

Learning Communicating and Nondeterministic Automata

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Main results

- New learning algorithm for NFA (NL*)
- Extension of existing learning algorithm towards learning CFMs
- Optimizations of learning algorithms
- Tools implementing these algorithms
- New software lifecycle model embedding our learning approach

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- New software lifecycle model embedding our learning approach

Areas of application

- Formal verification (e.g., regular model checking)
- Bioinformatics (e.g., prediction of structure of proteins)
- Robotics (e.g., learning environment models)
- Computational linguistics (e.g., compiling idiom dictionaries)
- ...

Outline

- 1 Learning Deterministic Automata
- 2 Learning Nondeterministic Automata
- 3 Learning Communicating Automata
- 4 Tools
- 5 Conclusion

Presentation outline

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Given exemplifying behavior of a system

Learn a *model* conforming to the given behavior

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Occam's razor:

“In case of different explanations, choose the *simplest* one.”

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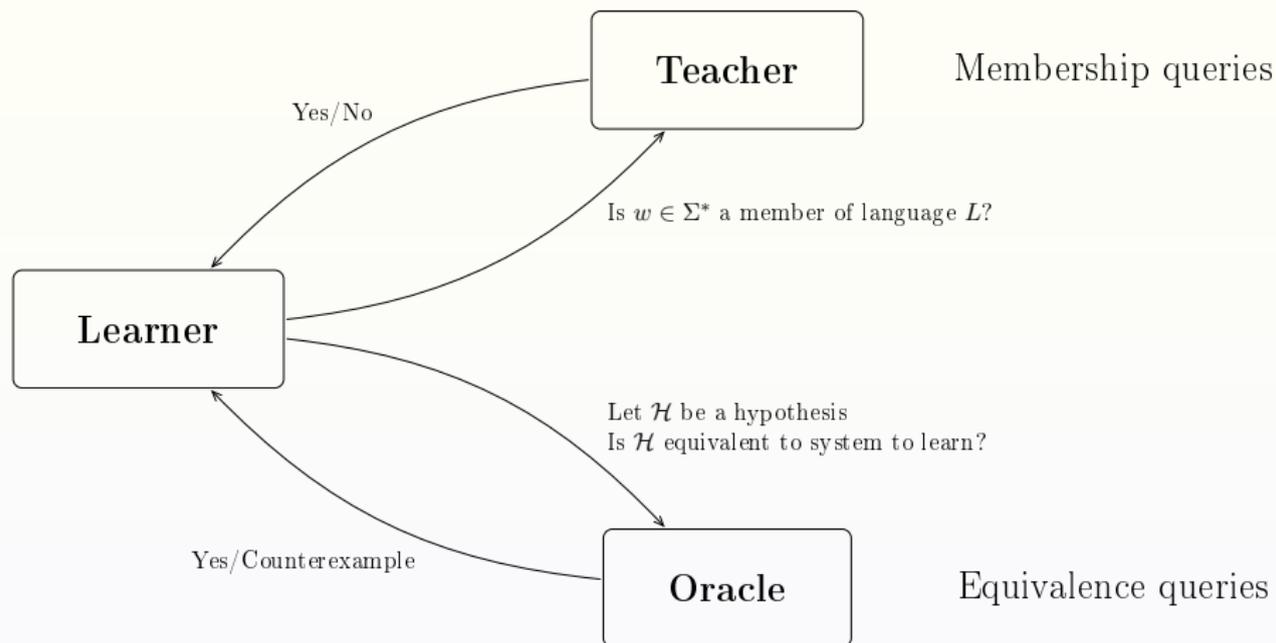
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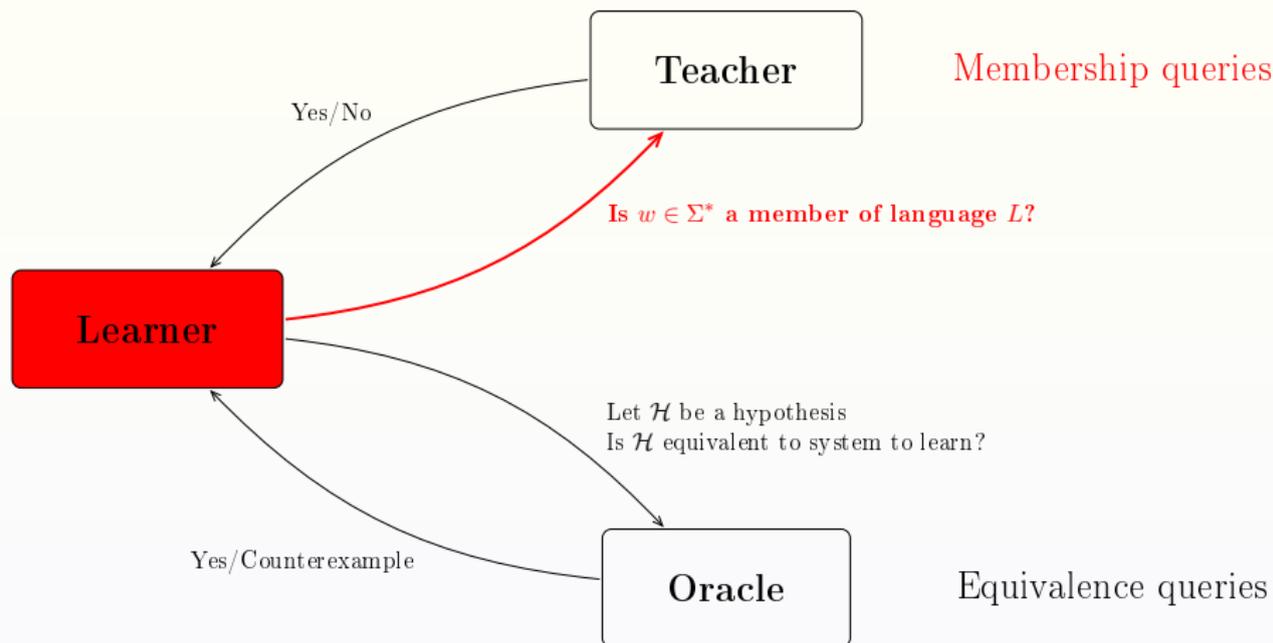
“In case of different explanations, choose the *simplest* one.”
⇒ Learn the *minimal* DFA conforming to given examples

Algorithm - Overview



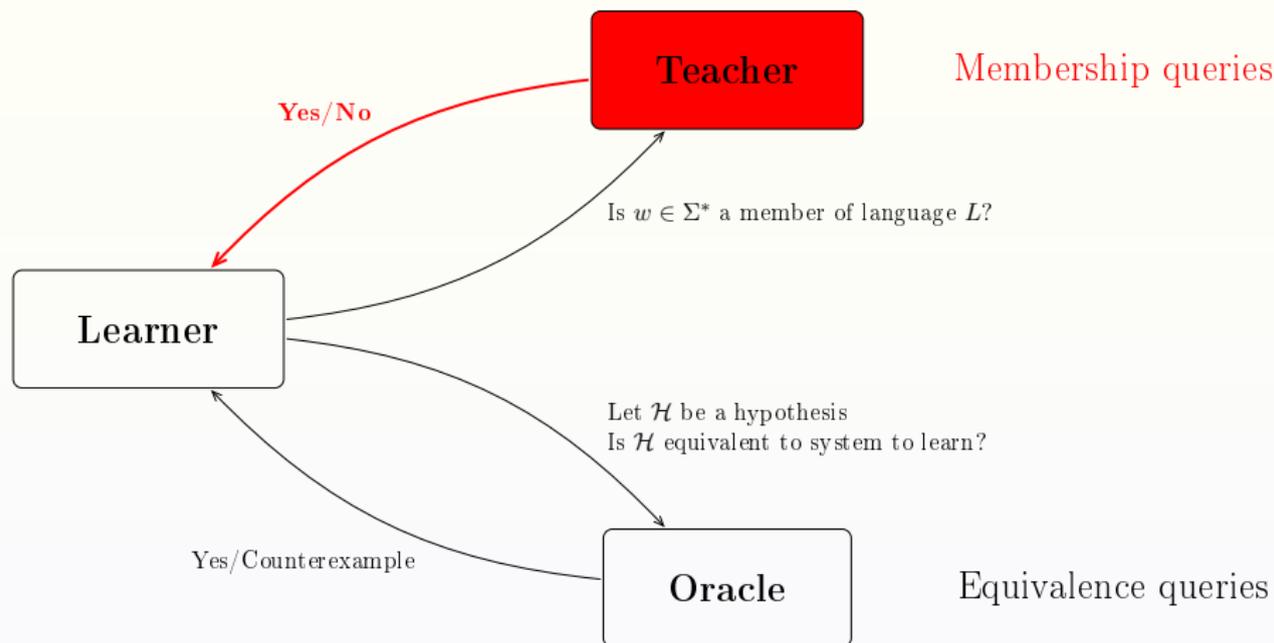
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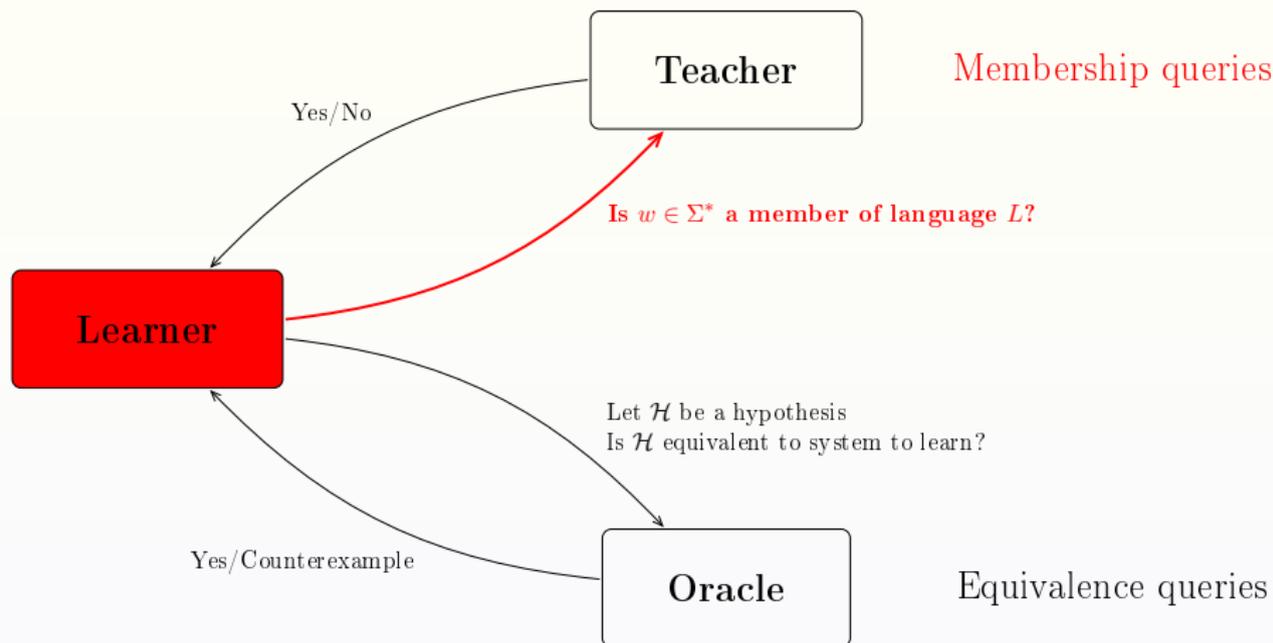
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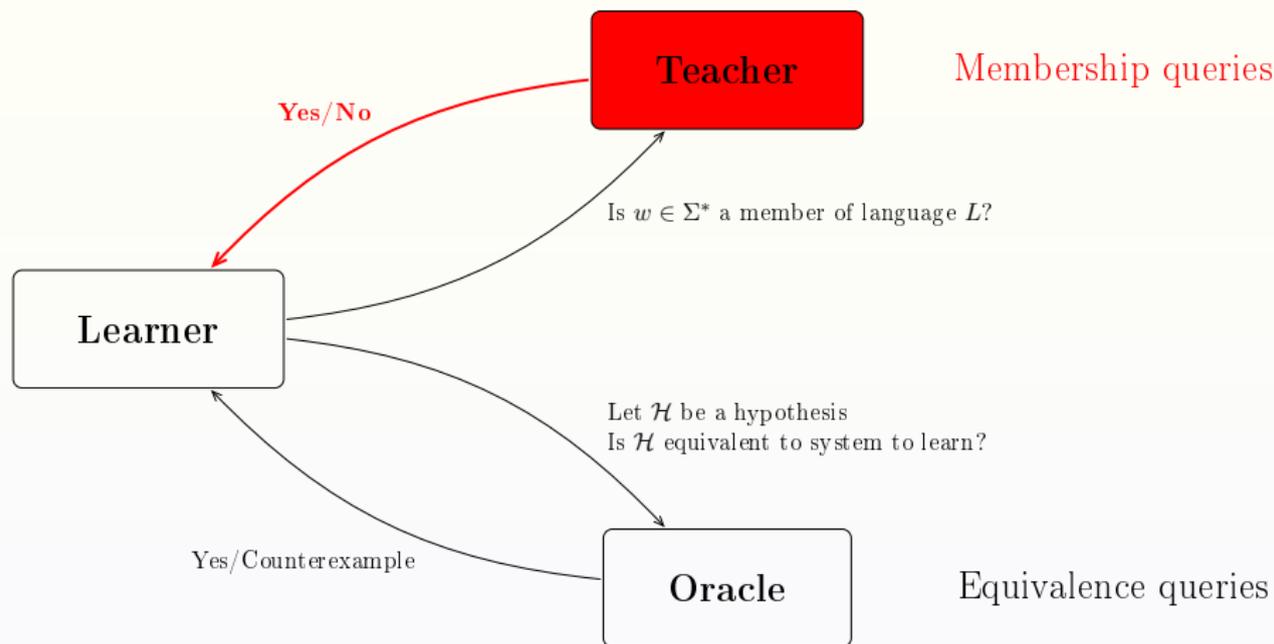
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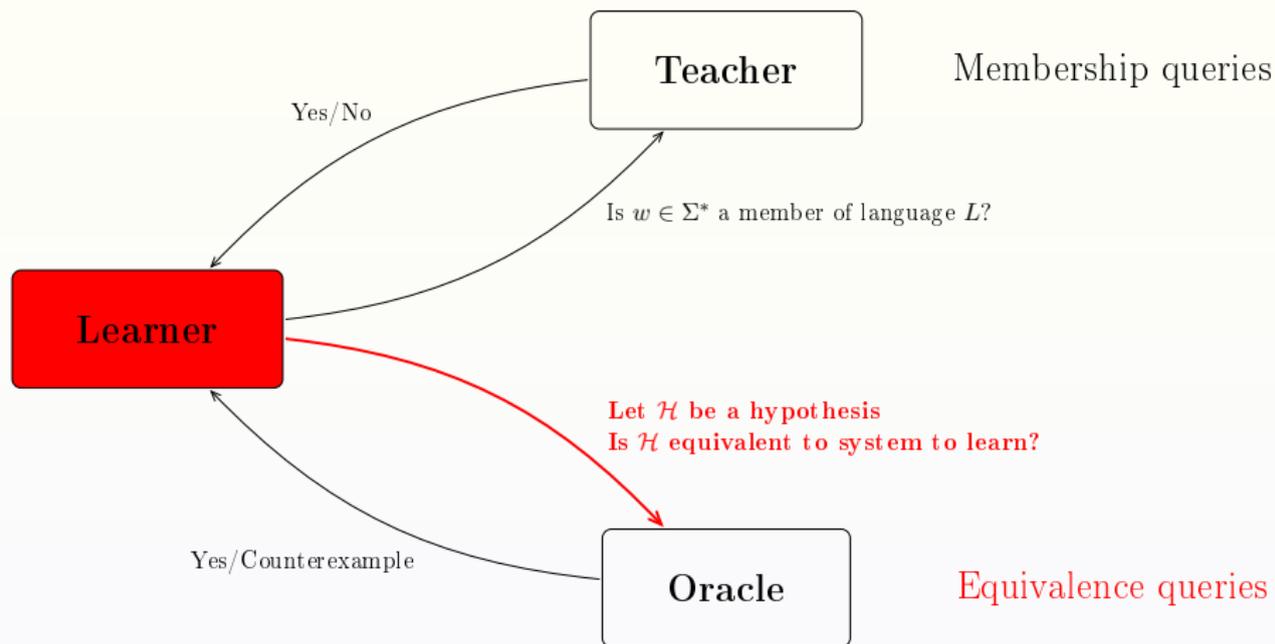
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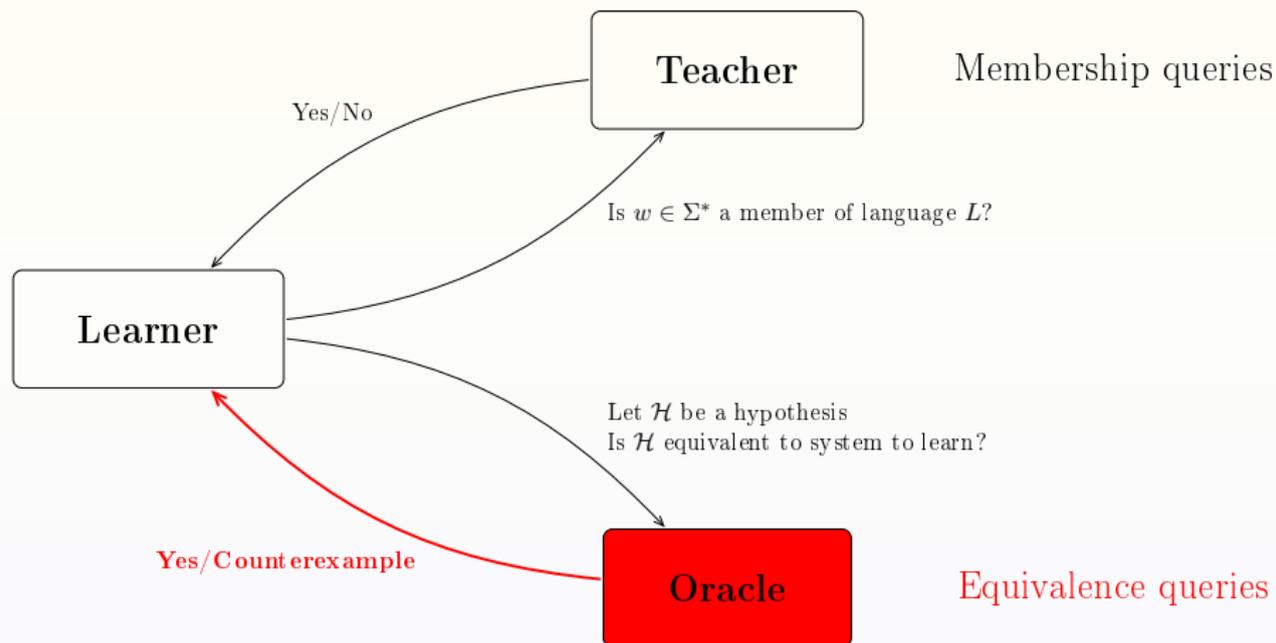
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- L : (regular) language to learn
- Counterexample: $w \in (L(\mathcal{H}) \setminus L) \cup (L \setminus L(\mathcal{H}))$

