

# Concurrency Theory

## Lecture 3: Hennessy-Milner Logic

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Lehrstuhl für Informatik 2  
(Software Modeling and Verification)



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Winter Semester 2013/14

- ① Friday, 21.02.2014, 11:30–14:00, AH 2
- ② Tuesday, 25.03.2014, 10:00–12:30, AH 1

Online registration via CampusOffice is enabled.



- D-MiLS research project (<http://www.d-mils.org/>)
  - architectural specification of secure systems
  - modular high-assurance platform
  - framework for the certification of systems
  - basis: MILS-AADL specification language
- Task: implementation of compiler frontend
  - parser
  - semantic checker
  - based on ANTLR 3 definition of SLIM specification language (COMPASS project)
  - estimated effort: 10 h/week

1 Recap: Calculus of Communicating Systems

2 Infinite State Spaces

3 Process Traces

4 Hennessy-Milner Logic

5 Closure under Negation

## Definition (Syntax of CCS)

- Let  $A$  be a set of (action) names.
- $\bar{A} := \{\bar{a} \mid a \in A\}$  denotes the set of co-names.
- $Act := A \cup \bar{A} \cup \{\tau\}$  is the set of actions where  $\tau$  denotes the silent (or: unobservable) action.
- Let  $Pid$  be a set of process identifiers.
- The set  $Prc$  of process expressions is defined by the following syntax:

$P ::=$	$nil$	(inaction)
	$\alpha.P$	(prefixing)
	$P_1 + P_2$	(choice)
	$P_1 \parallel P_2$	(parallel composition)
	$P \setminus L$	(restriction)
	$P[f]$	(relabelling)
	$C$	(process call)

where  $\alpha \in Act$ ,  $L \subseteq A$ ,  $C \in Pid$ , and  $f : Act \rightarrow Act$  such that  $f(\tau) = \tau$  and  $f(\bar{a}) = \bar{f(a)}$  for each  $a \in A$ .

## Definition (continued)

- A **(recursive) process definition** is an equation system of the form

$$(C_i = P_i \mid 1 \leq i \leq k)$$

where  $k \geq 1$ ,  $C_i \in Pid$  (pairwise distinct), and  $P_i \in Prc$  (with process identifiers from  $\{C_1, \dots, C_k\}$ ).

## Notational Conventions:

- $\bar{a}$  means  $a$
- $\sum_{i=1}^n P_i$  ( $n \in \mathbb{N}$ ) means  $P_1 + \dots + P_n$  (where  $\sum_{i=1}^0 P_i := \text{nil}$ )
- $P \setminus a$  abbreviates  $P \setminus \{a\}$
- $[a_1 \mapsto b_1, \dots, a_n \mapsto b_n]$  stands for  $f : Act \rightarrow Act$  with  $f(a_i) = b_i$  ( $i \in [n]$ ) and  $f(\alpha) = \alpha$  otherwise
- restriction and relabelling bind stronger than prefixing, prefixing stronger than composition, composition stronger than choice:

$$P \setminus a + b.Q \parallel R \quad \text{means} \quad (P \setminus a) + ((b.Q) \parallel R)$$

**Goal:** represent behaviour of system by (infinite) graph

- nodes = system states
- edges = transitions between states

Definition (Labelled transition system)

A **(Act-)labelled transition system (LTS)** is a triple  $(S, Act, \rightarrow)$  consisting of

- a set  $S$  of **states**
- a set  $Act$  of **(action) labels**
- a **transition relation**  $\rightarrow \subseteq S \times Act \times S$

For  $(s, \alpha, s') \in \rightarrow$  we write  $s \xrightarrow{\alpha} s'$ . An LTS is called **finite** if  $S$  is so.

**Remarks:**

- sometimes an **initial state**  $s_0 \in S$  is distinguished ("LTS( $s_0$ )")
- (finite) LTSs correspond to (finite) **automata** without final states

