

Replaying Play-In Play-Out: Synthesis of Design Models from Scenarios by Learning

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Outline

- 1 Introduction
- 2 Angluin's Learning Approach
- 3 Learning Design Models
- 4 Dedicated Tool: *Smyle*
- 5 Conclusion

Presentation outline

1 Introduction

2 Angluin's Learning Approach

3 Learning Design Models

4 Dedicated Tool: *Smyle*

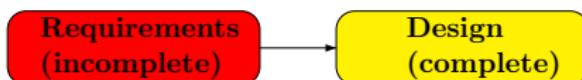
5 Conclusion

Motivation

Requirements (incomplete)

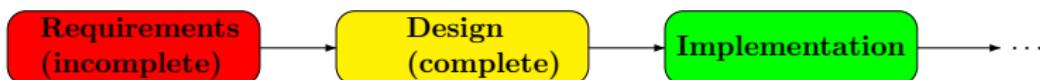
- initial phase: requirement elicitation
 - contradicting or incomplete system description
 - common description language: sequence diagrams
- goal: conforming design model
- closing gap between
 - requirement specification (usually incomplete) and
 - design model (complete description of system)
- similar to Harel's *play-in, play-out* approach

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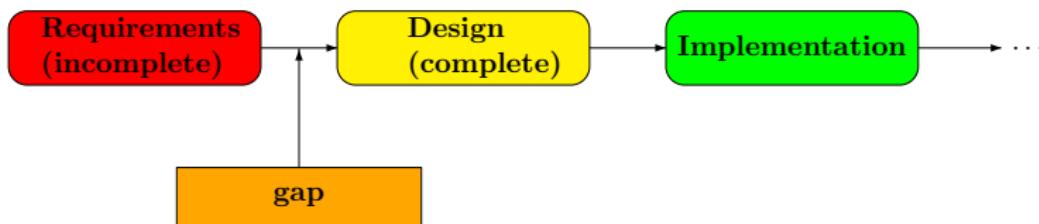
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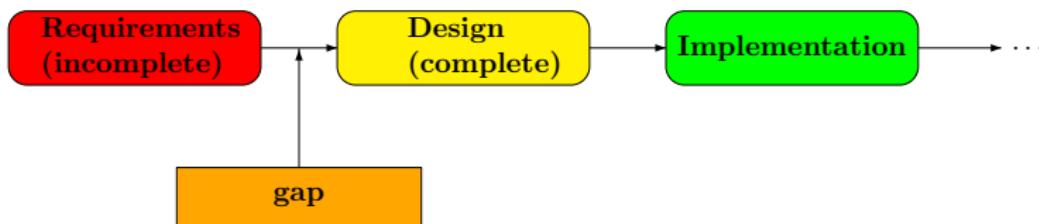
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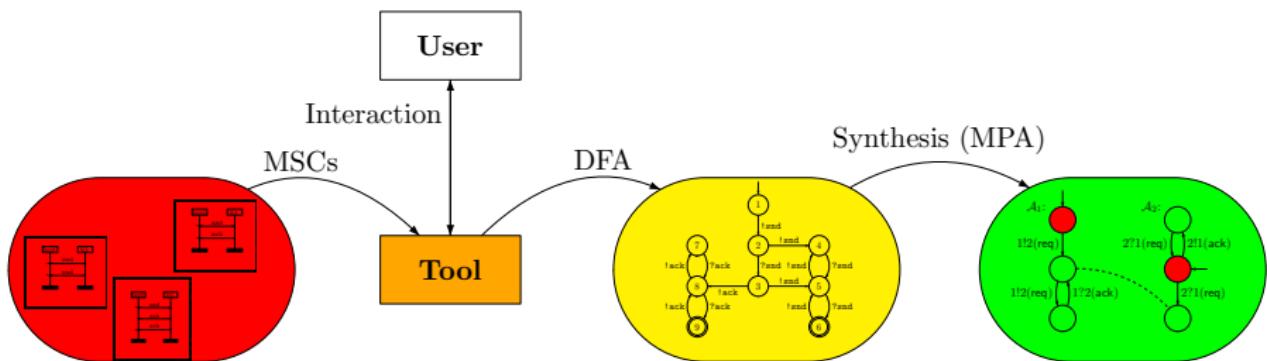


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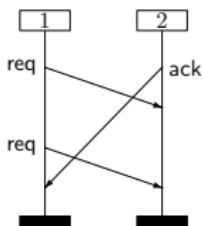
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Our Approach

- use **learning algorithms** to synthesize models for communication protocols
- **Input:** set of Message Sequence Charts
 - standardized: ITU Z.120
 - included in UML as sequence diagrams
- **Output:** MPA fulfilling the specification
 - model is close to implementation

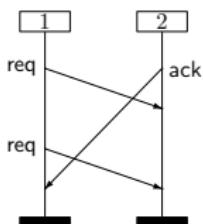
Message Sequence Chart



An MSC $M = \langle \mathcal{P}, E, \{\leq_p\}_{p \in \mathcal{P}}, <_{\text{msg}}, l \rangle$

- \mathcal{P} : finite set of processes
- E : finite set of events ($E = \bigcup_{p \in \mathcal{P}} E_p$)
- $l : E \rightarrow Act = \{p!q(\text{req}), p?q(\text{ack}), \dots\}$
- for $p \in \mathcal{P}$: $<_p \subseteq E_p \times E_p$ is a total order on E_p
- $<_{msg}$ relates sending and receiving events
- $\leq = \left(<_{msg} \cup \bigcup_{p \in \mathcal{P}} <_p \right)^*$

Message Sequence Chart



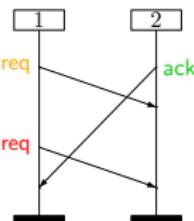
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A set of MSCs is called an *MSC language*.