Table-based learning

Let $\Sigma = \{a, b\}$

\mathcal{T}	ε
ε	
a	
b	
aa	
ab	

$\varepsilon \in L?$

Table-based learning

Let $\Sigma = \{a, b\}$

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$b, aa, ab \in L?$

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To derive an automaton:

- \mathcal{T} must be **closed**, i.e., all states are derivable from \mathcal{T}

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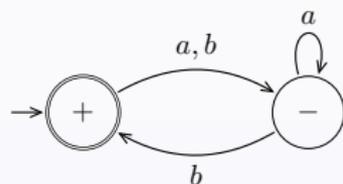
To derive an automaton:

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- \mathcal{T} must be **consistent**, i.e., there are no contradicting transitions

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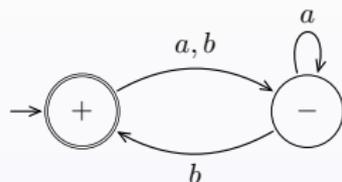
To this end:

- upper rows serve to derive states
- lower rows serve to derive transitions

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<hr/>	
b	-
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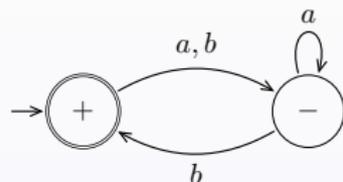
$bb \in L(\mathcal{H})$ but $bb \notin L!$

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Counterexample can be added to:



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bb	-
aa	-
ab	+
ba	-
bba	-
bbb	-

Counterexample can be added to:

- the rows (L^*)

Table-based learning

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Counterexample can be added to:

- the rows (L^*)
- the columns (L_{col}^*)

Theorem (Complexity of L^*)

Let:

- n : number of states of the minimal DFA \mathcal{A}_L for regular language L ,
- m : length of the biggest counterexample

Then, L^* returns after at most:

the minimal DFA \mathcal{A} .

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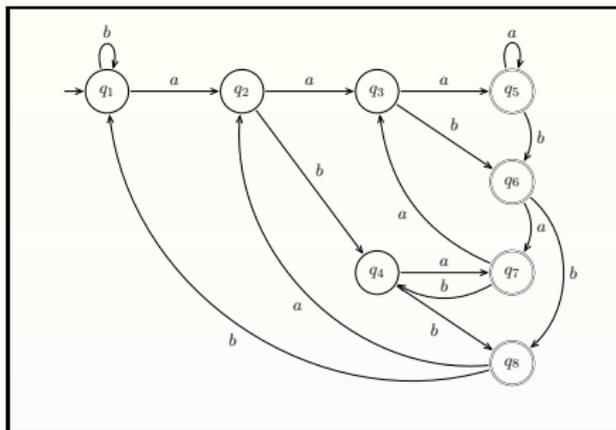
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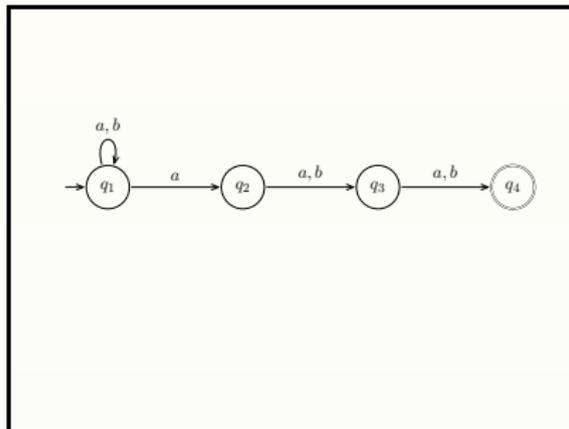
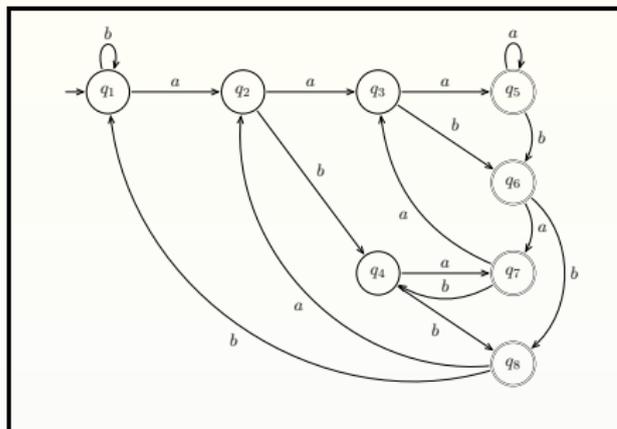
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But there is a problem ...



minimal DFA can be huge!

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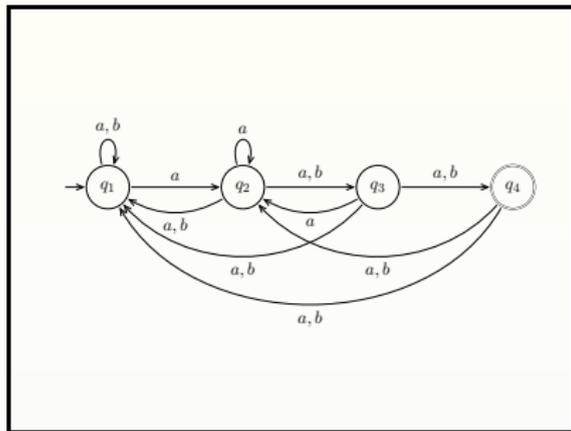
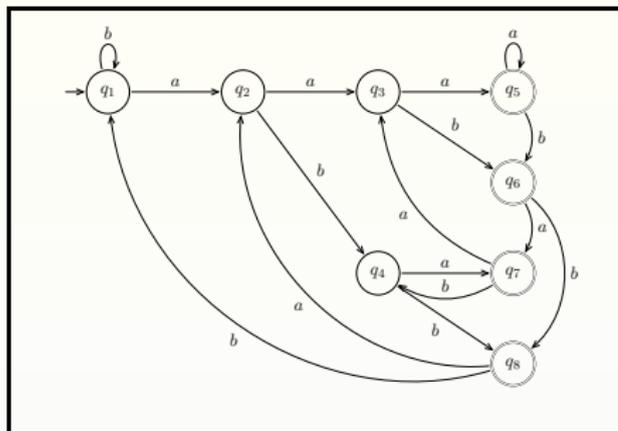


minimal DFA can be huge!

What about more succinct representations like NFA?

Can we learn (a certain subclass of) NFA?

But there is a problem ...



minimal DFA can be huge!

What about more succinct representations like NFA?

Can we learn (a certain subclass of) NFA?

Yes, we can!

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- DFA can be huge
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- Learn **more compact representations** of regular languages

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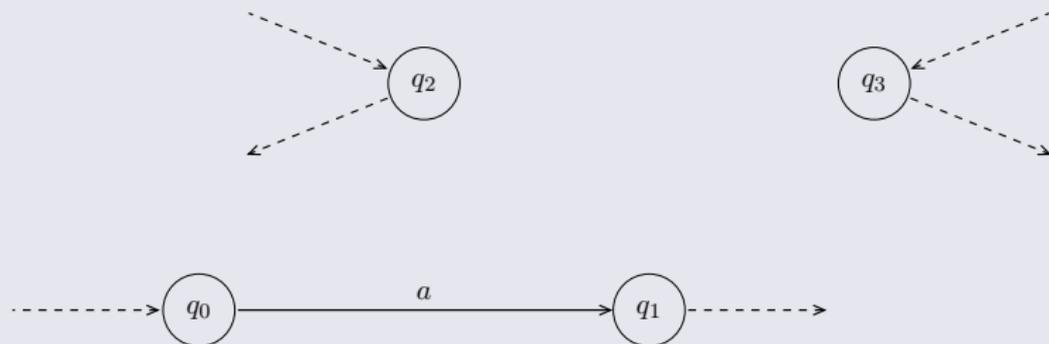
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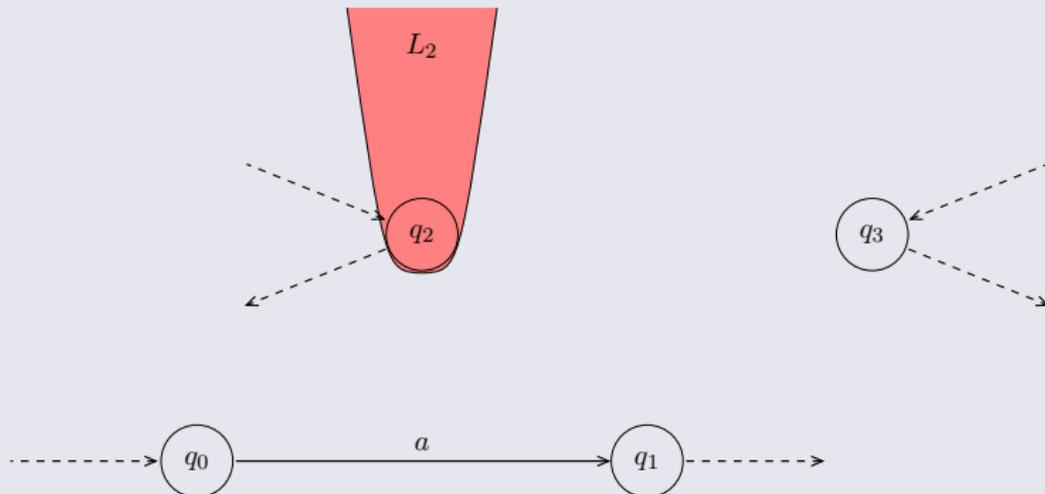
How?

- Use residual finite-state automata (RFSA) for learning

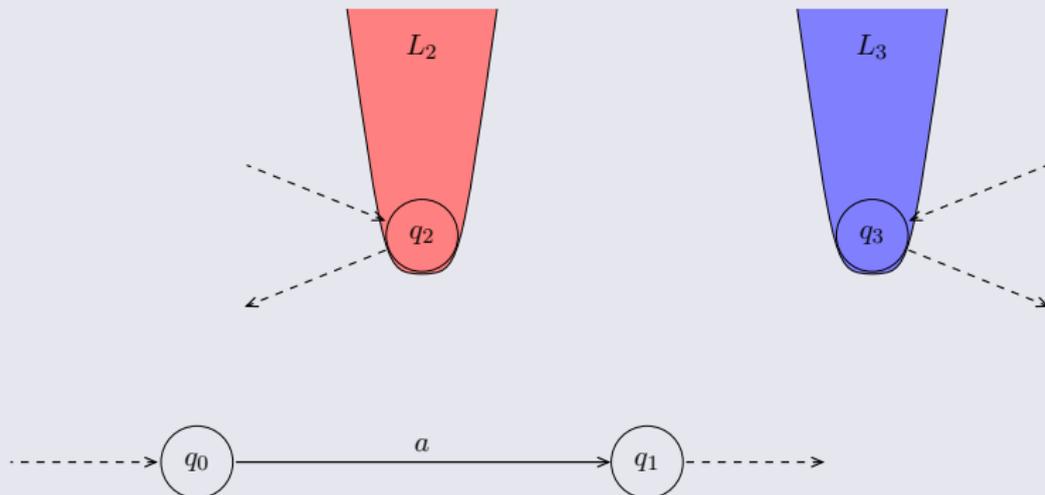
Residual Finite-State Automata [Denis et al.]