## Definition (Semantics of CCS)

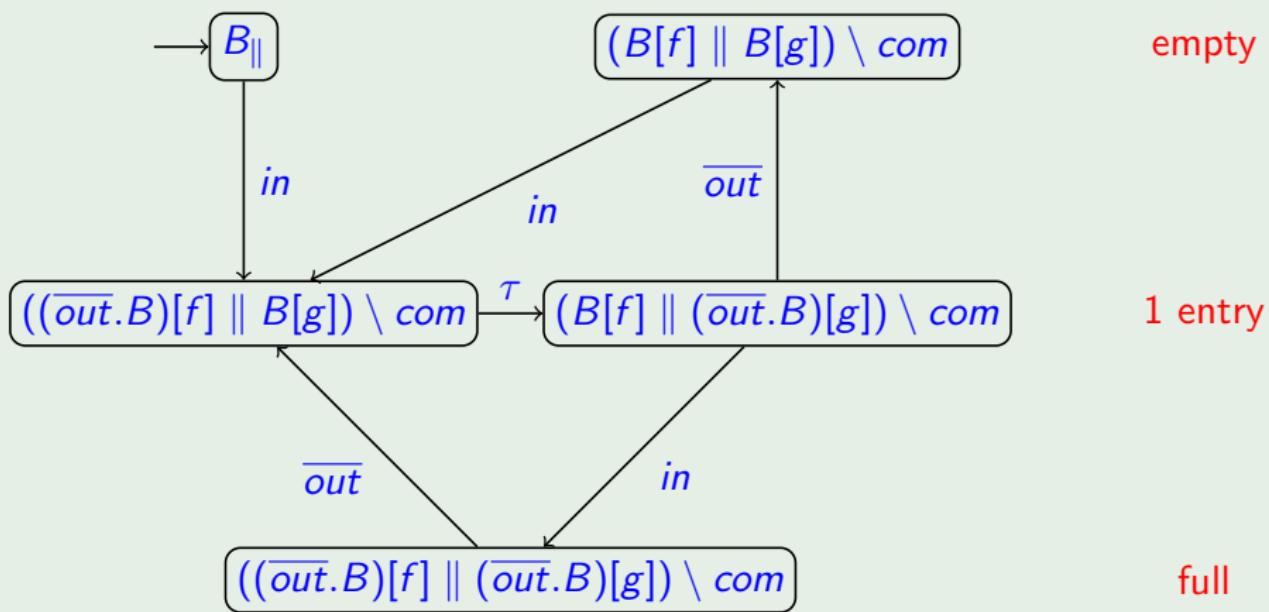
A process definition  $(C_i = P_i \mid 1 \leq i \leq k)$  determines the LTS  $(Prc, Act, \rightarrow)$  whose transitions can be inferred from the following rules  $(P, P', Q, Q' \in Prc, \alpha \in Act, \lambda \in A \cup \bar{A}, a \in A)$ :

$$\begin{array}{c}
 \text{(Act)} \frac{}{\alpha.P \xrightarrow{\alpha} P} \\
 \text{(Sum}_1\text{)} \frac{P \xrightarrow{\alpha} P'}{P + Q \xrightarrow{\alpha} P'} \qquad \text{(Sum}_2\text{)} \frac{Q \xrightarrow{\alpha} Q'}{P + Q \xrightarrow{\alpha} Q'} \\
 \text{(Par}_1\text{)} \frac{P \xrightarrow{\alpha} P'}{P \parallel Q \xrightarrow{\alpha} P' \parallel Q} \qquad \text{(Par}_2\text{)} \frac{Q \xrightarrow{\alpha} Q'}{P \parallel Q \xrightarrow{\alpha} P \parallel Q'} \\
 \text{(Com)} \frac{P \xrightarrow{\lambda} P' \quad Q \xrightarrow{\bar{\lambda}} Q'}{P \parallel Q \xrightarrow{\tau} P' \parallel Q'} \\
 \text{(Rel)} \frac{P \xrightarrow{\alpha} P'}{P[f] \xrightarrow{f(\alpha)} P'[f]} \qquad \text{(Res)} \frac{P \xrightarrow{\alpha} P' \quad (\alpha, \bar{\alpha} \notin L)}{P \setminus L \xrightarrow{\alpha} P' \setminus L} \\
 \text{(Call)} \frac{P \xrightarrow{\alpha} P' \quad (C = P)}{C \xrightarrow{\alpha} P'}
 \end{array}$$

## Example

Parallel two-place buffer:  $B_{\parallel} = (B[f] \parallel B[g]) \setminus com$   
 $B = in.\overline{out}.B$

