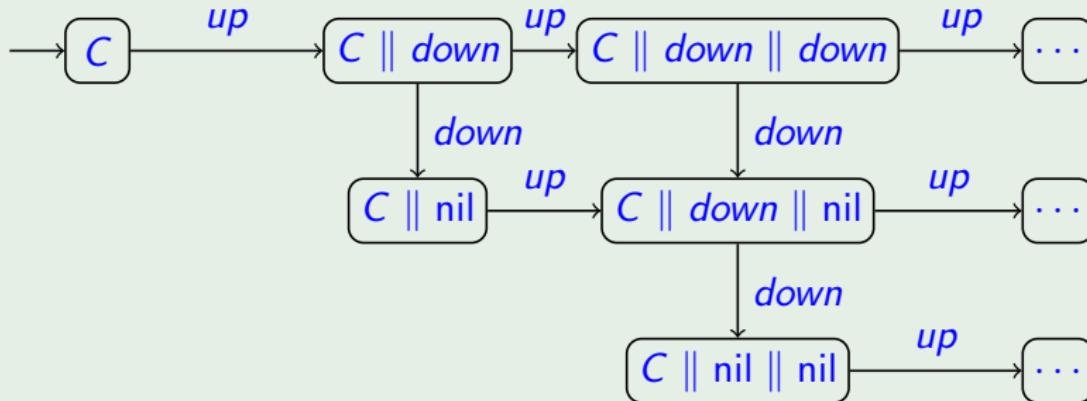
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gives rise to **infinite** LTS (abbreviating $\text{down} := \text{down.nil}$):



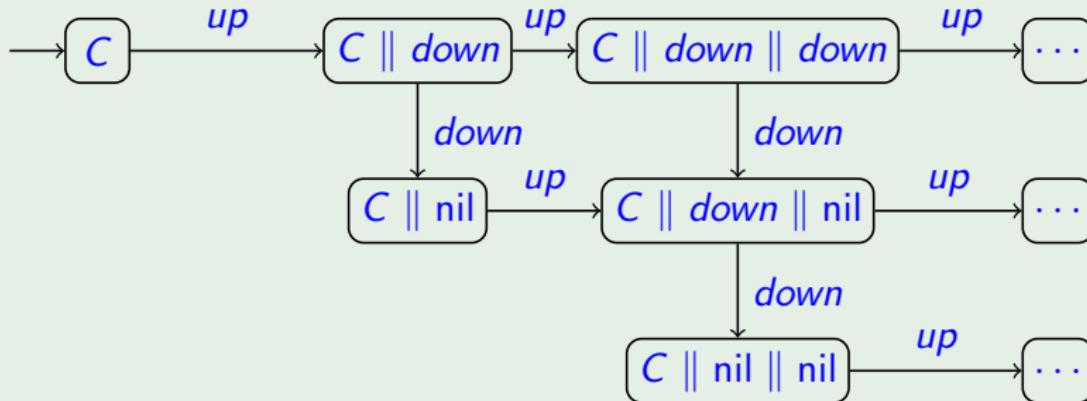
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gives rise to **infinite** LTS (abbreviating $down := down.nil$):



Sequential “specification”: $C_0 = up.C_1$

$$C_n = up.C_{n+1} + down.C_{n-1} \quad (n > 0)$$

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Goal: reduce processes to the action sequences they can perform

Definition 3.2 (Trace language)

For every $P \in Prc$, let

$$Tr(P) := \{w \in Act^* \mid \text{ex. } P' \in Prc \text{ such that } P \xrightarrow{w} P'\}$$

be the **trace language** of P

(where $\xrightarrow{w} := \xrightarrow{a_1} \circ \dots \circ \xrightarrow{a_n}$ for $w = a_1 \dots a_n$).

$P, Q \in Prc$ are called **trace equivalent** if $Tr(P) = Tr(Q)$.

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Example 3.3 (One-place buffer)

$$B = in.\overline{out}.B$$

$$\Rightarrow Tr(B) = (in \cdot \overline{out})^* \cdot (in + \varepsilon)$$

Remarks:

- The trace language of $P \in Prc$ is accepted by the LTS of P , interpreted as a (finite or infinite) automaton with **initial state P** and where **every state is final**.