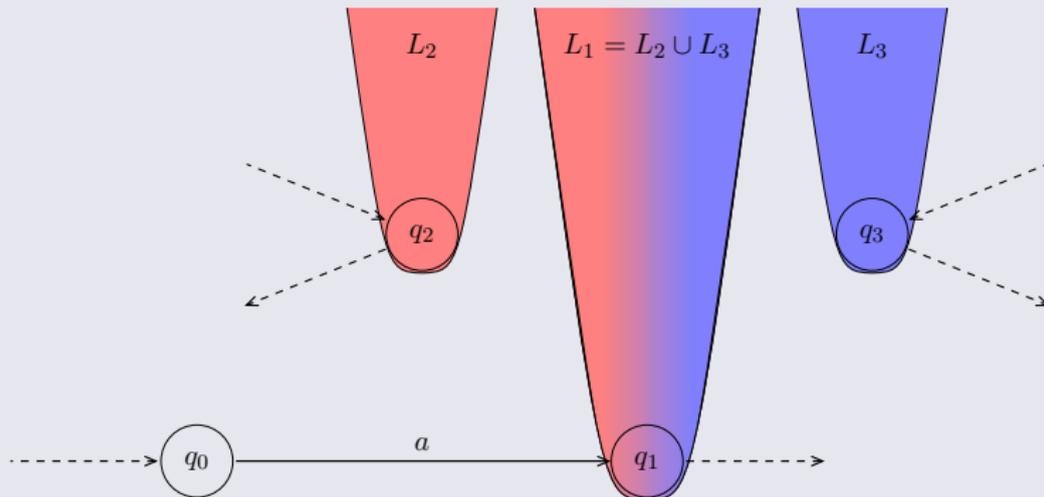
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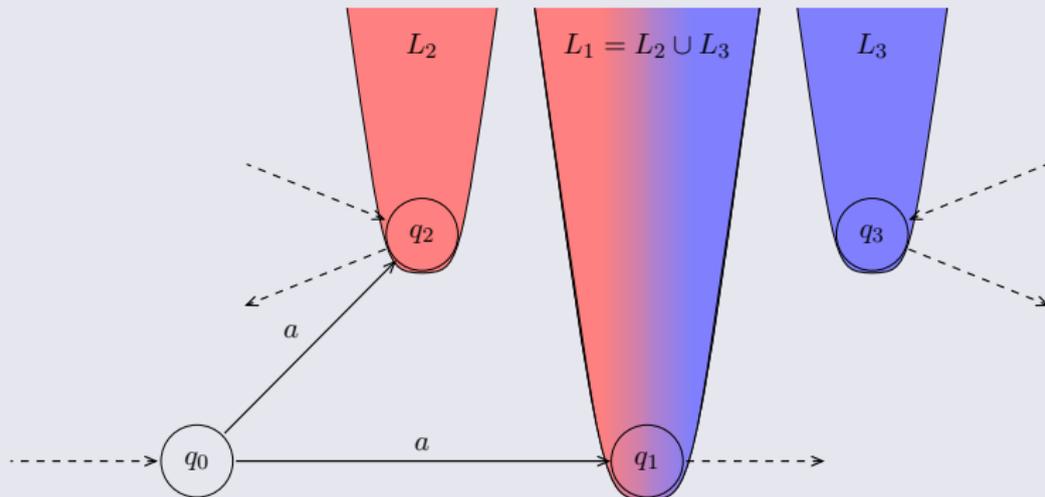
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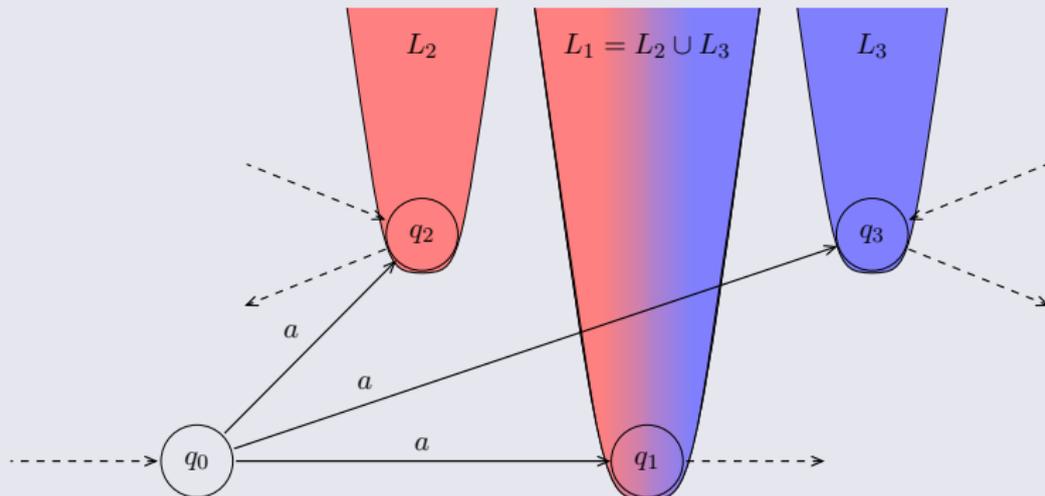
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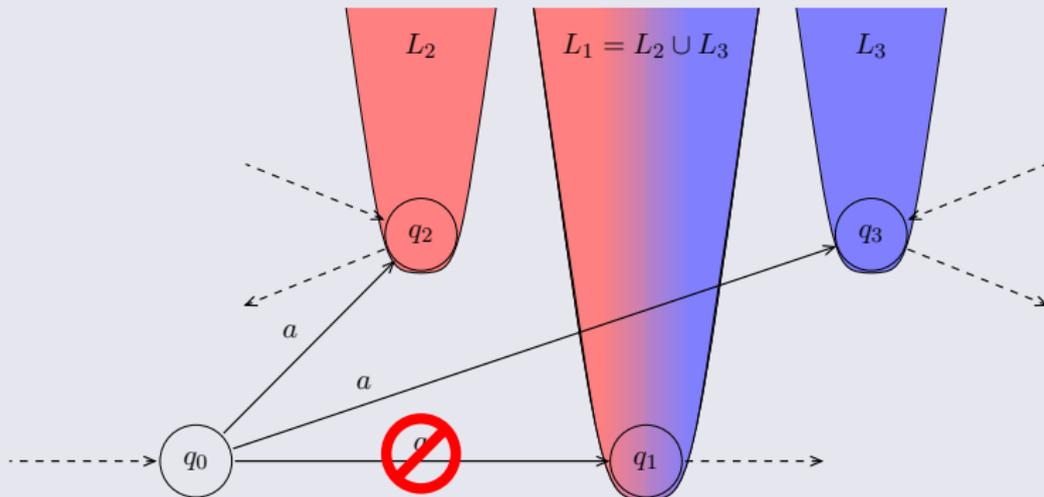
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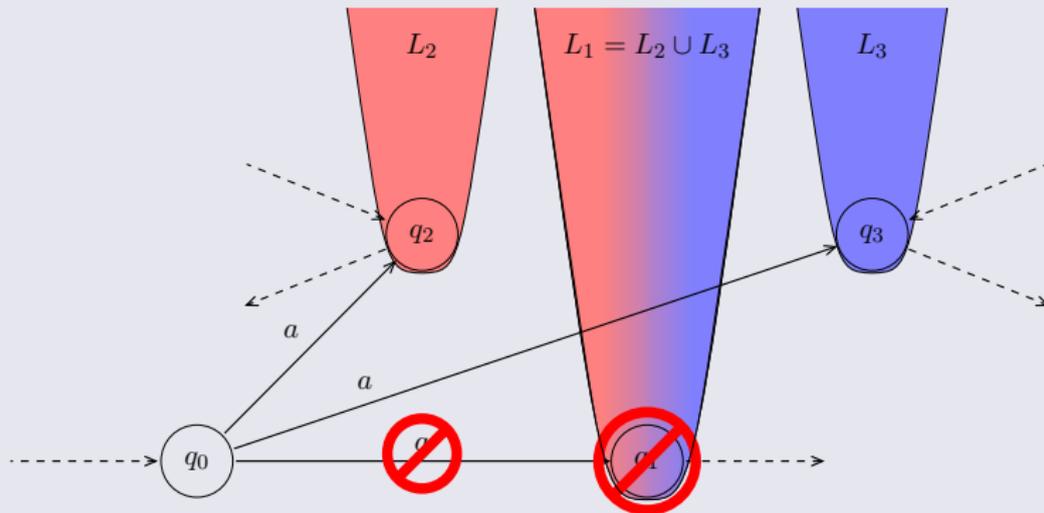
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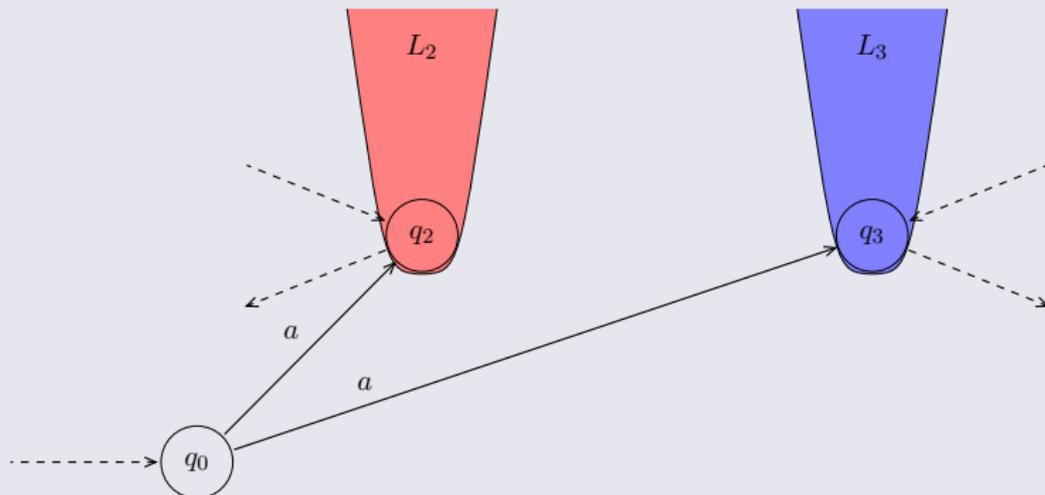
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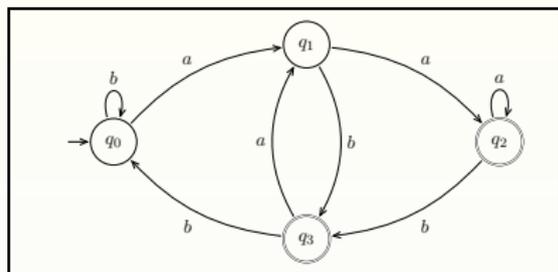
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Residual Finite-State Automata



Definition (Residual Language)

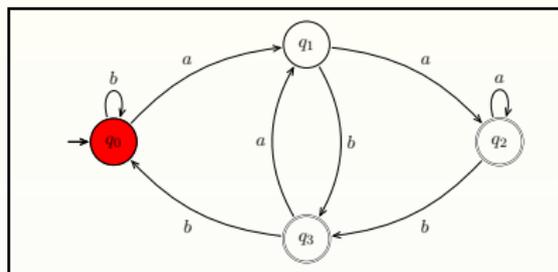
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$$u^{-1}L = \{v \in \Sigma^* \mid uv \in L\} \quad (u\text{-residual of } L)$$

$L' \subseteq \Sigma^*$ is a **residual language of L** if: $\exists u \in \Sigma^*$ with $L' = u^{-1}L$.

$Res(L)$: the set of residual languages of L .

Residual Finite-State Automata



$$\bullet \varepsilon^{-1}L = \Sigma^* a \Sigma \quad (= L_{q_0})$$

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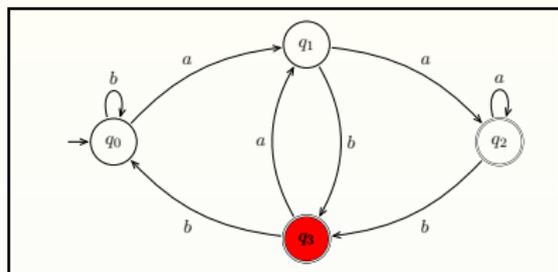
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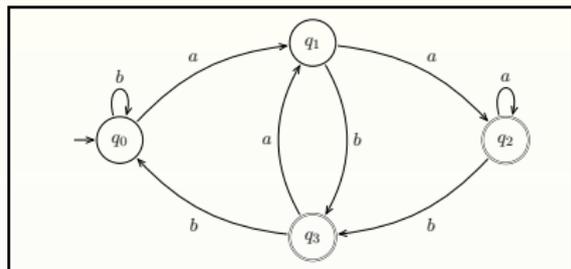
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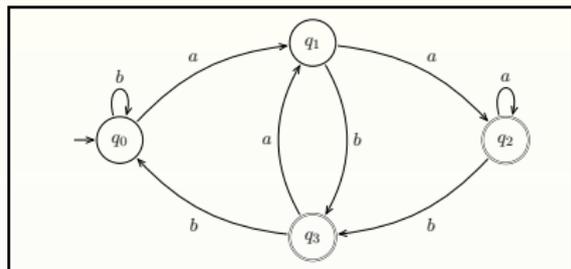
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Definition (Residual Finite-State Automaton)

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Residual Finite-State Automata

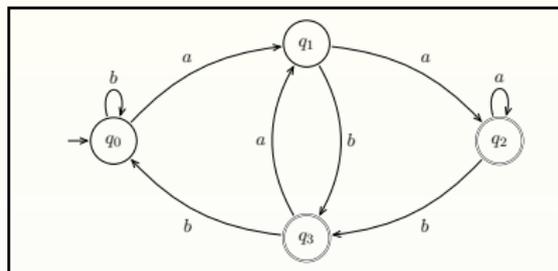


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Definition (Prime and Composed Residuals)

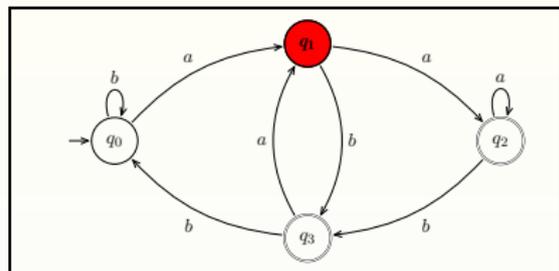
Let $L \subseteq \Sigma^*$ be a language. A residual $L' \in Res(L)$ is called **composed** if there are $L_1, \dots, L_n \in Res(L) \setminus \{L'\}$ such that

$$L' = L_1 \cup \dots \cup L_n$$

Otherwise, it is called **prime**.

The set of prime residuals of L is denoted by $Primes(L)$.

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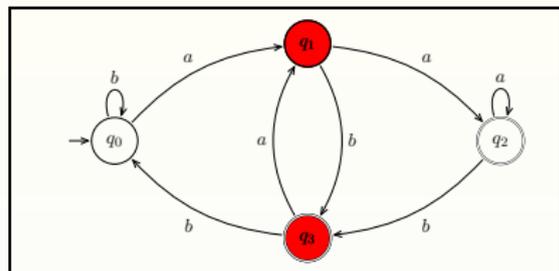
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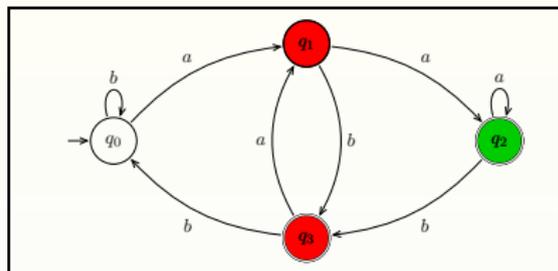
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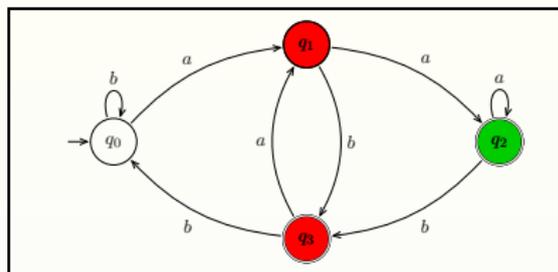
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Canonical RFSA



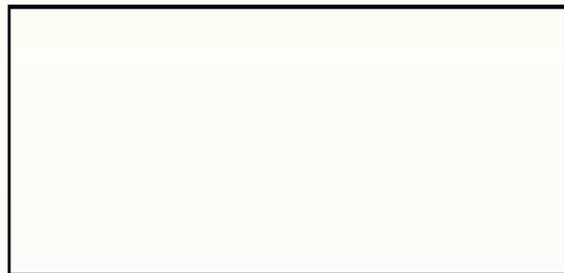
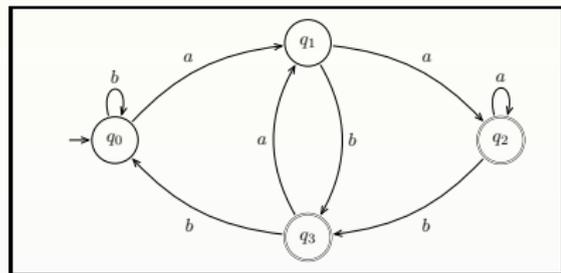
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Definition (Canonical RFSA [Denis, Lemay, Terlutte'02])

Let L be a regular language. The **canonical RFSA** of L , denoted by $\mathcal{R}(L)$, is the tuple (Q, Q_0, F, δ) where

- $Q = \text{Primes}(L)$,
- $Q_0 = \{L' \in Q \mid L' \subseteq L\}$,
- $F = \{L' \in Q \mid \varepsilon \in L'\}$, and
- $\delta(L_1, a) = \{L_2 \in Q \mid L_2 \subseteq a^{-1}L_1\}$, for $a \in \Sigma$.

Example: Deriving the canonical RFSA for $L = \Sigma^* a \Sigma$



Residual languages for $L = \Sigma^* a \Sigma$

$$L_{q_0} = \Sigma^* a \Sigma$$

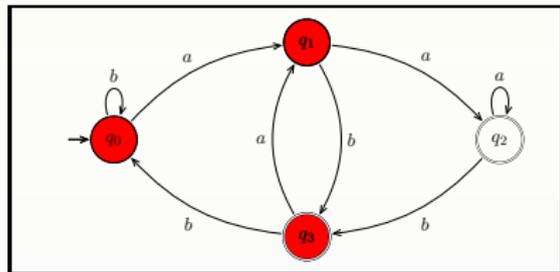
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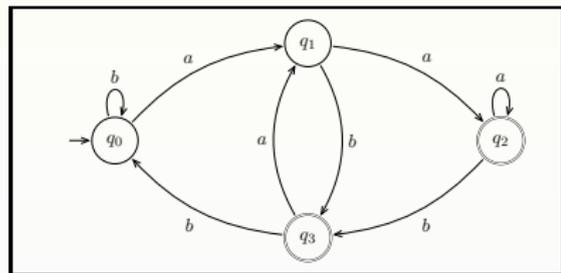
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Residual languages for $L = \Sigma^* a \Sigma$

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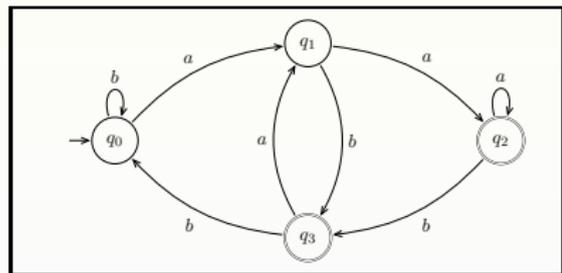
$$L_{q_1} = \Sigma^* a \Sigma \cup \Sigma$$

$$L_{q_2} = \Sigma^* a \Sigma \cup \Sigma \cup \{\varepsilon\}$$

$$L_{q_3} = \Sigma^* a \Sigma \cup \{\varepsilon\}$$

Example: Deriving the canonical RFSA for $L = \Sigma^* a \Sigma$

Initial states: $Q_0 = \{L' \in Q \mid L' \subseteq L\}$,



Residual languages for $L = \Sigma^* a \Sigma$

$$L_{q_0} = \Sigma^* a \Sigma \quad (\text{initial state})$$

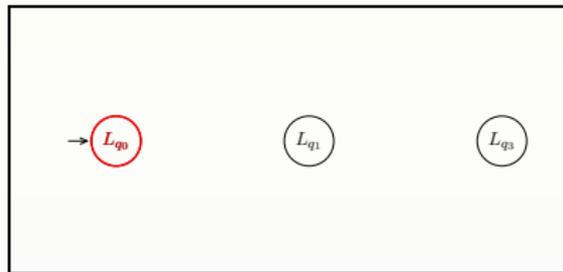
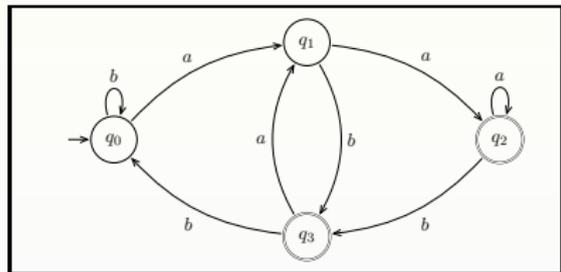
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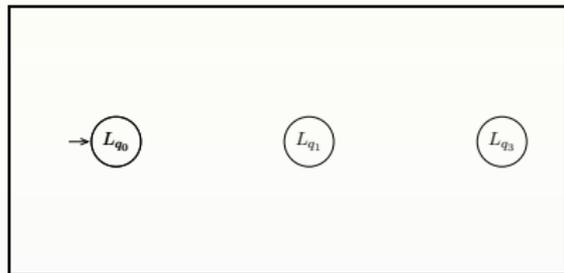
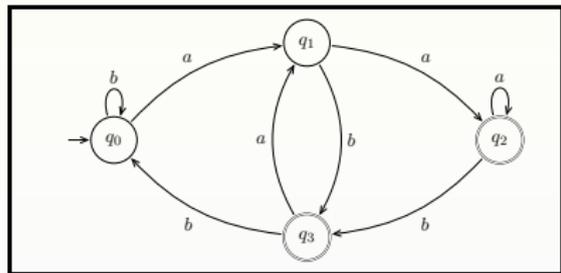
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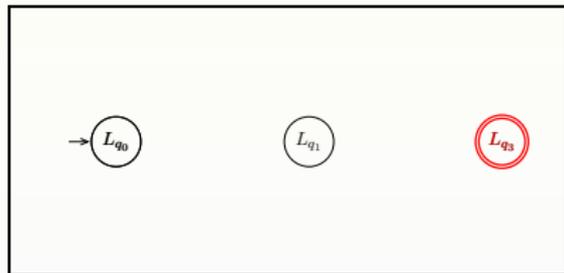
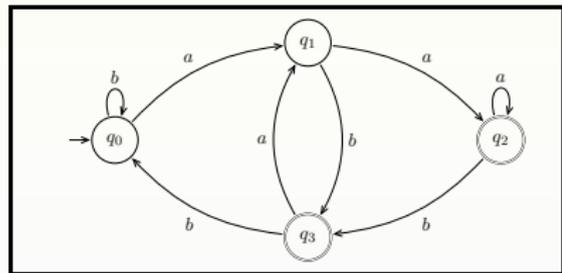
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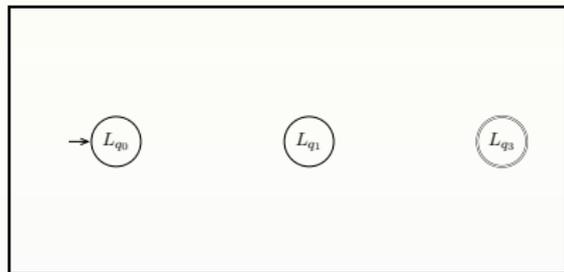
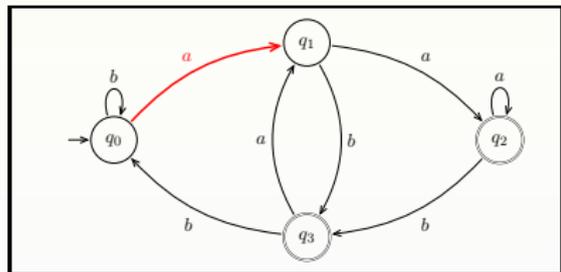
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Transitions: $\delta(L_1, a) = \{L_2 \in Q \mid L_2 \subseteq a^{-1}L_1\}$, for $a \in \Sigma$.