A *linearization* of an MSC is a total ordering of E subsuming \leq

MSCs and Linearizations



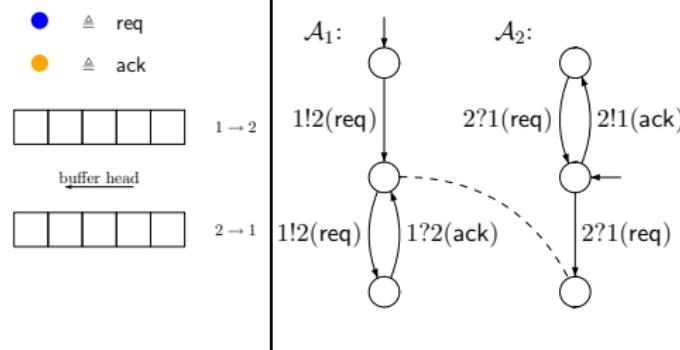
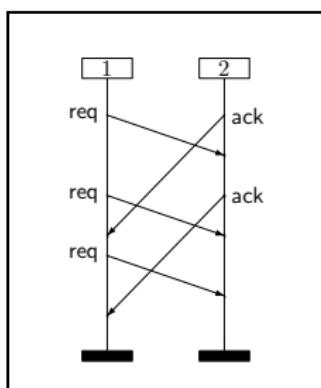
Some linearizations

- 1!2(req) 1!2(req) 2!1(ack) 1?2(ack) 2?1(req) 2?1(req)
- 1!2(req) 2!1(ack) 1!2(req) 1?2(ack) 2?1(req) 2?1(req)
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- ...

An MSC M is uniquely determined by its linearizations $Lin(M)$

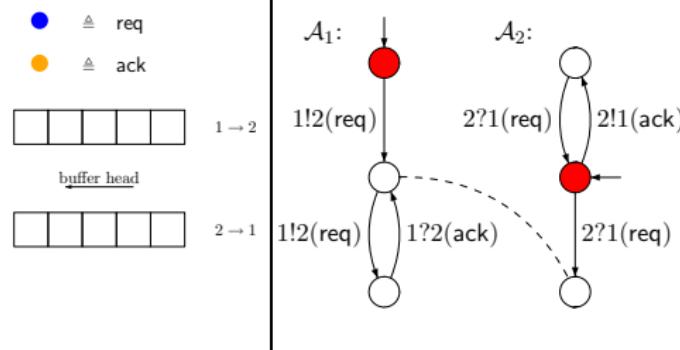
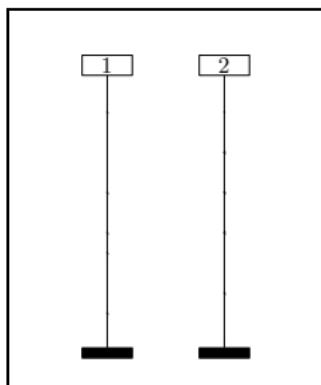
Message Passing Automata