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- Trace equivalence identifies processes with **identical LTSs**: the trace language of a process consists of the (finite) paths in the LTS. Thus:

$$LTS(P) = LTS(Q) \implies Tr(P) = Tr(Q)$$

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- Later we will see: trace equivalence is **too coarse**, i.e., identifies too many processes
 \implies **bisimulation**

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- action a is initially enabled
- action b is initially disabled
- a deadlock never occurs
- always sends a reply after receiving a request

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- formalisation in **Hennessy-Milner Logic (HML)**
- M. Hennessy, R. Milner: *On Observing Nondeterminism and Concurrency*, ICALP 1980, Springer LNCS 85, 299–309
- checking by **exploration of state space**

Definition 3.4 (Syntax of HML)

The set *HMF* of Hennessy-Milner formulae over a set of actions *Act* is defined by the following syntax:

$$\begin{array}{lcl} F ::= & & \\ & \text{tt} & \text{(true)} \\ & \text{ff} & \text{(false)} \\ & F_1 \wedge F_2 & \text{(conjunction)} \\ & F_1 \vee F_2 & \text{(disjunction)} \\ & \langle \alpha \rangle F & \text{(diamond)} \\ & [\alpha] F & \text{(box)} \end{array}$$

where $\alpha \in \text{Act}$.

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where $\alpha \in Act$.

Abbreviations for $L = \{\alpha_1, \dots, \alpha_n\}$ ($n \in \mathbb{N}$):

- $\langle L \rangle F := \langle \alpha_1 \rangle F \vee \dots \vee \langle \alpha_n \rangle F$
- $[L] F := [\alpha_1] F \wedge \dots \wedge [\alpha_n] F$
- In particular, $\langle \emptyset \rangle F := \text{ff}$ and $[\emptyset] F := \text{tt}$

- All processes satisfy tt .

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- No process satisfies **ff**.

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- A process satisfies $[\alpha]F$ for some $\alpha \in Act$ iff all its α -labelled transitions lead to a state satisfying F (necessity).

Definition 3.5 (Semantics of HML)

Let $(S, Act, \longrightarrow)$ be an LTS and $F \in HMF$. The set of processes in S that satisfy F , $\llbracket F \rrbracket \subseteq S$, is defined by

$$\begin{array}{ll} \llbracket \text{tt} \rrbracket := S & \llbracket \text{ff} \rrbracket := \emptyset \\ \llbracket F_1 \wedge F_2 \rrbracket := \llbracket F_1 \rrbracket \cap \llbracket F_2 \rrbracket & \llbracket F_1 \vee F_2 \rrbracket := \llbracket F_1 \rrbracket \cup \llbracket F_2 \rrbracket \\ \llbracket \langle \alpha \rangle F \rrbracket := \langle \cdot \alpha \cdot \rangle(\llbracket F \rrbracket) & \llbracket [\alpha] F \rrbracket := [\cdot \alpha \cdot](\llbracket F \rrbracket) \end{array}$$

where $\langle \cdot \alpha \cdot \rangle, [\cdot \alpha \cdot] : 2^S \rightarrow 2^S$ are given by

$$\begin{array}{l} \langle \cdot \alpha \cdot \rangle(T) := \{s \in S \mid \exists s' \in T : s \xrightarrow{\alpha} s'\} \\ [\cdot \alpha \cdot](T) := \{s \in S \mid \forall s' \in S : s \xrightarrow{\alpha} s' \implies s' \in T\} \end{array}$$

We write $s \models F$ iff $s \in \llbracket F \rrbracket$. Two HML formulae are equivalent (written $F \equiv G$) iff they are satisfied by the same processes in every LTS.

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Example 3.6 ($\langle \cdot \alpha \cdot \rangle, [\cdot \alpha \cdot]$ operators)

on the board

Example 3.7

① action a is initially enabled: $\langle a \rangle tt$

$$\begin{aligned}\llbracket \langle a \rangle tt \rrbracket &= \langle \cdot a \cdot \rangle \llbracket tt \rrbracket = \langle \cdot a \cdot \rangle (S) \\ &= \{s \in S \mid \exists s' \in S : s \xrightarrow{a} s'\} =: \{s \in S \mid s \xrightarrow{a}\}\end{aligned}$$

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③ absence of deadlock:

- initially: $\langle \text{Act} \rangle tt$
- always: later (requires recursion)

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④ responsiveness:

- initially: $[\text{request}] \langle \overline{\text{reply}} \rangle tt$
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Closure under Negation

Observation: negation is *not* one of the HML constructs

Reason: HML is closed under negation

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Lemma 3.8

For every $F \in \text{HMF}$ there exists $F^c \in \text{HMF}$ such that $\llbracket F^c \rrbracket = S \setminus \llbracket F \rrbracket$ for every LTS $(S, \text{Act}, \longrightarrow)$.

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Proof.

Definition of F^c :

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$\llbracket F^c \rrbracket = S \setminus \llbracket F \rrbracket$: on the board

□