Residual languages for $L = \Sigma^* a \Sigma$

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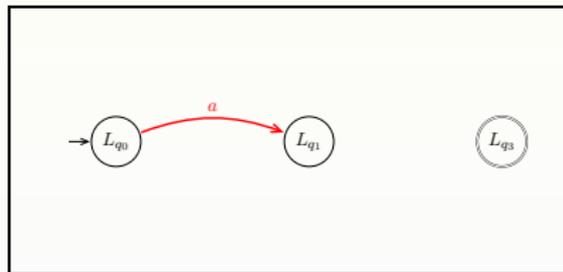
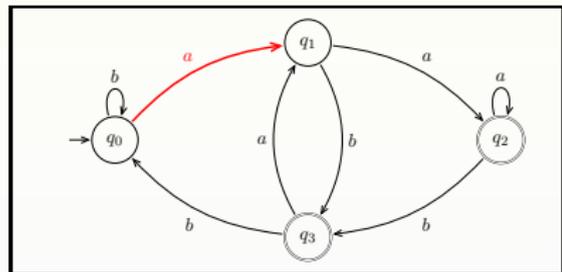
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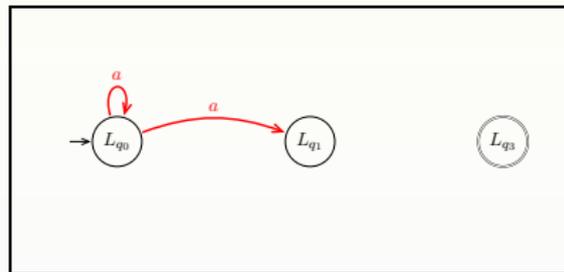
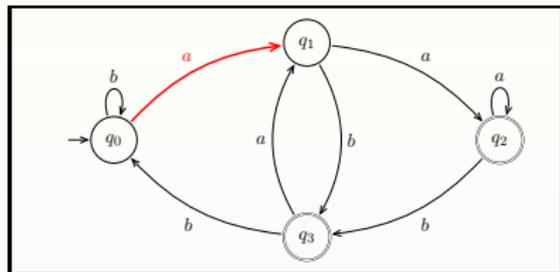
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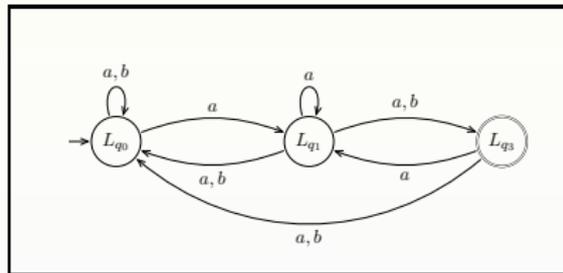
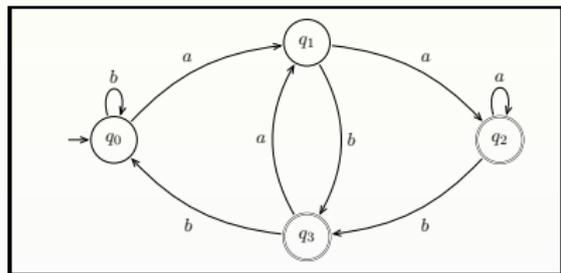
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Designing a table-based learning algorithm

Let $\mathcal{T} = (T, U, V)$ be a table. Find *analogon to union of residuals*

Definition (Join Operator)

join of two rows $r_1, r_2 \in \text{Rows}(\mathcal{T})$ is defined component-wise for each $v \in V$:

$(r_1 \sqcup r_2) : V \rightarrow \{+, -\}$:

$(r_1 \sqcup r_2)(v) = r_1(v) \sqcup r_2(v)$ where

- $- \sqcup - = -$ and
- $+ \sqcup + = + \sqcup - = - \sqcup + = +$

\mathcal{T}	ε	a	aa
ε	-	-	+
a	-	+	+
ab	+	-	+
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aa	+	+	+
aba	-	+	+
abb	-	-	+

Example

$\text{row}(a) \sqcup \text{row}(ab) = (-, +, +) \sqcup (+, -, +) = (+, +, +) = \text{row}(aa)$

Designing a table-based learning algorithm

Find analogon to *Composed and prime residuals*

Definition (Composed and Prime Rows)

Row $r \in Rows(\mathcal{T})$ is called:

- **composed** if there are rows $r_1, \dots, r_n \in Rows(\mathcal{T}) \setminus \{r\}$ such that $r = r_1 \sqcup \dots \sqcup r_n$.

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aa	+	+	+
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abb	-	-	+

Example

Row $(+, +, +)$ is composed:

$$row(aa) = (+, +, +) = (-, +, +) \sqcup (+, -, +) = row(a) \sqcup row(ab)$$

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- **prime, otherwise.**

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b	-	-	+
aa	+	+	+
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abb	-	-	+

Example

E.g. rows $(-, -, +)$, $(-, +, +)$ are prime

Designing a table-based learning algorithm

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$Primes(\mathcal{T})$: The set of prime rows in \mathcal{T} and

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b	-	-	+
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Example

$Primes(\mathcal{T}) = \{row(\varepsilon), row(a), row(ab), row(b), row(aba), row(abb)\}$

Designing a table-based learning algorithm

Find analogon to *Composed and prime residuals*

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ab	+	-	+
b	-	-	+
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Example

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Designing a table-based learning algorithm

Find analogon to *subset relation between residuals*

Definition (Covering Relation)

Row $r \in Rows(\mathcal{T})$ is:

- covered by row $r' \in Rows(\mathcal{T})$ ($r \sqsubseteq r'$), if for all $v \in V$: $r(v) = + \Rightarrow r'(v) = +$.

\mathcal{T}	ε	a	aa
ε	-	-	+
a	-	+	+
ab	+	-	+
b	-	-	+
aa	+	+	+
aba	-	+	+
abb	-	-	+

Example

- e.g., $row(\varepsilon) \sqsubseteq row(a)$ and $row(\varepsilon) \sqsubseteq row(abb)$

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Designing a table-based learning algorithm

Find analogon to *subset relation between residuals*

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- **covered** by row $r' \in Rows(\mathcal{T})$ ($r \sqsubseteq r'$), if for all $v \in V$: $r(v) = + \Rightarrow r'(v) = +$.
- If moreover $r' \neq r$, then r is **strictly covered** by r' , denoted by $r \sqsubset r'$.

\mathcal{T}	ε	a	aa
ε	-	-	+
a	-	+	+
ab	+	-	+
b	-	-	+
aa	+	+	+
aba	-	+	+
abb	-	-	+

Example

- e.g., $row(\varepsilon) \sqsubseteq row(a)$ and $row(\varepsilon) \sqsubseteq row(abb)$
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Table properties

Find analogon to *closedness and consistency* in L^*

\mathcal{T}	ε	a	aa
ε	-	-	+
a	-	+	+
ab	+	-	+
b	-	-	+
aa	+	+	+
aba	-	+	+
abb	-	-	+

RFSA-Closedness

- all states identifiable from the table

Table properties

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- all *non-composed* rows have to be in the upper part of the table

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RFSA-Consistency

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Definition (NFA of a Table)

For a table $\mathcal{T} = (T, U, V)$ that is RFSA-closed and RFSA-consistent, we define an NFA $\mathcal{R}_{\mathcal{T}} = (Q, Q_0, F, \delta)$ by

- $Q = \text{Primes}_{\text{upp}}(\mathcal{T})$,
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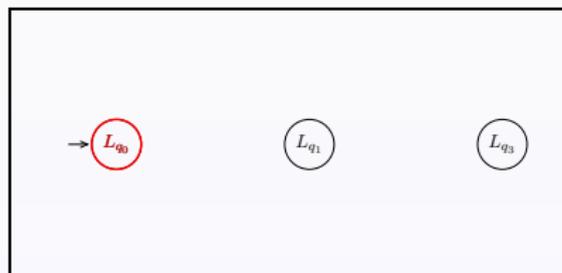


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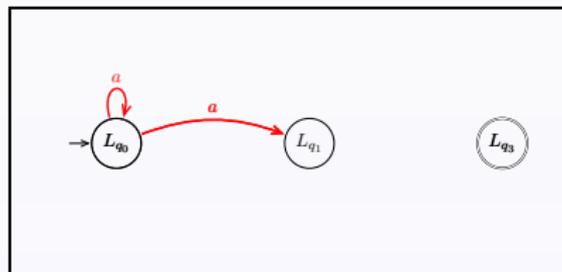
From Table to NFA

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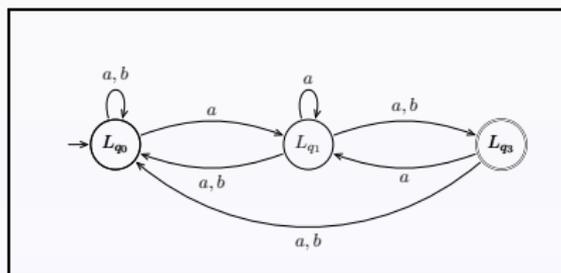
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Summarizing: Tables in NL^*

\mathcal{T}	ε	a	aa
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a	-	+	+
ab	+	-	+
b	-	-	+
aa	+	+	+
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From tables to RFSA

- we deal with tables

Summarizing: Tables in NL^*

\mathcal{T}	ε	a	aa
ε	-	-	+
a	-	+	+
ab	+	-	+
b	-	-	+
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From tables to RFSA

- we deal with tables
- table rows approximate residual languages
- not all rows represent states
- as long as there is no other evidence: equal rows represent equal residual languages
- transition relation respects language inclusion
- **treatment of counterexamples:**
 - add to columns (as in L_{col}^*)
 - otherwise non-termination

Definition (Consistency with a table)

We say that $\mathcal{R}_{\mathcal{T}}$ is **consistent with the table \mathcal{T}** if, for all $w \in (U \cup U\Sigma)V$, we have $T(w) = +$ iff $w \in L(\mathcal{R}_{\mathcal{T}})$.

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Theorem (Correctness)

Let \mathcal{T} be a table that is **RFSA-closed** and **RFSA-consistent** and let $\mathcal{R}_{\mathcal{T}}$ be **consistent with \mathcal{T}** . Then, $\mathcal{R}_{\mathcal{T}}$ is a **canonical RFSA**.

Theorem (Complexity of NL^*)

Let:

- n : number of states of minimal DFA \mathcal{A}_L for regular language L ,
- m : length of the biggest counterexample

Then, NL^* returns after at most:

the **canonical RFSA** $\mathcal{R}(L)$.

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- $O(m|\Sigma|n^3)$ membership queries

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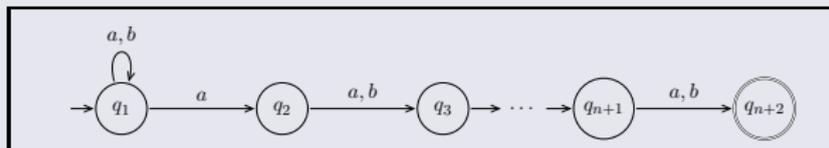
It's worth considering RFSA...

Theorem

There is an *infinite family* of languages $(\{L_n\}_{n \in \mathbb{N}})$ for which NL^* infers *canonical RFSA* that are *exponentially more succinct* than their corresponding *minimal DFA*.

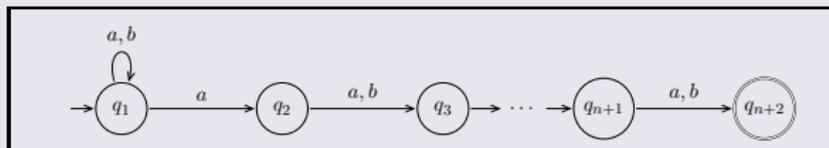
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$$L_n = \{w \in \Sigma^* \mid w \text{ has an } a \text{ at the } (n+1)\text{-last position}\}$$

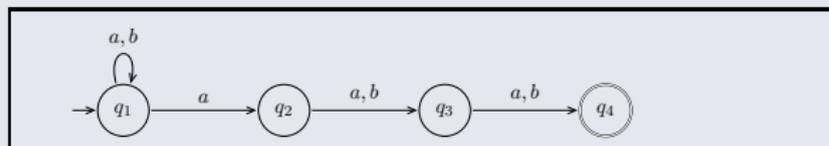


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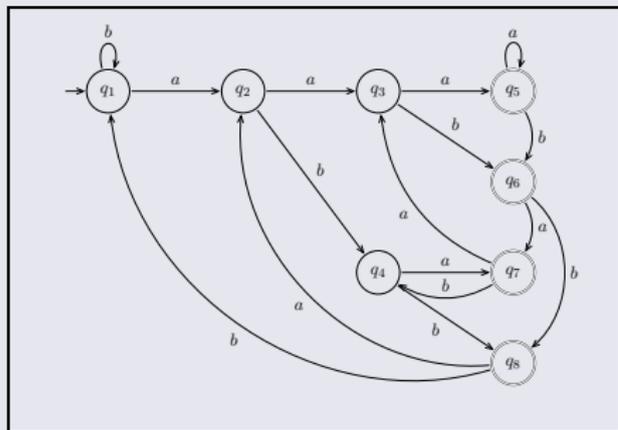


$$L_2 = \{w \in \Sigma^* \mid w \text{ has an } a \text{ at the } 3^{\text{rd}}\text{-last position}\}$$



Minimal DFA and RFSA

Minimal DFA and RFSA for L_2 :

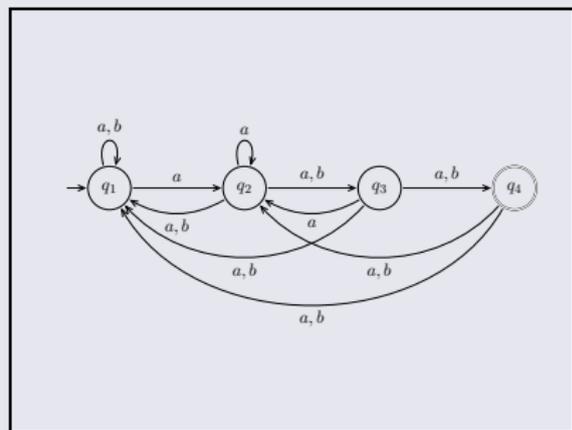
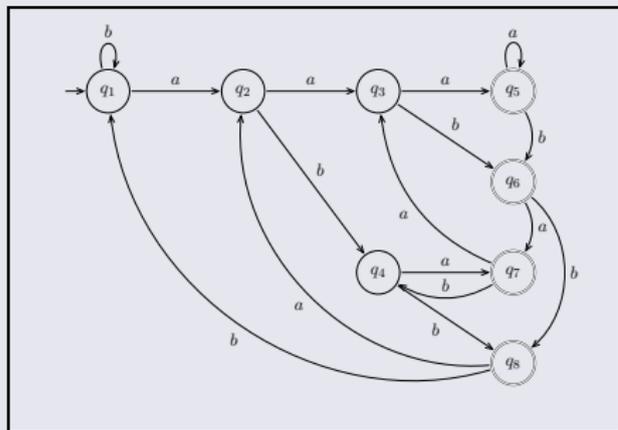


Automata for language L_n :

- minimal DFA general case: 2^{n+1} states

Minimal DFA and RFSA

Minimal DFA and RFSA for L_2 :



Automata for language L_n :

- minimal DFA general case: 2^{n+1} states
- *canonical RFSA* general case: $n + 2$ states

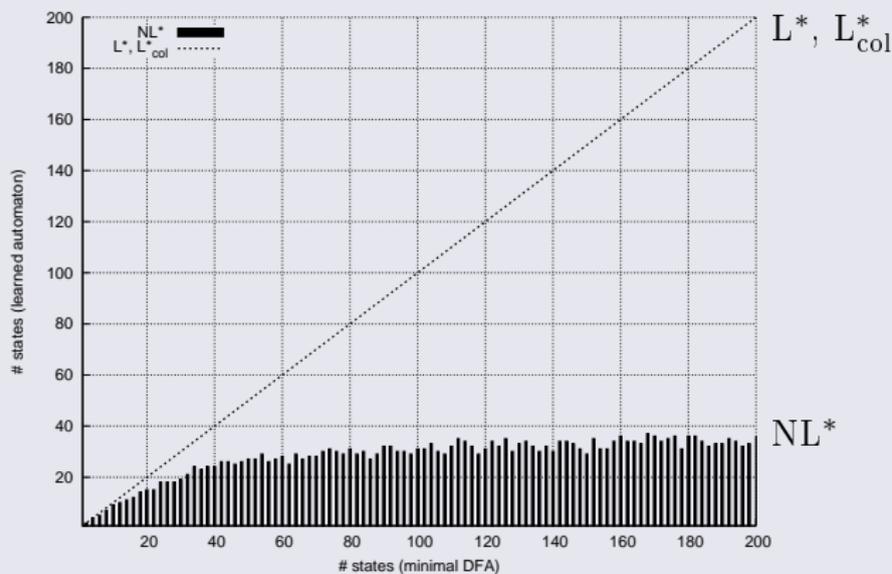
Comparison of L^* , L_{col}^* , and NL^*

	Equivalence queries	Membership queries	Treatment of counterexamples
L^*	n	$\mathcal{O}(m \Sigma n^2)$	to rows
L_{col}^*	n	$\mathcal{O}(m \Sigma n^2)$	to columns
NL^*	$\mathcal{O}(n^2)$	$\mathcal{O}(m \Sigma n^3)$	to columns

Theoretical complexity for the number of queries is a **bit worse** than for learning DFA.