- a set of finite-state automata (*processes*) with
 - common global initial state
 - set of global final states
- communication between automata through (reliable) FIFO channels
 - $p!q(a)$ appends message a to buffer between p and q
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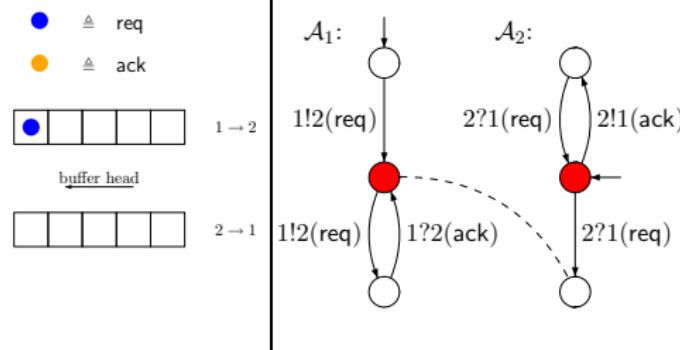
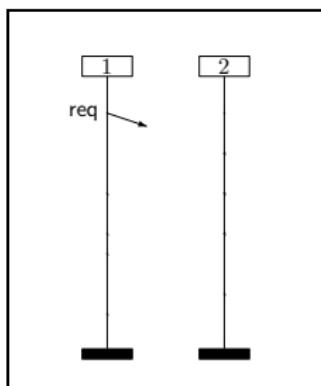
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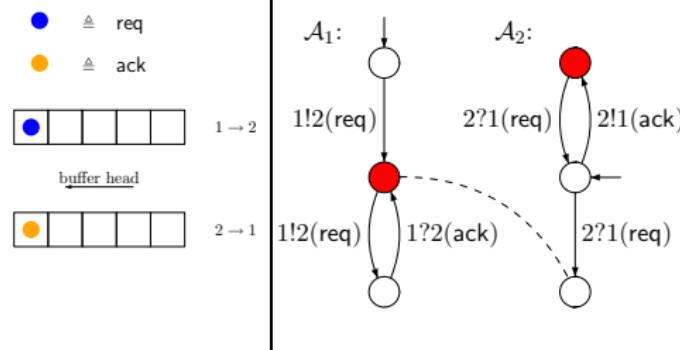
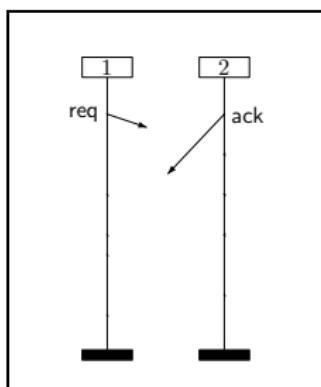
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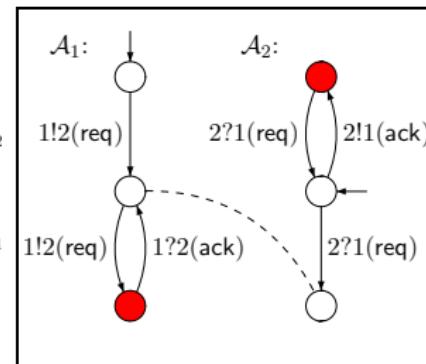
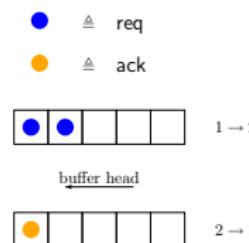
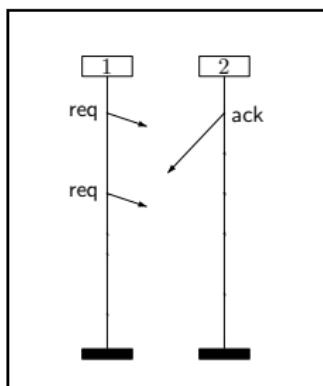
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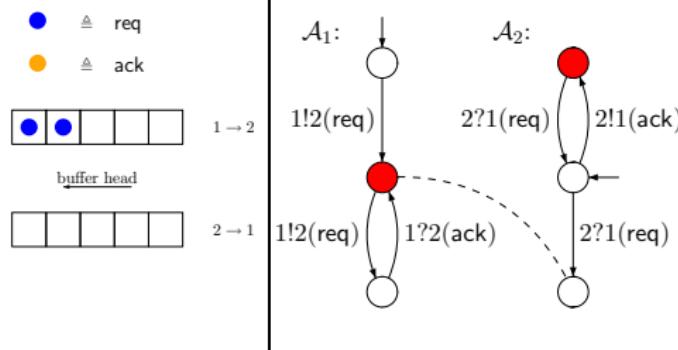
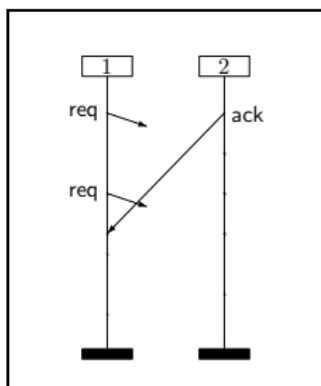