where  $f := [out \mapsto com]$  and  $g := [in \mapsto com]$



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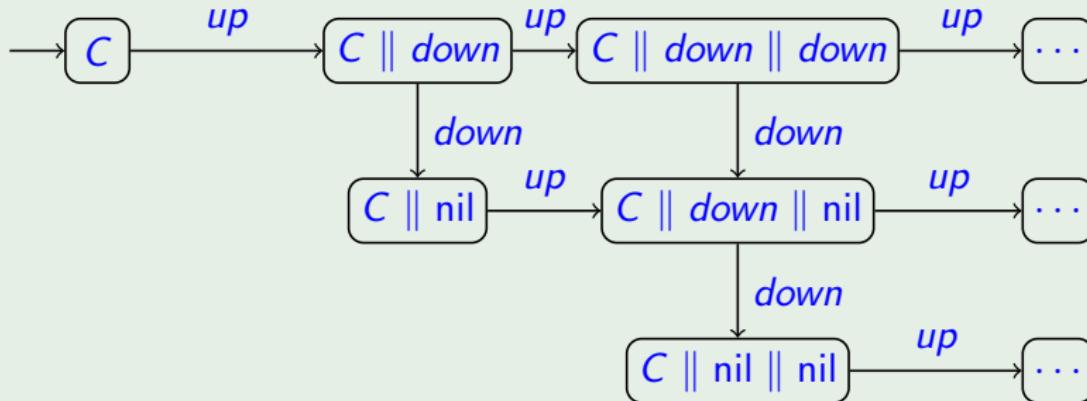
# The Power of Recursive Definitions

So far: only **finite** state spaces

## Example 3.1 (Counter)

$$C = up.(C \parallel down.nil)$$

gives rise to **infinite** LTS (abbreviating  $down := down.nil$ ):



Sequential “specification”:  $C_0 = up.C_1$

$$C_n = up.C_{n+1} + down.C_{n-1} \quad (n > 0)$$

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**Goal:** reduce processes to the action sequences they can perform

## Definition 3.2 (Trace language)

For every  $P \in Prc$ , let

$$Tr(P) := \{w \in Act^* \mid \text{ex. } P' \in Prc \text{ such that } P \xrightarrow{w} P'\}$$

be the **trace language** of  $P$

(where  $\xrightarrow{w} := \xrightarrow{a_1} \circ \dots \circ \xrightarrow{a_n}$  for  $w = a_1 \dots a_n$ ).

$P, Q \in Prc$  are called **trace equivalent** if  $Tr(P) = Tr(Q)$ .

## Example 3.3 (One-place buffer)

$$B = in.\overline{out}.B$$

$$\Rightarrow Tr(B) = (in \cdot \overline{out})^* \cdot (in + \varepsilon)$$

## Remarks:

- The trace language of  $P \in Prc$  is accepted by the LTS of  $P$ , interpreted as a (finite or infinite) automaton with **initial state  $P$**  and where **every state is final**.
- Trace equivalence is obviously an **equivalence relation** (i.e., reflexive, symmetric, and transitive).
- Trace equivalence identifies processes with **identical LTSs**: the trace language of a process consists of the (finite) paths in the LTS. Thus:

$$LTS(P) = LTS(Q) \implies Tr(P) = Tr(Q)$$

- Later we will see: trace equivalence is **too coarse**, i.e., identifies too many processes  
 $\implies$  **bisimulation**

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**Goal:** check processes for **simple properties**

- action  $a$  is initially enabled
- action  $b$  is initially disabled
- a deadlock never occurs
- always sends a reply after receiving a request

- formalisation in **Hennessy-Milner Logic (HML)**
- M. Hennessy, R. Milner: *On Observing Nondeterminism and Concurrency*, ICALP 1980, Springer LNCS 85, 299–309
- checking by **exploration of state space**

## Definition 3.4 (Syntax of HML)

The set  $HMF$  of Hennessy-Milner formulae over a set of actions  $Act$  is defined by the following syntax:

$$\begin{array}{lcl} F ::= & \text{tt} & \text{(true)} \\ | & \text{ff} & \text{(false)} \\ | & F_1 \wedge F_2 & \text{(conjunction)} \\ | & F_1 \vee F_2 & \text{(disjunction)} \\ | & \langle \alpha \rangle F & \text{(diamond)} \\ | & [\alpha] F & \text{(box)} \end{array}$$

where  $\alpha \in Act$ .

**Abbreviations** for  $L = \{\alpha_1, \dots, \alpha_n\}$  ( $n \in \mathbb{N}$ ):

- $\langle L \rangle F := \langle \alpha_1 \rangle F \vee \dots \vee \langle \alpha_n \rangle F$
- $[L] F := [\alpha_1] F \wedge \dots \wedge [\alpha_n] F$
- In particular,  $\langle \emptyset \rangle F := \text{ff}$  and  $[\emptyset] F := \text{tt}$

- All processes satisfy  $tt$ .
- No process satisfies  $ff$ .
- A process satisfies  $F \wedge G$  iff it satisfies  $F$  and  $G$ .
- A process satisfies  $F \vee G$  iff it satisfies either  $F$  or  $G$  or both.
- A process satisfies  $\langle \alpha \rangle F$  for some  $\alpha \in Act$  iff it affords an  $\alpha$ -labelled transition to a state satisfying  $F$  (possibility).
- A process satisfies  $[\alpha]F$  for some  $\alpha \in Act$  iff all its  $\alpha$ -labelled transitions lead to a state satisfying  $F$  (necessity).