Algorithm - Overview

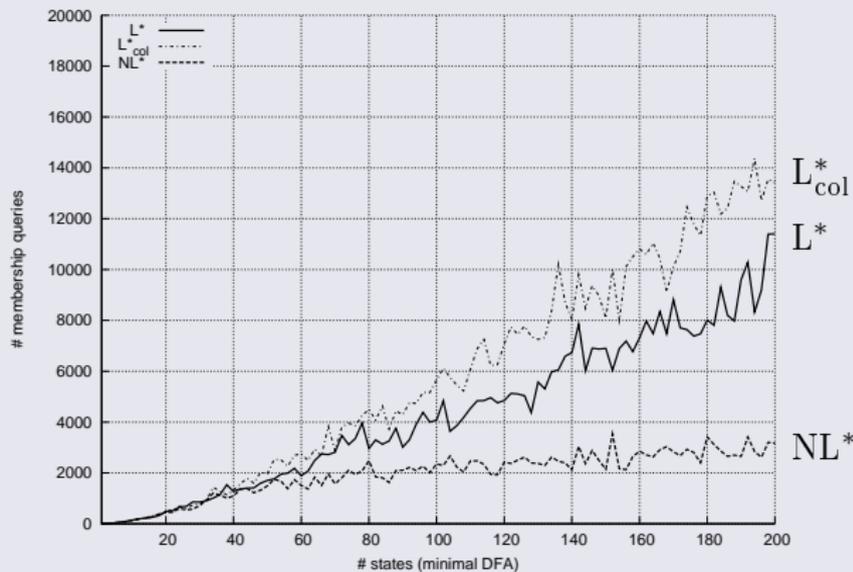
Number of states (L^* , L_{col}^* vs. NL^*)



- ≈ 3200 reg. exp. with minimal DFA of 1 to 200 states

Algorithm - Overview

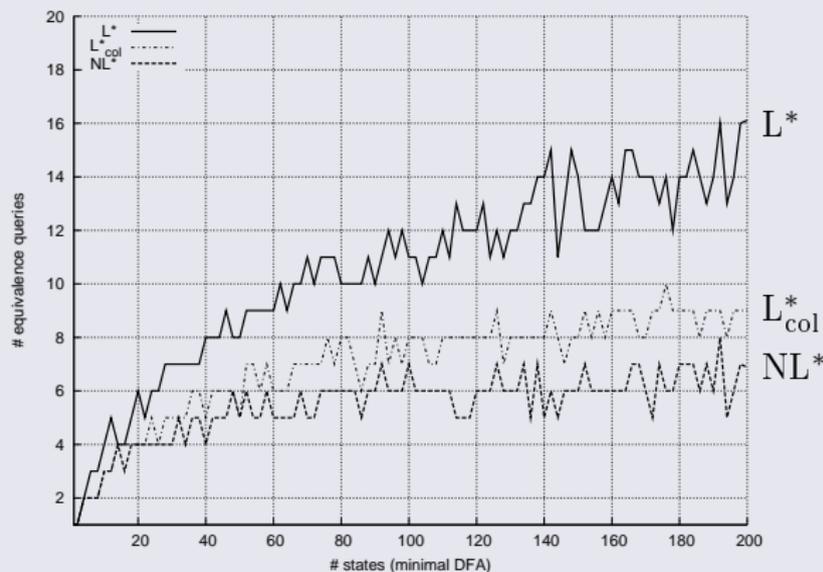
Number of membership queries (L^* vs. L_{col}^* vs. NL^*)



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Algorithm - Overview

Number of equivalence queries (L^* vs. L_{col}^* vs. NL^*)



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Presentation outline

- 1 Learning Deterministic Automata
- 2 Learning Nondeterministic Automata
- 3 Learning Communicating Automata**
- 4 Tools
- 5 Conclusion

Requirements (incomplete)

- initial phase: requirement elicitation
 - contradicting or incomplete system description
 - common description language: sequence diagrams



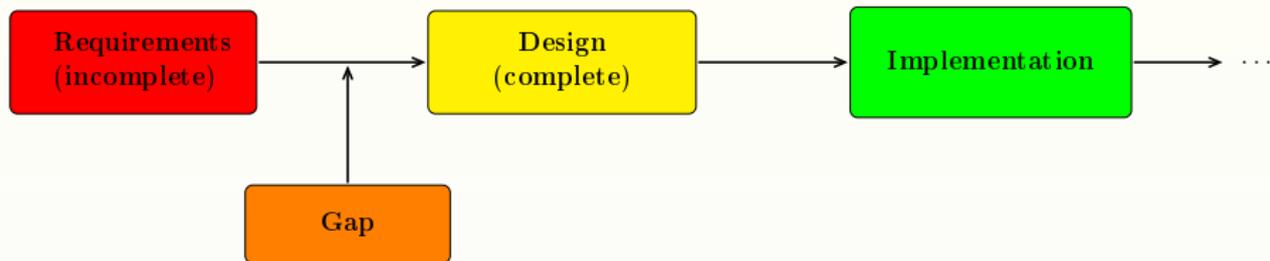
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Motivation

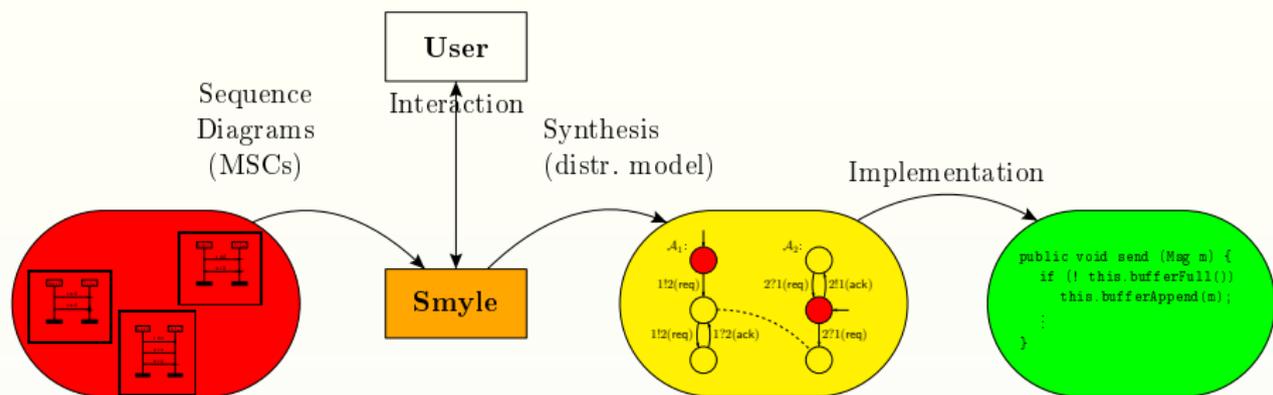


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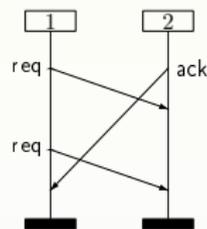
- initial phase: requirement elicitation
 - contradicting or incomplete system description
 - common description language: sequence diagrams
- goal: conforming design model
- closing gap between
 - requirement specification (usually incomplete) and
 - design model (complete description of system)



Our Approach

- use **learning algorithms** to synthesize models for communication protocols
- **Input:** set of Message Sequence Charts
 - standardized: ITU Z.120
 - included in UML as sequence diagrams
- **Output:** Communicating finite-state machine
 - distributed system fulfilling the specification
 - CFM model is close to implementation

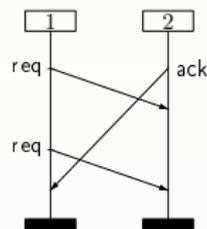
Message Sequence Chart



An MSC $M = \langle \mathcal{P}, E, \{\leq_p\}_{p \in \mathcal{P}}, <_{msg}, l \rangle$

- \mathcal{P} : finite set of processes
- E : finite set of events ($E = \bigcup_{p \in \mathcal{P}} E_p$)
- $l : E \rightarrow Act = \{1!2(req), 1?2(ack), \dots\}$
- for $p \in \mathcal{P}$: $<_p \subseteq E_p \times E_p$ is a total order on E_p
- $<_{msg}$ relates sending and receiving events
- $\leq = \left(<_{msg} \cup \bigcup_{p \in \mathcal{P}} <_p \right)^*$

Message Sequence Chart



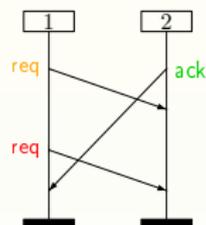
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A set of MSCs is called an *MSC language*

A *linearization* of an MSC is a total ordering of E subsuming \leq

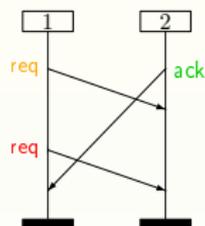
MSCs and Linearizations



Some linearizations

- 1!2(req) 1!2(req) 2!1(ack) 1?2(ack) 2?1(req) 2?1(req)
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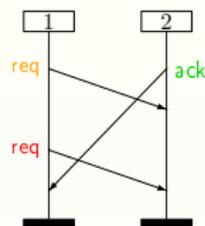


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- An MSC $M = \text{MSC}(w)$ is uniquely determined by any $w \in \text{Lin}(M)$

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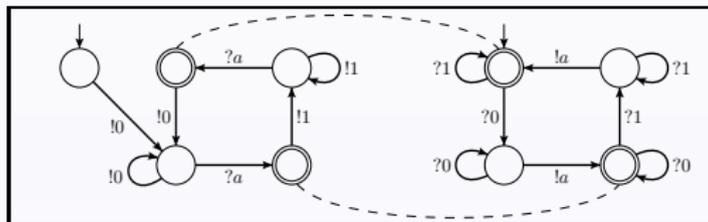
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- An MSC $M = \text{MSC}(w)$ is uniquely determined by any $w \in \text{Lin}(M)$
- Linearizations of an MSC are called *equivalent*
($\forall w, w' \in \text{Lin}(M) : w \approx w'$)

Communicating Finite-State Machines (CFM)

A CFM consists of:

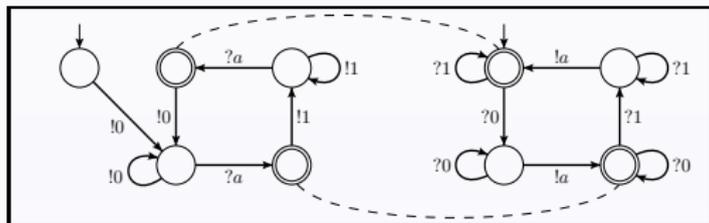
- a set of finite-state automata (*processes*) with
 - common global initial state
 - set of global final states



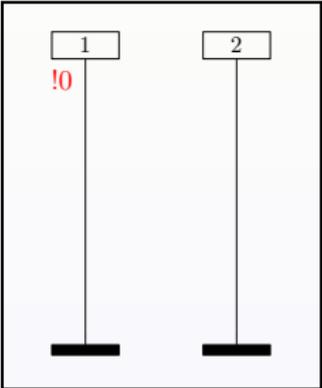
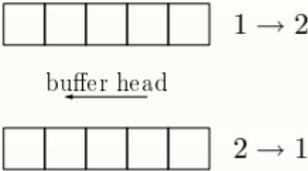
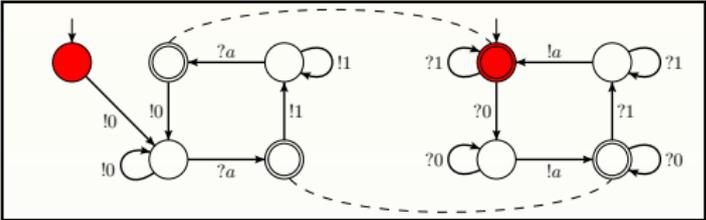
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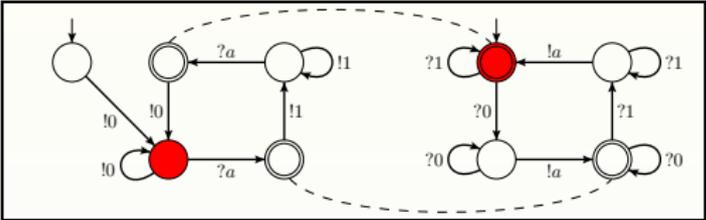
- a set of finite-state automata (*processes*) with
 - common global initial state
 - set of global final states
- communication between automata through (reliable) FIFO channels
 - $p!q(a)$ appends message a to buffer between p and q
 - $q?p(a)$ removes message a from buffer between p and q



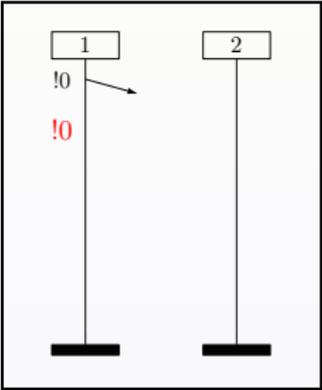
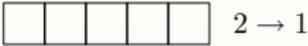
CFM: An Example



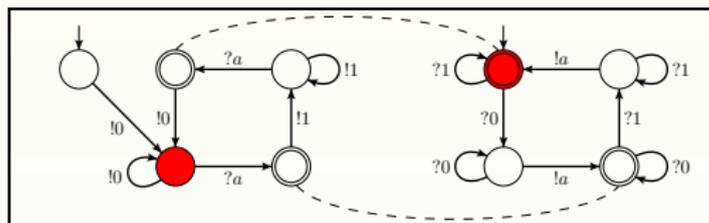
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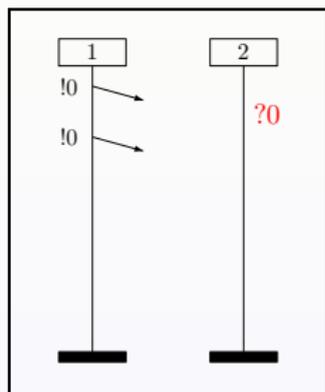
buffer head