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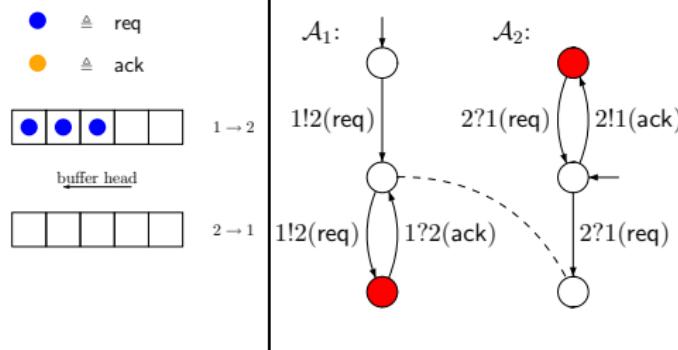
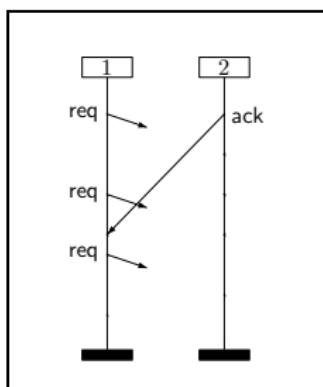
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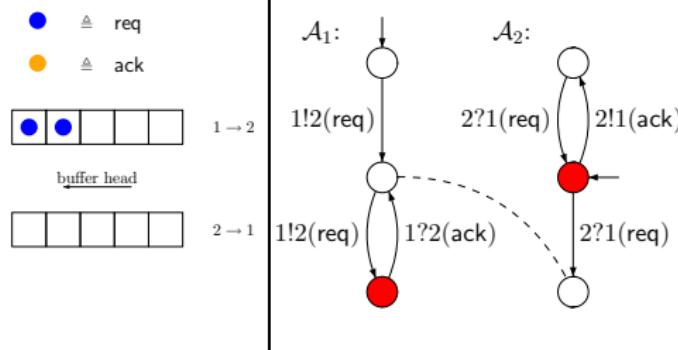
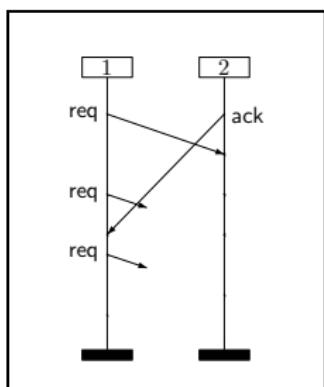
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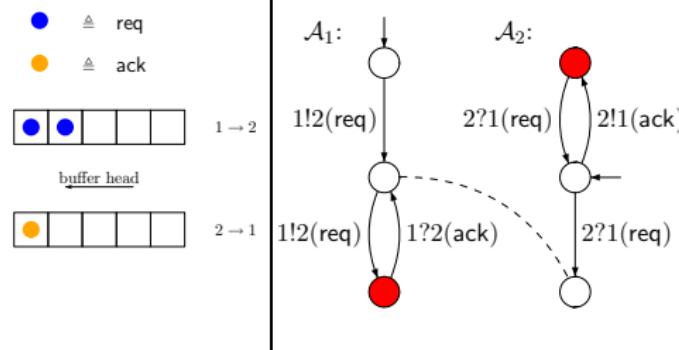
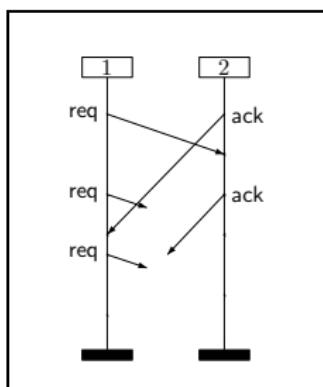
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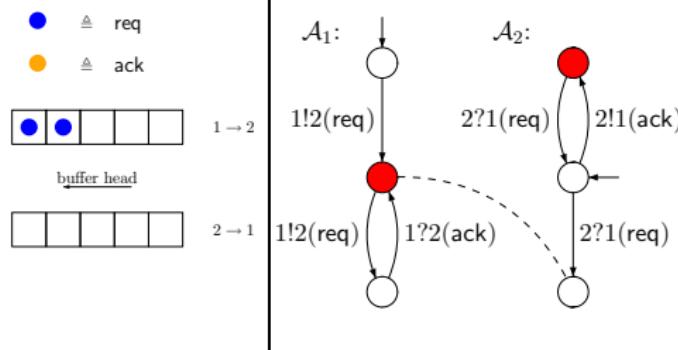
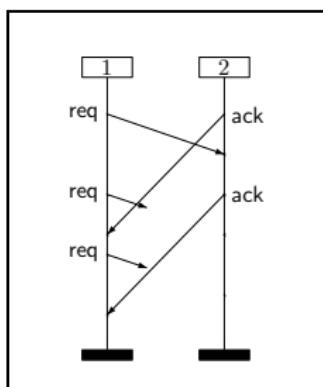
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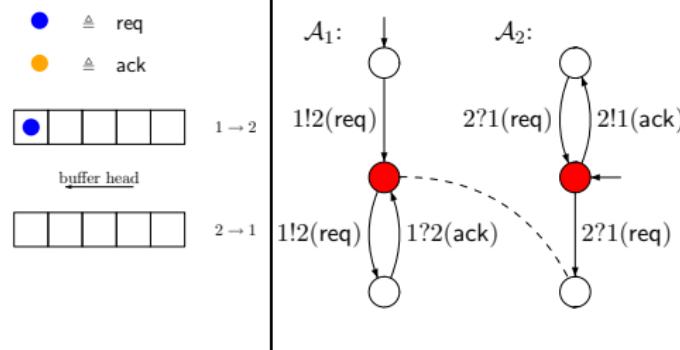
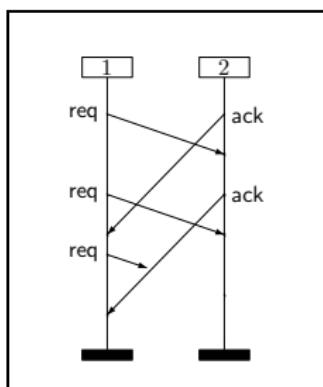
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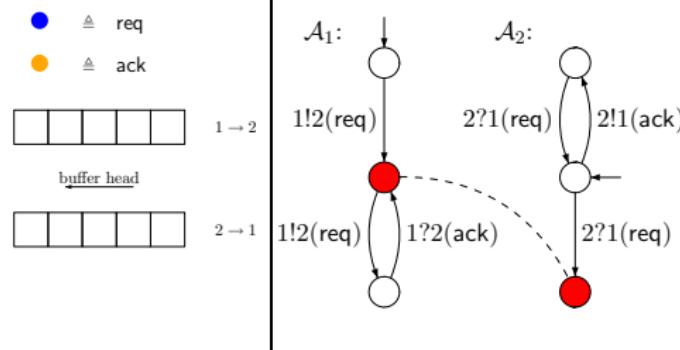
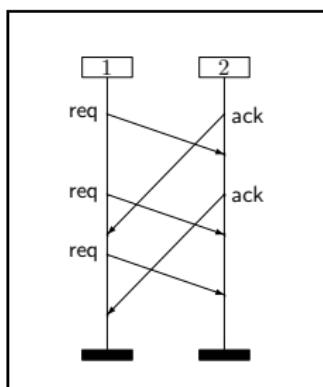
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Current State