## Definition 3.5 (Semantics of HML)

Let  $(S, Act, \rightarrow)$  be an LTS and  $F \in HMF$ . The set of processes in  $S$  that satisfy  $F$ ,  $\llbracket F \rrbracket \subseteq S$ , is defined by

$$\begin{array}{ll} \llbracket \text{tt} \rrbracket := S & \llbracket \text{ff} \rrbracket := \emptyset \\ \llbracket F_1 \wedge F_2 \rrbracket := \llbracket F_1 \rrbracket \cap \llbracket F_2 \rrbracket & \llbracket F_1 \vee F_2 \rrbracket := \llbracket F_1 \rrbracket \cup \llbracket F_2 \rrbracket \\ \llbracket \langle \alpha \rangle F \rrbracket := \langle \cdot \alpha \cdot \rangle(\llbracket F \rrbracket) & \llbracket [\alpha] F \rrbracket := [\cdot \alpha \cdot](\llbracket F \rrbracket) \end{array}$$

where  $\langle \cdot \alpha \cdot \rangle, [\cdot \alpha \cdot] : 2^S \rightarrow 2^S$  are given by

$$\begin{array}{l} \langle \cdot \alpha \cdot \rangle(T) := \{s \in S \mid \exists s' \in T : s \xrightarrow{\alpha} s'\} \\ [\cdot \alpha \cdot](T) := \{s \in S \mid \forall s' \in S : s \xrightarrow{\alpha} s' \implies s' \in T\} \end{array}$$

We write  $s \models F$  iff  $s \in \llbracket F \rrbracket$ . Two HML formulae are equivalent (written  $F \equiv G$ ) iff they are satisfied by the same processes in every LTS.

## Example 3.6 ( $\langle \cdot \alpha \cdot \rangle, [\cdot \alpha \cdot]$ operators)

on the board

## Example 3.7

① action  $a$  is initially enabled:  $\langle a \rangle tt$

$$\begin{aligned}\llbracket \langle a \rangle tt \rrbracket &= \langle \cdot a \cdot \rangle \llbracket tt \rrbracket = \langle \cdot a \cdot \rangle (S) \\ &= \{s \in S \mid \exists s' \in S : s \xrightarrow{a} s'\} =: \{s \in S \mid s \xrightarrow{a}\}\end{aligned}$$

② action  $b$  is initially disabled:  $[b]ff$

$$\begin{aligned}\llbracket [b]ff \rrbracket &= [\cdot b \cdot] \llbracket ff \rrbracket = [\cdot b \cdot](\emptyset) \\ &= \{s \in S \mid \forall s' \in S : s \xrightarrow{b} s' \implies s' \in \emptyset\} \\ &= \{s \in S \mid \nexists s' \in S : s \xrightarrow{b} s'\} =: \{s \in S \mid s \not\xrightarrow{b}\}\end{aligned}$$

③ absence of deadlock:

- initially:  $\langle \text{Act} \rangle tt$
- always: later (requires recursion)

④ responsiveness:

- initially:  $[\text{request}] \langle \overline{\text{reply}} \rangle tt$
- always: later (requires recursion)

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# Closure under Negation

**Observation:** negation is *not* one of the HML constructs

**Reason:** HML is *closed under negation*

## Lemma 3.8

For every  $F \in \text{HMF}$  there exists  $F^c \in \text{HMF}$  such that  $\llbracket F^c \rrbracket = S \setminus \llbracket F \rrbracket$  for every LTS  $(S, \text{Act}, \longrightarrow)$ .

## Proof.

Definition of  $F^c$ :

$$\begin{array}{ll} \text{tt}^c := \text{ff} & \text{ff}^c := \text{tt} \\ (F_1 \wedge F_2)^c := F_1^c \vee F_2^c & (F_1 \vee F_2)^c := F_1^c \wedge F_2^c \\ (\langle \alpha \rangle F)^c := [\alpha]F^c & ([\alpha]F)^c := \langle \alpha \rangle F^c \end{array}$$

$\llbracket F^c \rrbracket = S \setminus \llbracket F \rrbracket$ : on the board

□