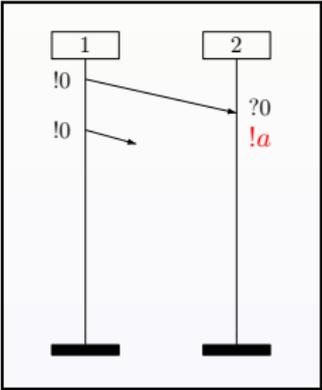
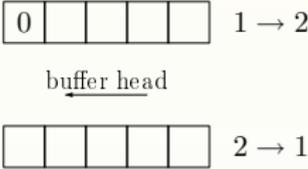
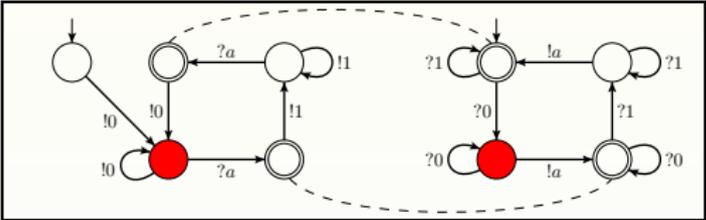
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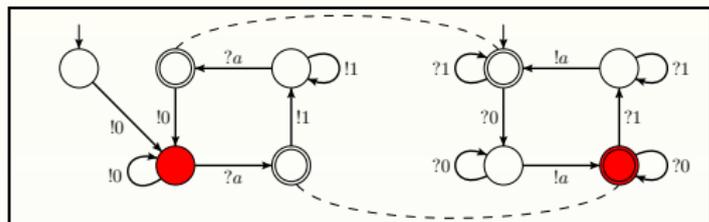
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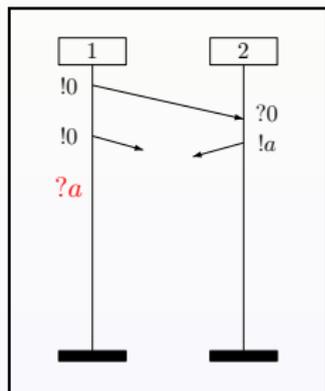
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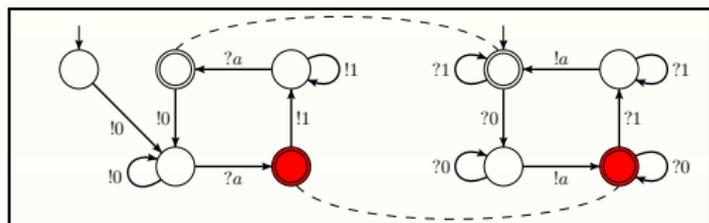
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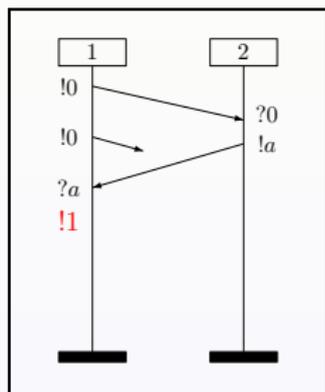
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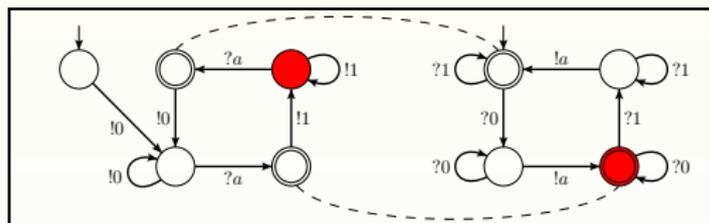
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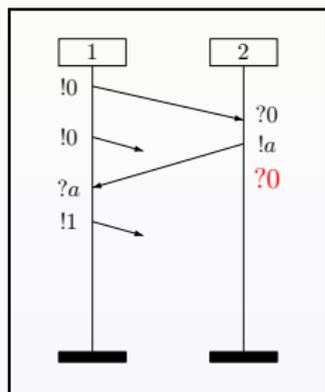
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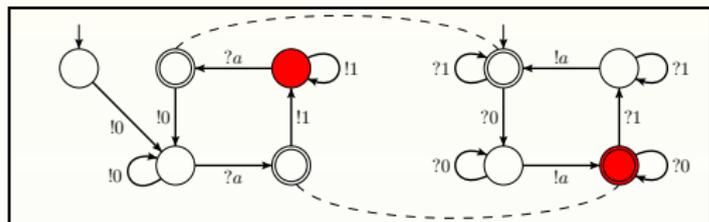
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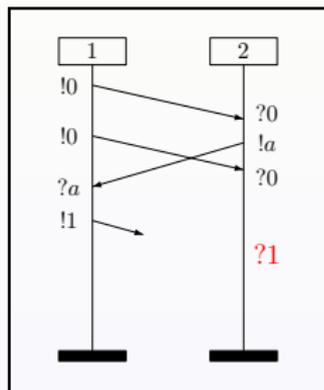
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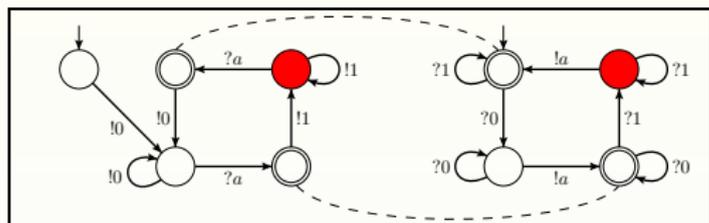
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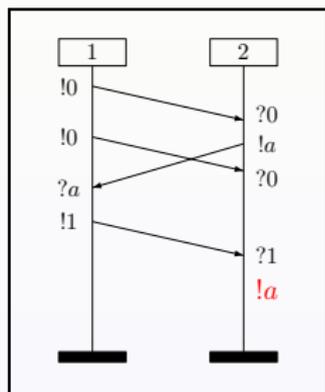
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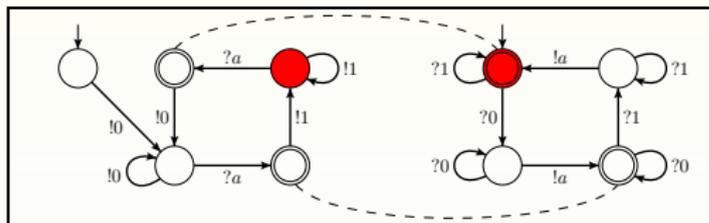
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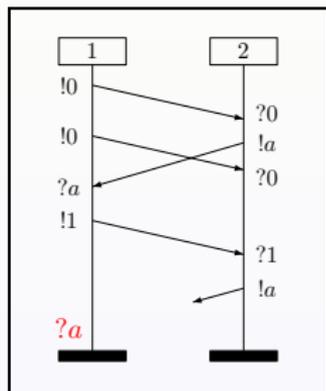
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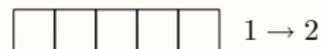
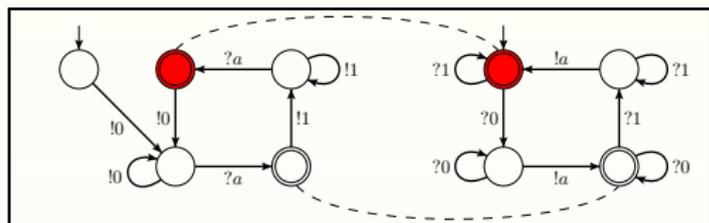
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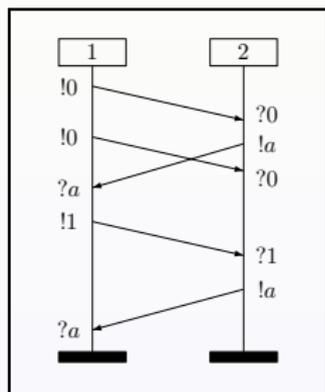
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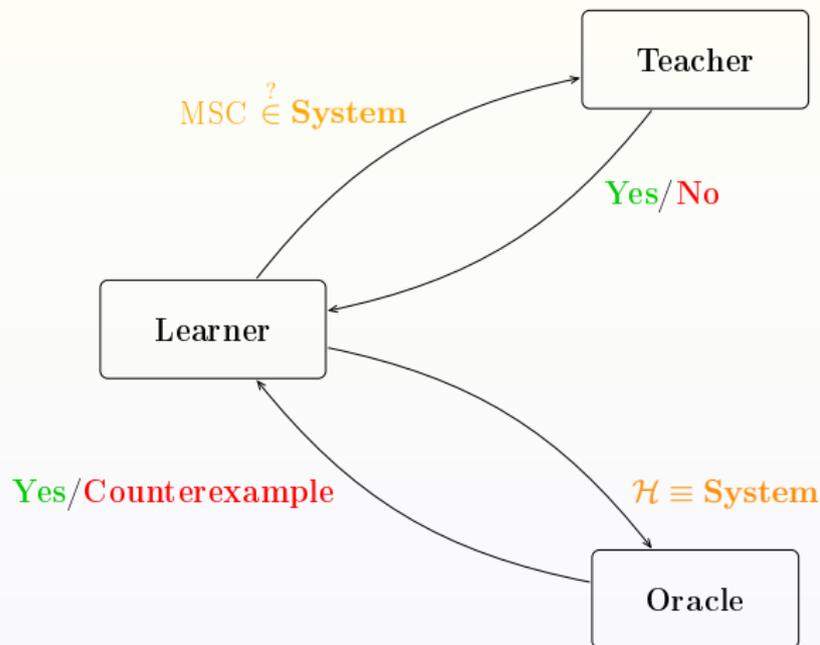
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Current State

- **given:** *learning DFA* [Angluin]
- **goal:** *learning CFMs*

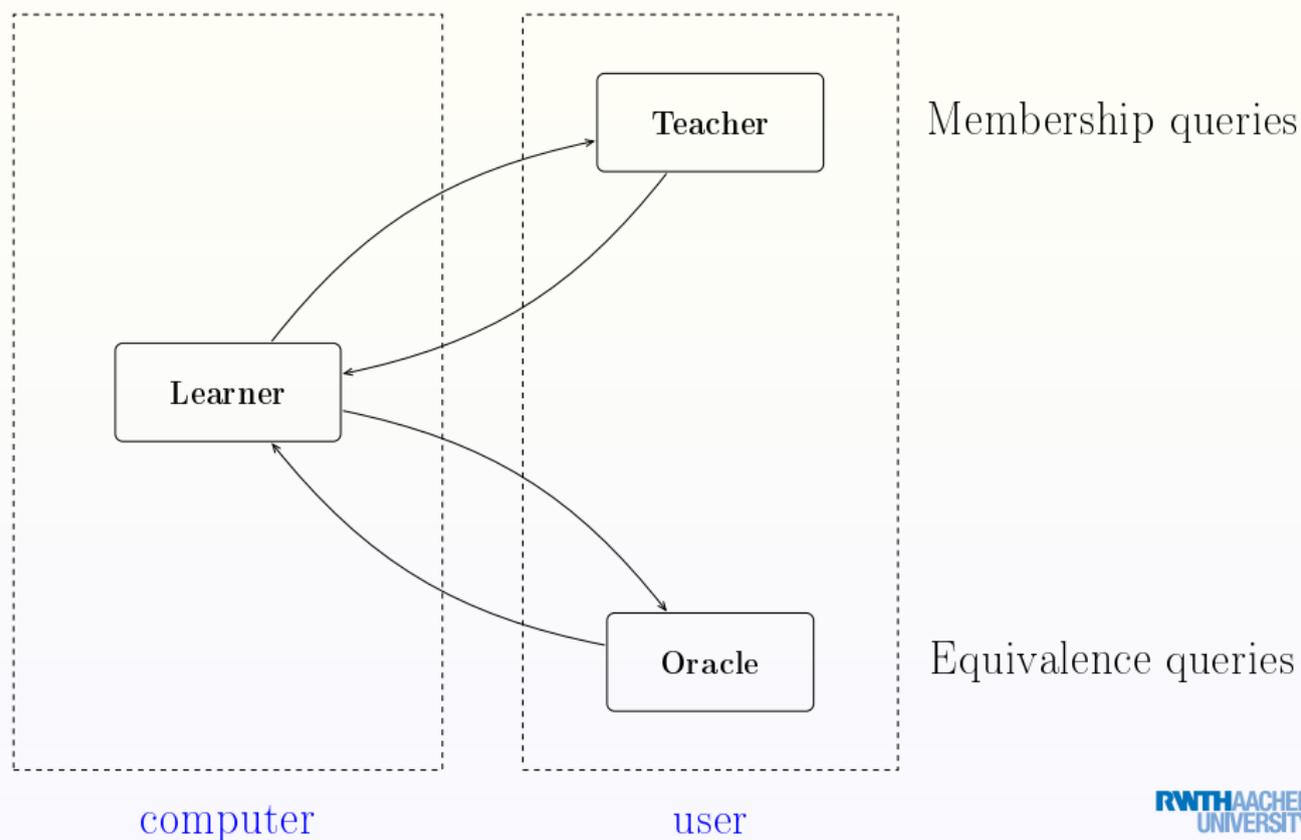
The learning algorithm (extension of Angluin's L^*)