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- **goal:** *learning MPA*
- **given:** *learning DFA* [Angluin]

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Angluin's algorithm

Idea:

- learning regular language $L(\mathcal{A}) \subseteq \Sigma^*$ in terms of a minimal DFA \mathcal{A}
- components:
 - *Learner*:
 - initially knows nothing about \mathcal{A}
 - tries to learn \mathcal{A}
 - proposes *hypothetical* automaton \mathcal{H}
 - *Teacher*:
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 - answers membership queries of *Learner* ($w \stackrel{?}{\in} L(\mathcal{A})$)
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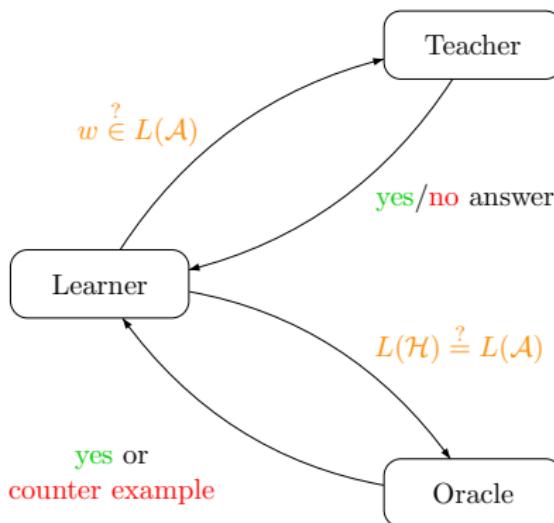
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- query complexity: polynomial

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Goal

- learning MPA from examples (MSCs)

Approach

- extending Angluin's algorithm
- **Input:** linearizations of MSCs
 - **positive** scenarios are included in the language to learn
 - **negative** scenarios must not be contained
- **positive** and **negative** scenarios form system behavior

Problem

- correspondence between MPA and regular word languages needed

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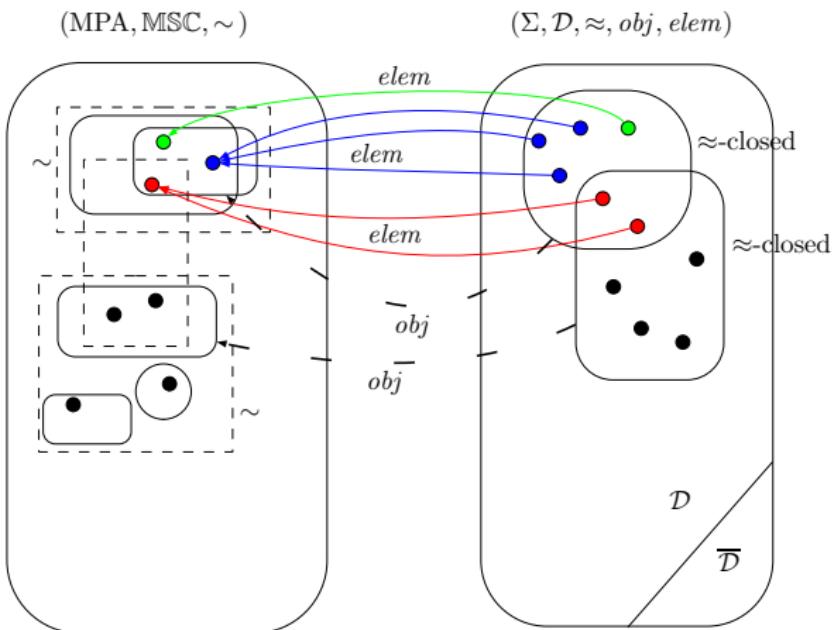
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Defining a *Learning Setup*

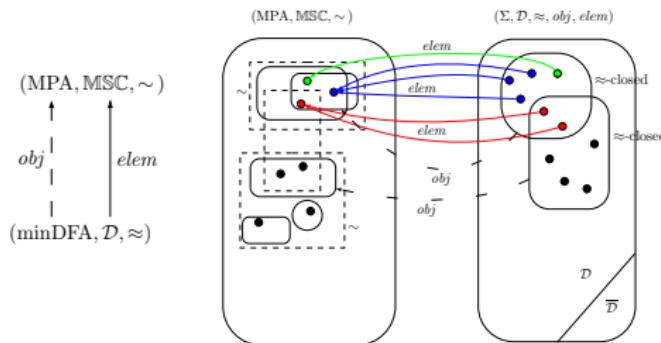
(MPA, MSC, \sim)