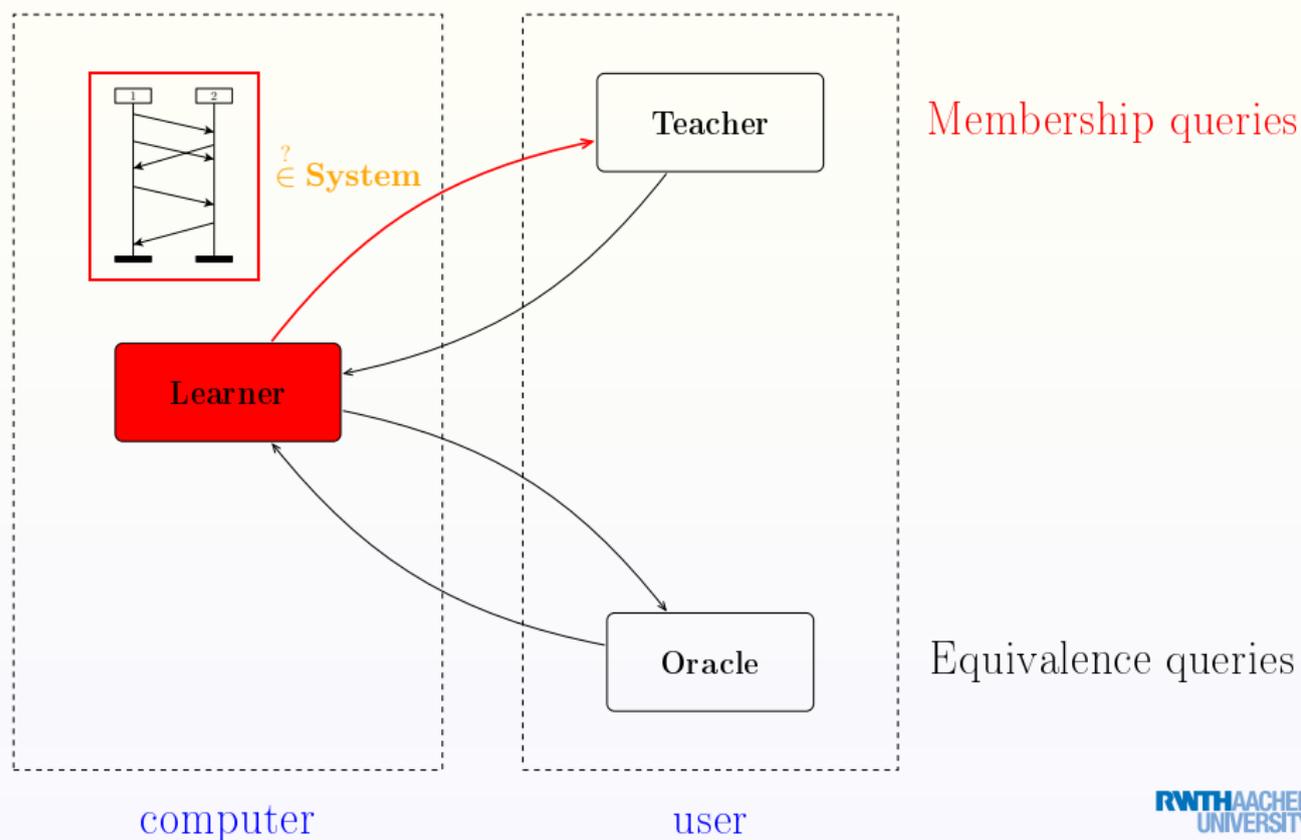
Membership queries

Equivalence queries

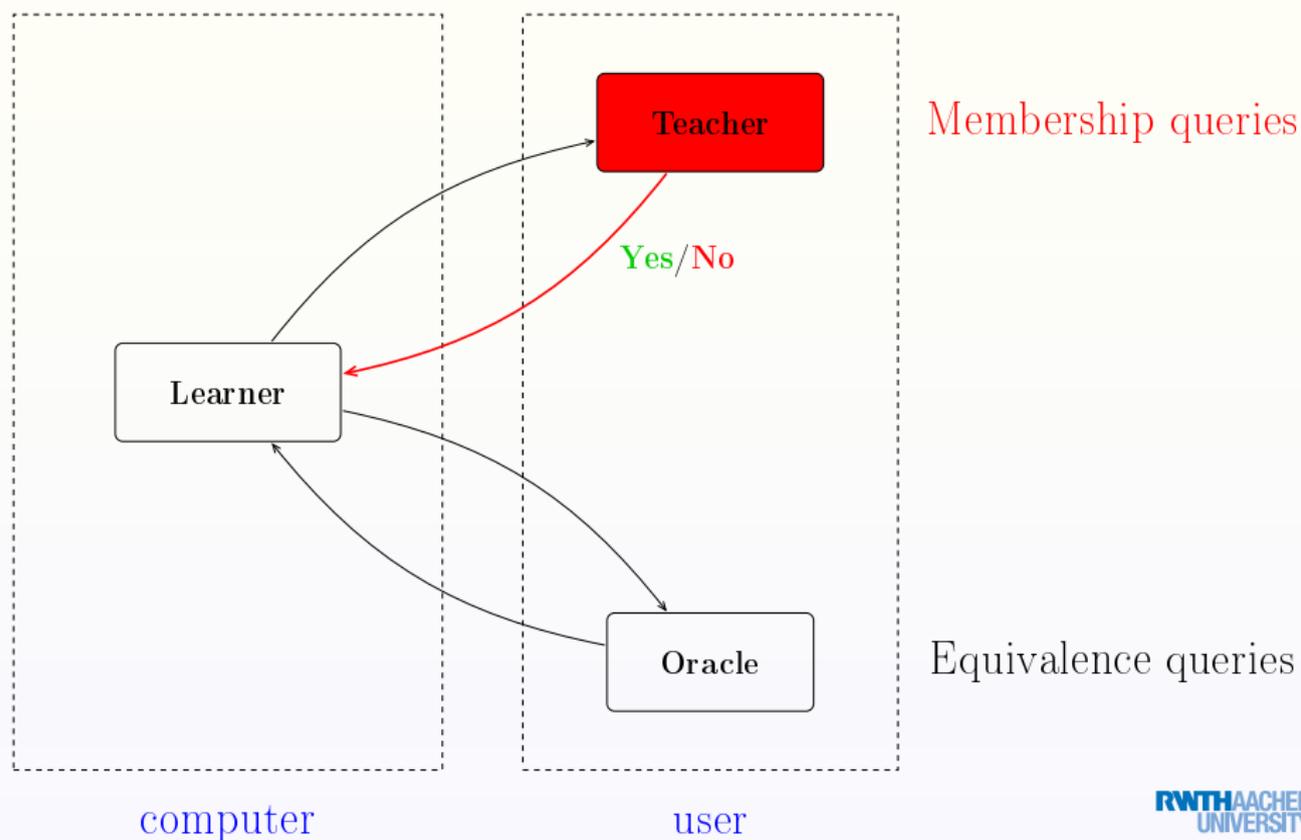
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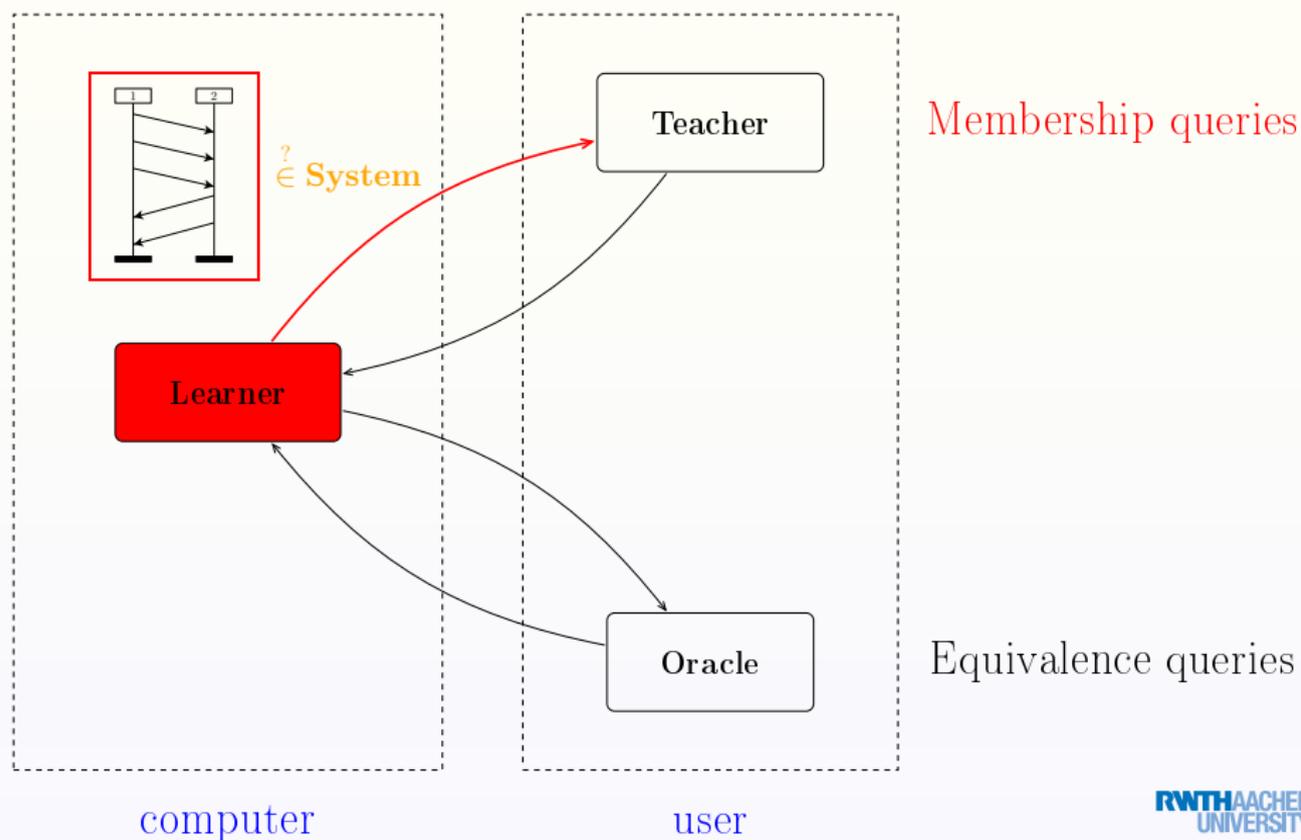
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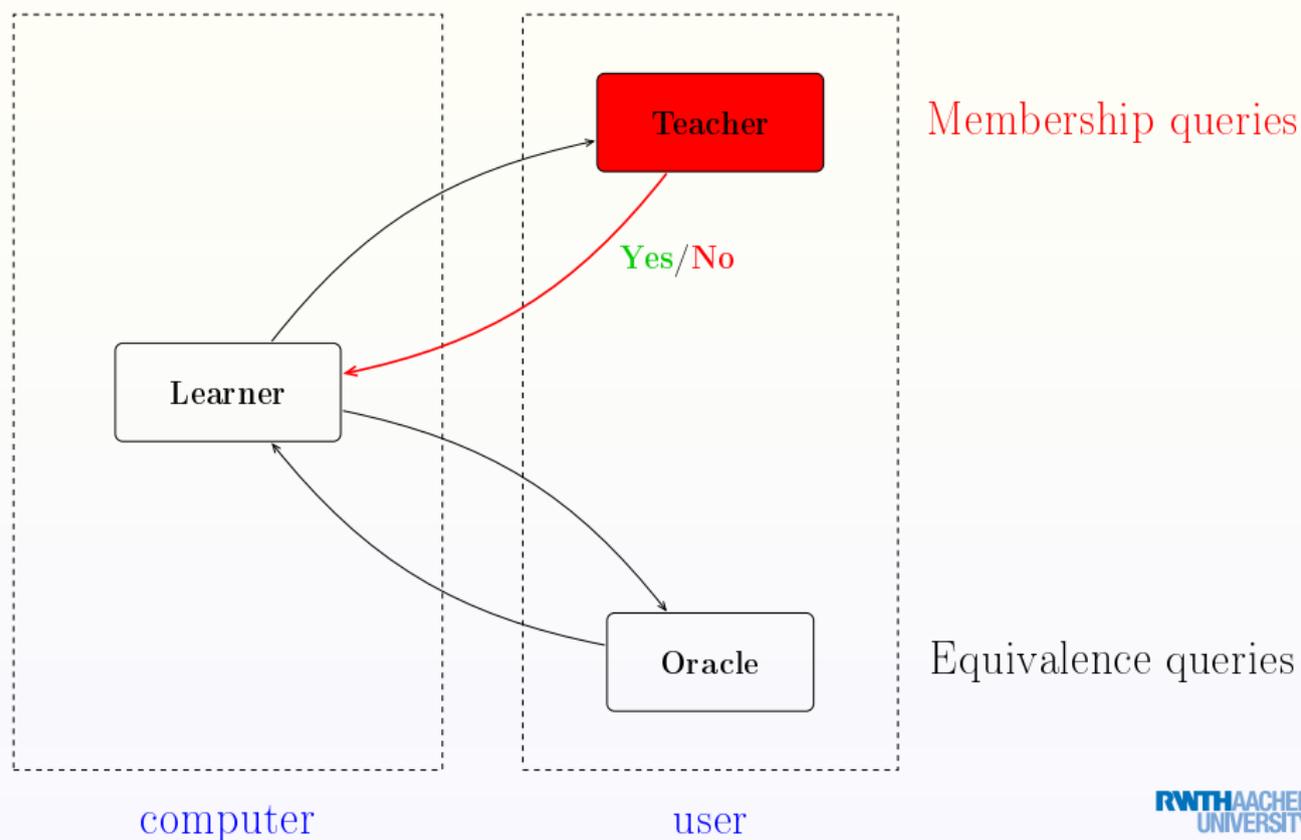
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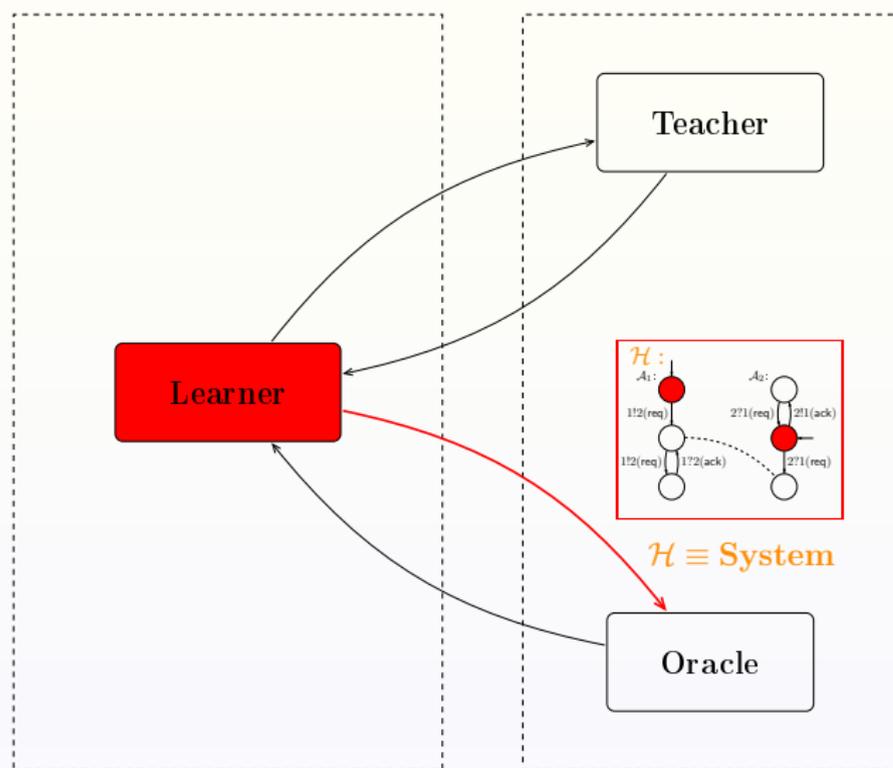
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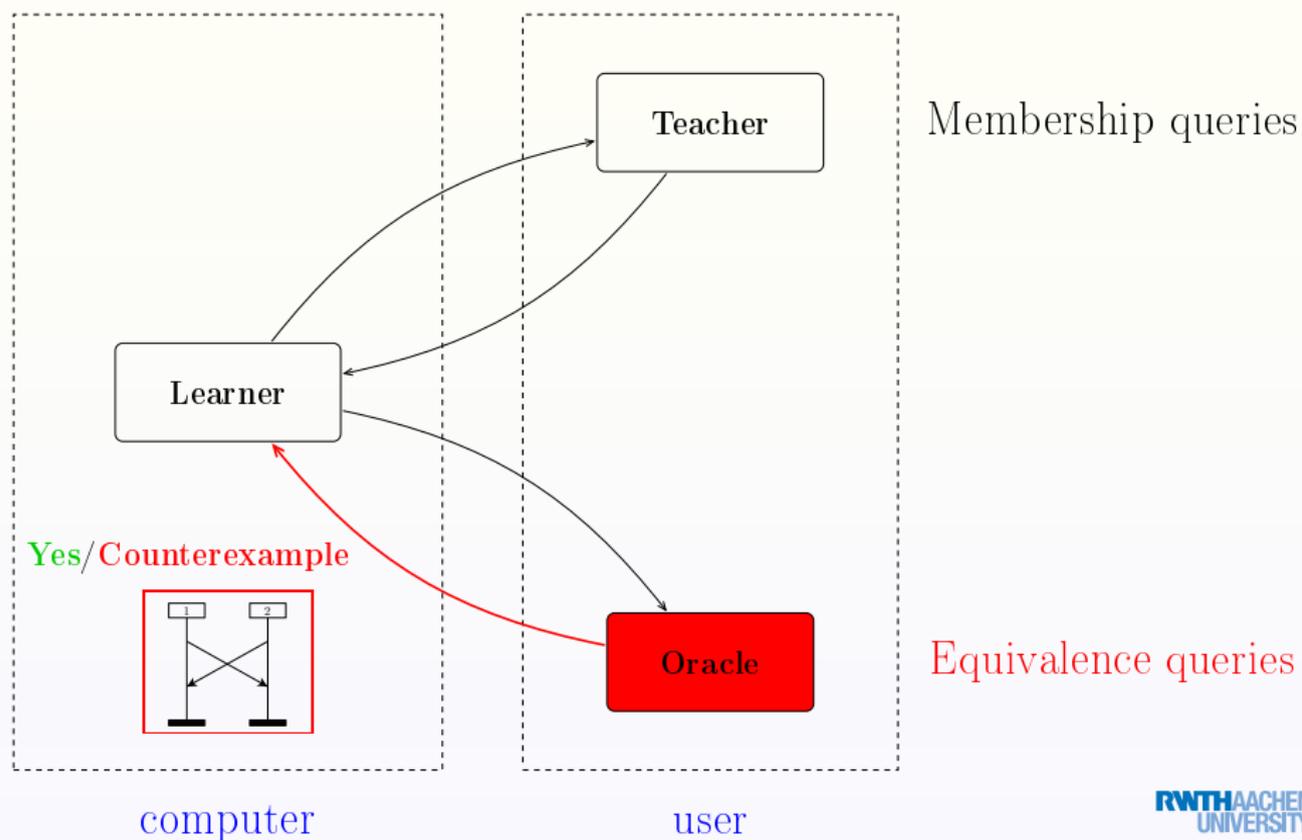
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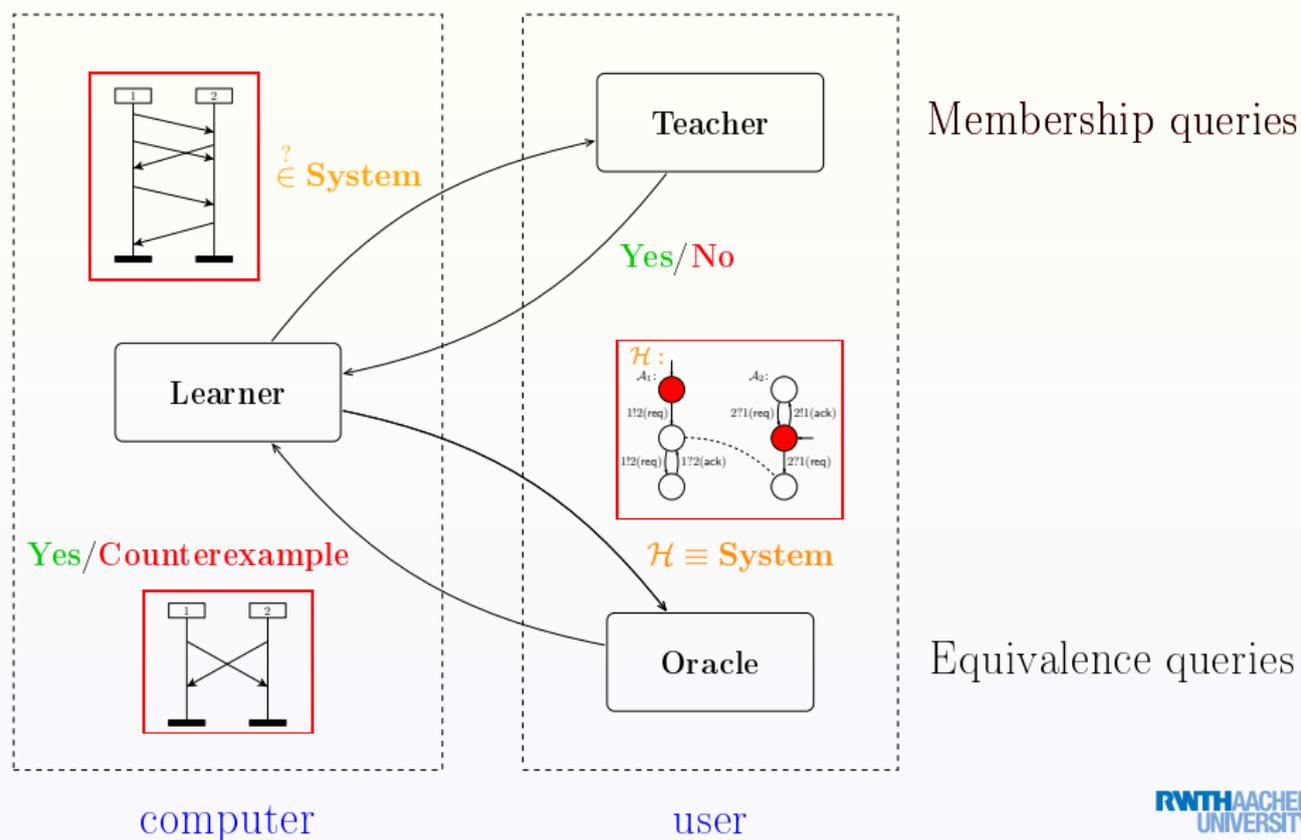
computer

user

The learning algorithm (extension of Angluin's L^*)



The learning algorithm (extension of Angluin's L^*)



Goal

- learning CFMs from examples (MSCs)

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- extending Angluin's algorithm
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 - **negative** scenarios must not be contained
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Problem

- **correspondence** between **CFMs** and **regular word languages** needed

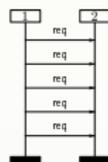
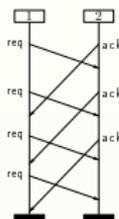
Classes of MSCs

M is $\forall B$ -bounded ($B \in \mathbb{N}$) if

all linearizations of M do not exceed buffer bound B

M is $\exists B$ -bounded ($B \in \mathbb{N}$) if

events of M can be scheduled s.t. B is not exceeded



Fix a learning setup

- \mathcal{D} domain over ($\forall/\exists B$ -bounded) MSC linearizations
- \approx : equivalence of ($\forall/\exists B$ -bounded) linearizations
- *synth* : Synthesis function from DFA to ($\forall/\exists - B$ -bounded) CFMs

From regular languages to CFM languages

User specification: final system should be, e.g.,...