obj | $elem$

$(minDFA, \mathcal{D}, \approx)$

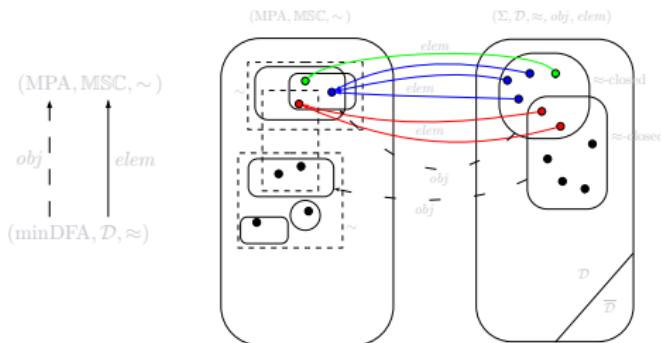


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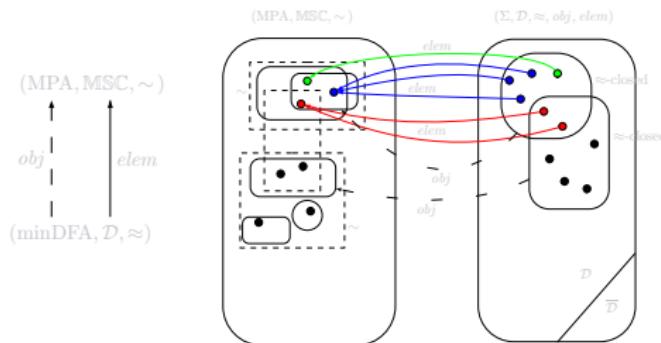
- membership queries for equiv. words need to be answered equivalently
- having found a hypothesis DFA \mathcal{H} :
 - if $L(\mathcal{H}) \not\subseteq \mathcal{D}$, compute counterexample $w \in L(\mathcal{H}) \setminus \mathcal{D}$
 - else if $L(\mathcal{H}) \subseteq \mathcal{D}$ but $L(\mathcal{H})$ not \approx -closed:
 - compute $w \approx w'$, $w \in L(\mathcal{H})$, $w' \notin L(\mathcal{H})$ and
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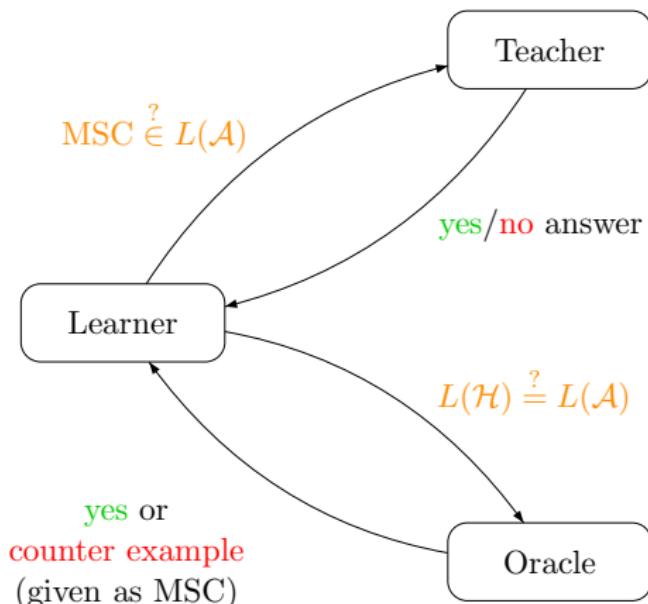


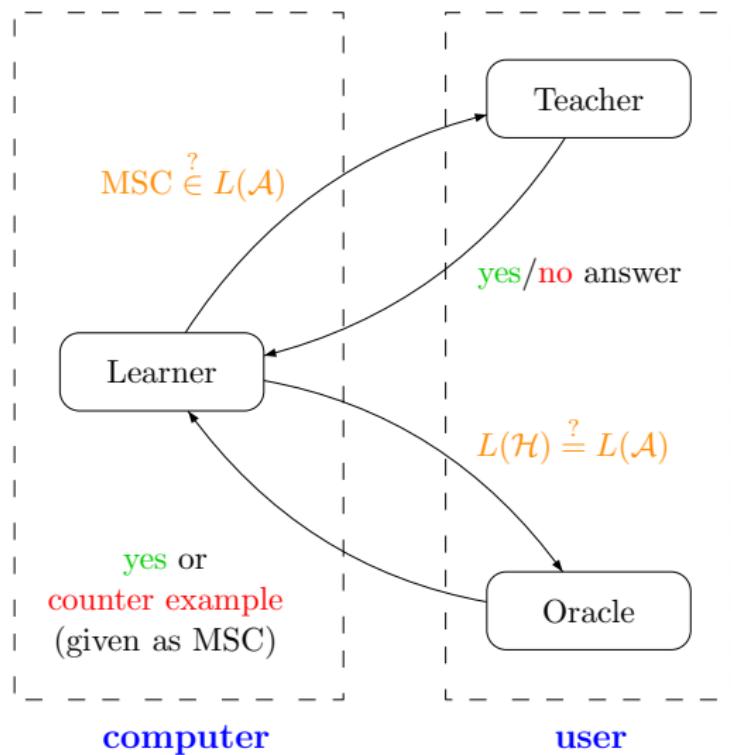
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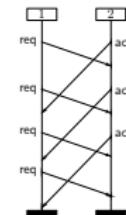




Classes of MSCs

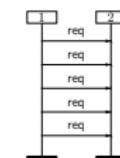
M is $\forall B$ -bounded if

all linearizations of M do not exceed buffer bound B



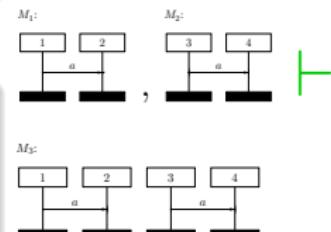
M is $\exists B$ -bounded ($B \in \mathbb{N}$) if

events of M can be scheduled s.t. B is not exceeded



Definition: Inference relation \vdash

- process sets of M_1 and M_2 are distinct
- M_3 is inferred from two MSCs M_1, M_2



Results

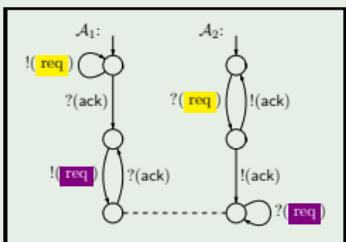
Learnable classes of MPA:

- \forall -bounded MPA
- $\exists B$ -bounded MPA (for all $B \in \mathbb{N}$)
- \forall -bounded safe product MPA

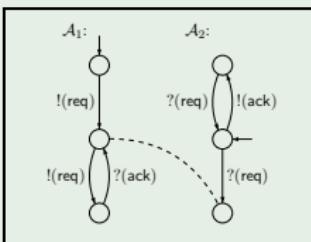
Not learnable

- \forall -bounded product MPA

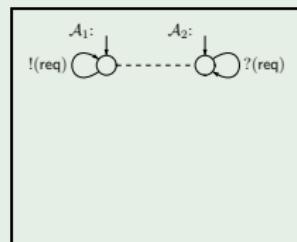
Example



not $\exists B$ -bounded
no product MPA
not safe



\forall -bounded
product MPA
safe



not \forall -bounded
 $\exists 1$ -bounded
product MPA
safe

Learning Message-Passing Automata

Theorem: [Genest, Kuske, Muscholl], [Henriksen et al.]

- for any \exists -regular MSC language \mathcal{L} one can compute an MPA \mathcal{A} , s.t. $\mathcal{L}(\mathcal{A}) = \mathcal{L}$
- for any \forall -regular MSC language \mathcal{L} one can compute a **deterministic** MPA \mathcal{A} , s.t. $\mathcal{L}(\mathcal{A}) = \mathcal{L}$

Theorem:

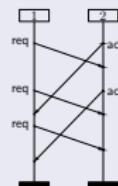
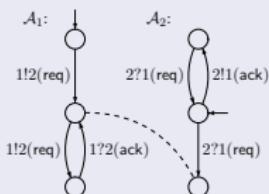
The \forall -regular safe product MSC languages are exactly the languages accepted by \forall -bounded safe product MPA

- \exists/\forall -regular is treated with \approx
- \forall -regular safe product is handled by \approx , \vdash

universally-bounded MPA

A *universally-bounded* MPA

- Example of a universally-bounded MPA and $\forall 3$ -bounded MSC



- \sim : language equivalence of \forall -bounded MPA
- \approx : linearization equivalence
- obj : mapping a minimal DFA to a \forall -bounded MPA
- $elem$: mapping a linearization to its corresponding MSC

Algorithm for \forall -bounded MPA

Let \mathcal{H} be a minimal DFA (hypothesis)

The problems $L(\mathcal{H}) \subseteq \mathcal{D}$ and $L(\mathcal{H})$ is \approx -closed are *constructively decidable*

- successively mark the states of \mathcal{H} with channel contents
 - sending an event adds a message to the corresponding channel
 - receiving an event removes the message from the channel head
- check *diamond property* for independent σ, τ
- if problems in labeling the states are encountered, a **counter example** can be constructed and the learning algorithm continues

Complexity: linear in the size of \mathcal{H}

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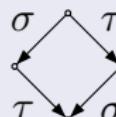
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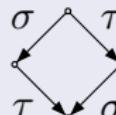
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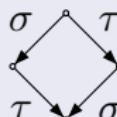
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Complexity: linear in the size of \mathcal{H}

existentially B -bounded MPA

An *existentially B -bounded* MPA

- Example of an $\exists B$ -bounded MPA (bound $B = 1$)



- \sim : language equivalence of $\exists B$ -bounded MPA
- \approx : linearization equivalence for $\exists B$ -bounded MSCs
- obj : mapping a minimal DFA to a $\exists B$ -bounded MPA
- $elem$: mapping a linearization to its corresponding MSC

Algorithm for \forall -bounded safe product MPA

Let \mathcal{H} be a \approx -closed minimal DFA

The problem if a regular \approx -closed set of MSC linearizations is recognized by some safe product MPA is *constructively decidable* (based on *EXPSPACE* algorithm by

[Alur, Etessami, Yannakakis])

- construct deterministic MPA by projecting \mathcal{H} to Act_p for any $p \in \mathcal{P}$ (determinizing and minimizing the resulting components): results in $(\mathcal{H}|_p)_{p \in \mathcal{P}}$
- $L(\mathcal{H})$ is recognized by some safe product MPA \iff $(\mathcal{H}|_p)_{p \in \mathcal{P}}$ is safe and recognizes $L(\mathcal{H})$
 - deadlocks contained?
 - buffer bound exceeded?
 - $L(\mathcal{H}) \stackrel{?}{=} L((\mathcal{H}|_p)_{p \in \mathcal{P}})$

Algorithm for \forall -bounded safe product MPA

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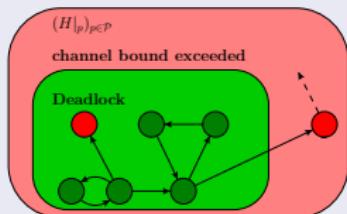
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Results

Learnable classes of MPA:

- \forall -bounded MPA
- $\exists B$ -bounded MPA (for all $B \in \mathbb{N}$)
- \forall -bounded safe product MPA

Not learnable

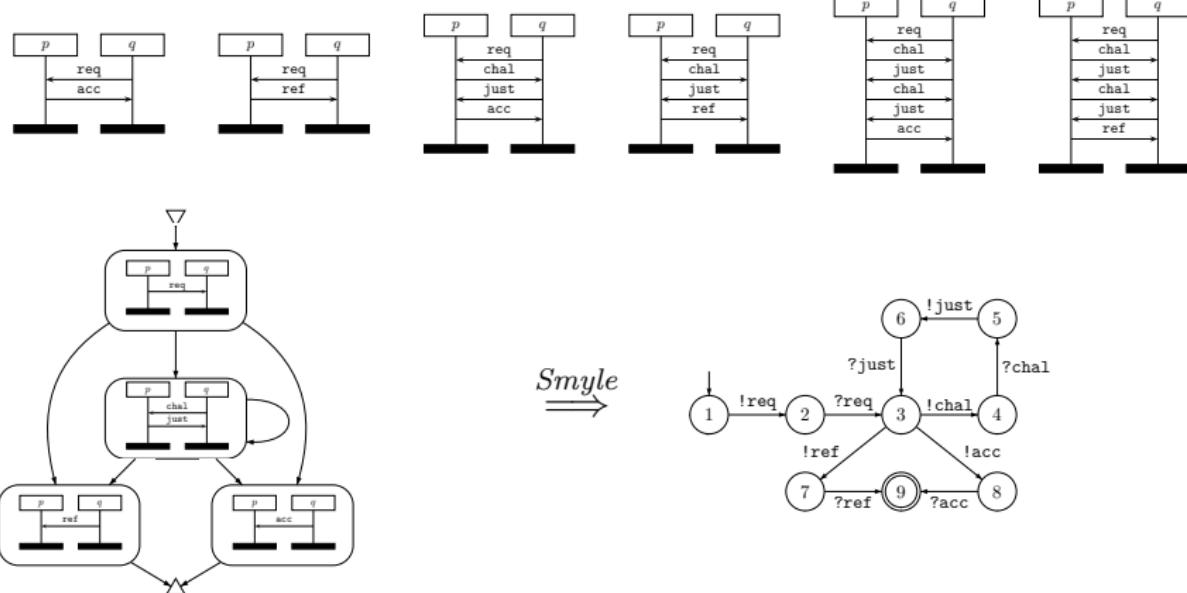
- \forall -bounded product MPA

Presentation outline

- 1 Introduction
- 2 Angluin's Learning Approach
- 3 Learning Design Models
- 4 Dedicated Tool: *Smyle*
- 5 Conclusion

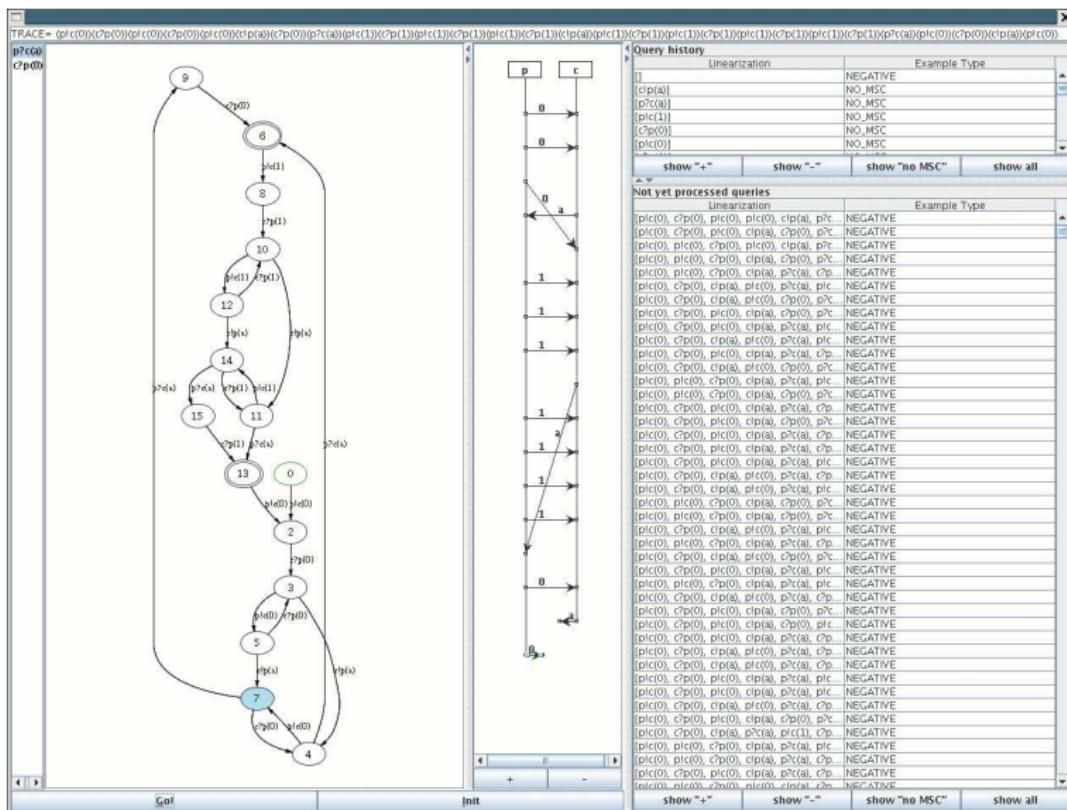
Tool Demo

A Negotiation Protocol



membership queries: 9675
user queries: 60

Alternating Bit Protocol (after 105 user queries)



Implementation of learning approach: Smyle



S(ythesizing) M(odels) (b)Y L(earning from) E(xamples)

- written in Java 1.5
- uses LearnLib library from University of Dortmund
(Lehrstuhl 5, Prof. Dr. Bernhard Steffen)
- **Smyle homepage:**
<http://smyle.in.tum.de>

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Related Work

Similar Approaches

- *Play-In/Play-Out* approach [Harel et al.]
 - use the more expressive language of LSCs
 - more involved treatment of negative scenarios
- MAS (Minimally Adequate Synthesizer) [Mäkinen et al.]
 - based on Angluin's learning approach
 - only synchronous/sequential behavior
 - implementation model is not distributed

Outlook

Current Work

- more efficient partial order treatment
- dealing with *don't know* answers
- discover new/broader classes of learnable MPA
- case studies
- ...



<http://smyle.in.tum.de>

Thank you for your attention!