- deterministic, \exists/\forall -bounded (i.e., fix domain \mathcal{D}), deadlockfree etc.

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 - compute $w \approx w'$: $w \in L(\mathcal{H})$, $w' \notin L(\mathcal{H})$ and
 - perform membership query for $MSC(w)$

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If \mathcal{H} satisfies $L(\mathcal{H}) \subseteq \mathcal{D}$ and $L(\mathcal{H})$ is \approx -closed

CFM (depending on user specification) can be derived using *synth.*

Results:

There are synthesis functions such that the following classes of CFMs are learnable:

Learnable classes of CFMs:

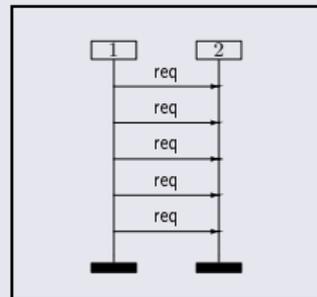
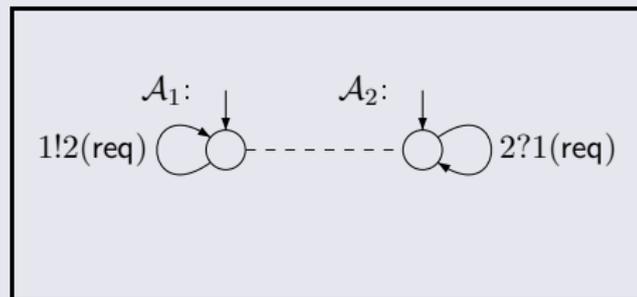
- (deterministic) \forall -bounded CFMs
- $\exists B$ -bounded CFMs ($B \in \mathbb{N}$)
- deterministic \forall -bounded deadlock-free weak CFMs

Not learnable (in a guided fashion)

- \forall -bounded weak CFMs

An *existentially B -bounded* CFM

- Example of an $\exists B$ -bounded CFM (bound $B = 1$)



- \mathcal{D} : domain for $\exists B$ -bounded words
- \approx : linearization equivalence for $\exists B$ -bounded MSCs
- *synth* : mapping a minimal DFA to a $\exists B$ -bounded CFMs

Algorithm for $\exists B$ -bounded CFMs

Let \mathcal{H} be a minimal DFA (hypothesis)

Problems $L(\mathcal{H}) \subseteq \mathcal{D}$ and $L(\mathcal{H})$ is \approx -closed are *constructively decidable*

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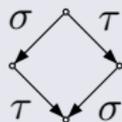
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- 2 check diamond rule



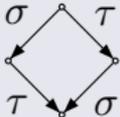
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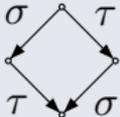
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 - **sending adds** a message to corresponding channel
 - **receiving removes** a message from channel head

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Complexity: linear in the size of \mathcal{H}

Number of equivalence queries:

- deterministic $\forall B$ -bounded CFMs: $(|\mathcal{A}| \cdot |Msg| + 1)^{B \cdot |Proc|^2 + |Proc|}$
- $\forall B$ -bounded CFMs: $2^{(|\mathcal{A}| \cdot |Msg| + 1)^{B \cdot |Proc|^2 + |Proc|}}$
- $\exists B$ -bounded CFMs: $2^{(|\mathcal{A}| \cdot |Msg| + 1)^{B \cdot |Proc|^2 + |Proc|}}$
- deterministic \forall -bounded deadlock-free weak CFMs:
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Some results

Protocol	# membership queries			#user queries	#equivalence queries	$ \mathcal{H} $	# rows in table			learning setup
	w.o. POL	w. POL	savings				w.o. POL	w. POL	reduction	
part of <i>USB 1.1</i>	488	200	59.0%	14	1 (5)	9	61	26	57.4%	$\exists 2$
<i>continuous update</i>	712	264	62.9%	21	1 (3)	8	89	34	61.8%	$\exists 1$
<i>negotiation</i>	1,179	432	63.4%	31	1 (3)	9	131	49	62.6%	$\exists 1$
<i>ABP</i>	2,286	697	69.5%	64	2 (4)	15	127	42	66.9%	$\exists 1$
<i>ABP</i>	14,432	4,557	68.4%	158	2 (13)	25	451	131	71.0%	$\exists 2$
<i>ABP</i>	55,131	19,252	65.1%	407	2 (22)	37	799	222	72.2%	$\exists 3$
<i>leader elec. (v₁)</i>	3,612	900	75.1%	43	1 (2)	13	301	76	74.8%	\forall
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- # membership queries: reduced by *partial order learning* (**POL**)
- # equivalence queries: reduced by our learning approach
- # user queries: reducible by employing a logic (**PDL**)

Similar Approaches

- *Play-In/Play-Out* approach [Harel et al.]
 - use the more expressive language of LSCs
 - more involved treatment of negative scenarios
 - problem: detecting inconsistencies
- *MAS (Minimally Adequate Synthesizer)* [Mäkinen et al.]
 - based on Angluin's learning approach
 - only synchronous/sequential behavior
 - implementation model is not distributed

Presentation outline

- 1 Learning Deterministic Automata
- 2 Learning Nondeterministic Automata
- 3 Learning Communicating Automata
- 4 Tools**
- 5 Conclusion

Features

- implements wide range of learning algorithms:
 L^* , L^*_{col} , NL^* , PO learning, Biermann, RPNI, DeLeTe2, etc.
- written in C++
- approx. 13,500 lines of code

Features

- implements $\forall/\exists - B/\dots$ learning setups
- written in Java 1.6
- implements partial order learning
- implements a logic (PDL) for reducing user queries
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- GRAPPA (visualization of automata)
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<http://www.smyle-tool.org>

Smile

The screenshot shows the Smyle software interface with the following components and callouts:

- 1**: Learning setup section, including "Type of abstraction to learn: EXISTENTIALLY_BOUNDED", "Learning Bound b = 1", "Always add all linearizations of a given NSC: true", and "Apply partial-order learning: true".
- 2**: A state transition graph on the right side of the window, showing nodes and transitions.
- 3**: A command line at the bottom containing the command: `digraph cp_graph { nodes {southreshold=100, inithreshold=100} 0 [fontsize=16]; 4 [fontsize=16]; 7 [fontsize=16]; 8 [fontsize=16]; 9->9 [label="cp[a]"]; 3->8 [label="cp[b]"]; 4->3 [label="cp[a]"]; 10->9 [label="cp[b]"]; 5->4 [label="pk[b]"]; }`
- 4**: A diagram showing a sequence of nodes (p, c) with transitions labeled a, b, c, d, e, f, g, h, i, j, k, l, m, n, o, p, q, r, s, t, u, v, w, x, y, z.
- 5**: A dialog box titled "PDL Filter confirms action of fact matching f" with a table showing "Action" as "Add=Success" and "Formula" as "true".

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Results achieved:

- first active online learning algorithm for NFA: NL*
- several classes of CFMs learnable by an extension to L*
- optimizations of learning algorithms (POL, PDL, etc.)
- tools supporting the theory
- ...

Open problems:

- applying NL^* in fields like verification, robotics, etc.
- detect further learnable classes of CFMs
- learn other classes of automata (Büchi automata, alternating automata)
- ...

List of Publications

- (1) *MSCan: A tool for analyzing MSC specifications.*
Bollig, Kern, Schlütter, Stolz. (TACAS 2006), LNCS.
- (2) *Replaying play in and play out: Synthesis of design models from scenarios by learning.*
Bollig, Katoen, Kern, Leucker. (TACAS 2007), LNCS.
- (3) *Smyle: A Tool for Synthesizing Distributed Models from Scenarios by Learning.*
Bollig, Katoen, Kern, Leucker. (CONCUR 2008), LNCS.
- (4) *SMA—The Smyle Modeling Approach.*
Bollig, Katoen, Kern, Leucker. (CEE-SET 2008 (IFIP)), LNCS.
- (5) *Angluin-Style Learning of NFA.*
Bollig, Habermehl, Kern, Leucker. (IJCAI 2009).
- (6) *SMA—The Smyle Modeling Approach.*
Bollig, Katoen, Kern, and Leucker. (Computing and Informatics, to appear).
- (7) *Learning Communicating Automata from MSCs.*
Bollig, Katoen, Kern, Leucker. (Submitted to IEEE TSE).

▶ RFSA-closedness and -consistency

▶ NL* in action

Designing a table-based learning algorithm

Definition (RFSA-Closedness)

Table $\mathcal{T} = (T, U, V)$ is called **RFSA-closed** if, for each $r \in Rows_{low}(\mathcal{T})$,

$$r = \bigsqcup \{r' \in Primes_{upp}(\mathcal{T}) \mid r' \sqsubseteq r\}$$

\mathcal{T}	ε	a	aa
ε	-	-	+
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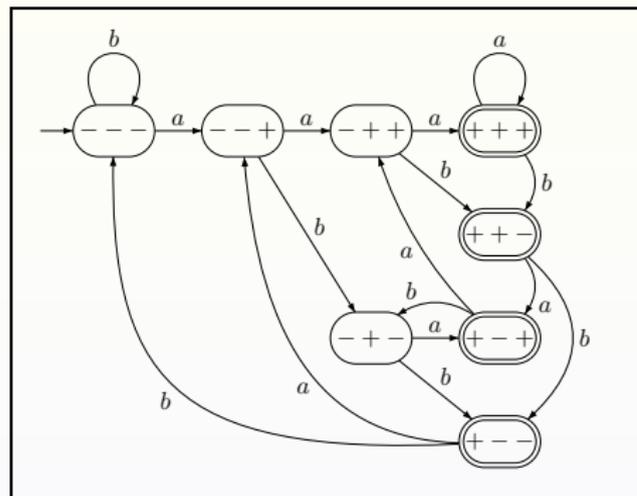
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 - $\text{row}(a) \sqsubseteq \text{row}(aba)$ and
 - $\text{row}(b) \sqsubseteq \text{row}(abb)$

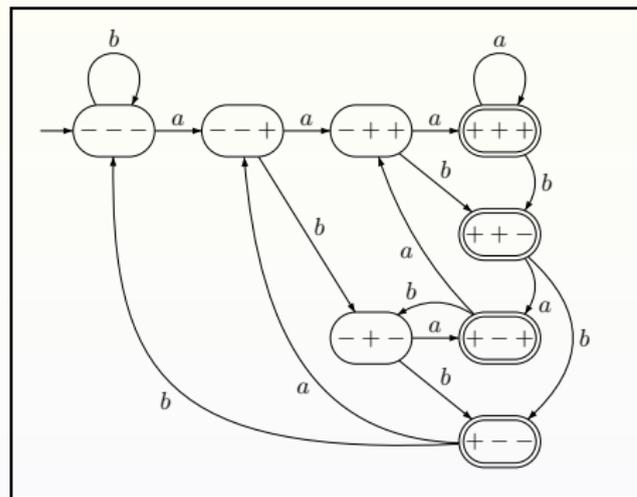
The algorithm in action



Create initial table \mathcal{T}_1 .

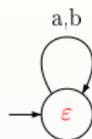
\mathcal{T}_1	ϵ
* ϵ	-
* a	-
* b	-

The algorithm in action



\mathcal{T}_1	ϵ
* ϵ	-
* a	-
* b	-

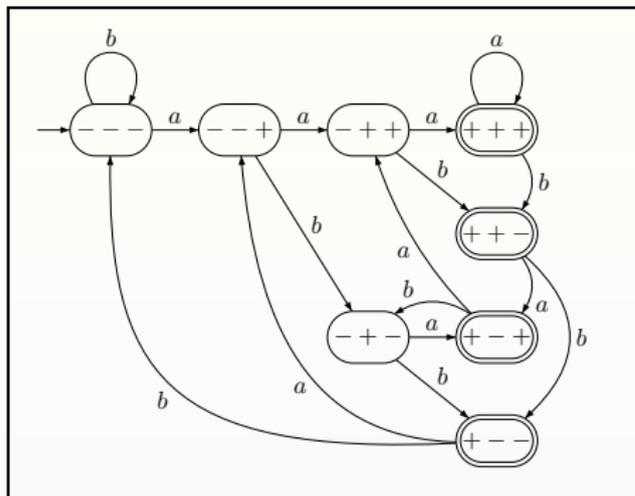
Hypothesis $\mathcal{R}_{\mathcal{T}_1}$:



\Rightarrow Counterexample is aaa .

\Rightarrow Add $Suff(aaa)$ to V .

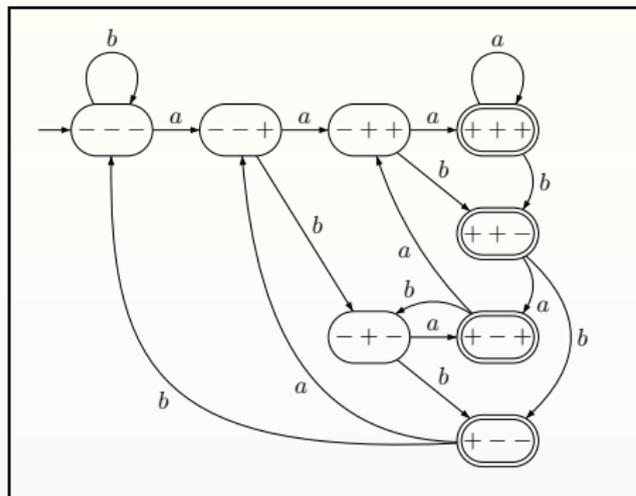
The algorithm in action



	T_1	ϵ
*	ϵ	-
*	a	-
*	b	-

	T_2	ϵ	aaa	aa	a
*	ϵ	-	+	-	-
*	a	-	+	+	-
*	b	-	+	-	-

The algorithm in action

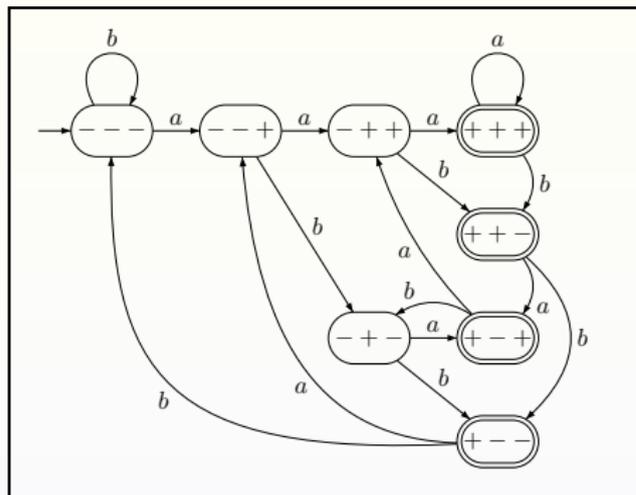


\mathcal{T}_2 is not closed:
 $row(a) \notin Primes_{\text{upp}}$

\mathcal{T}_1	ϵ
*	-
*	a
*	b

\mathcal{T}_2	ϵ	aaa	aa	a
*	-	+	-	-
*	a	-	+	-
*	b	-	+	-

The algorithm in action

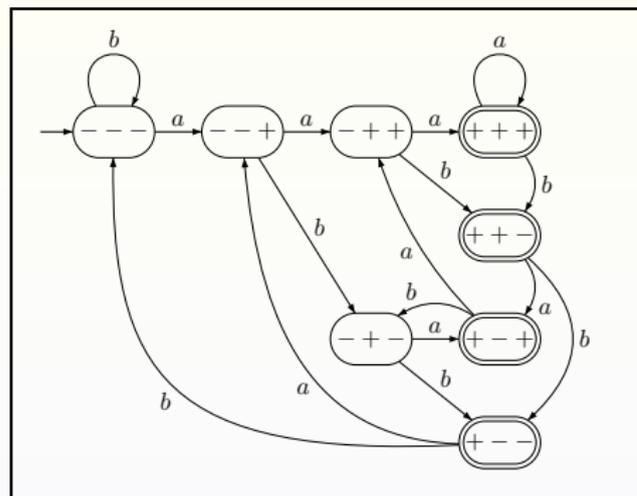


	T_1	ϵ
*	ϵ	-
*	a	-
*	b	-

	T_2	ϵ	aaa	aa	a
*	ϵ	-	+	-	-
*	a	-	+	+	-
*	b	-	+	-	-

	T_3	ϵ	aaa	aa	a
*	ϵ	-	+	-	-
*	a	-	+	+	-
*	b	-	+	-	-
*	aa	-	+	+	+
*	ab	-	+	-	+

The algorithm in action



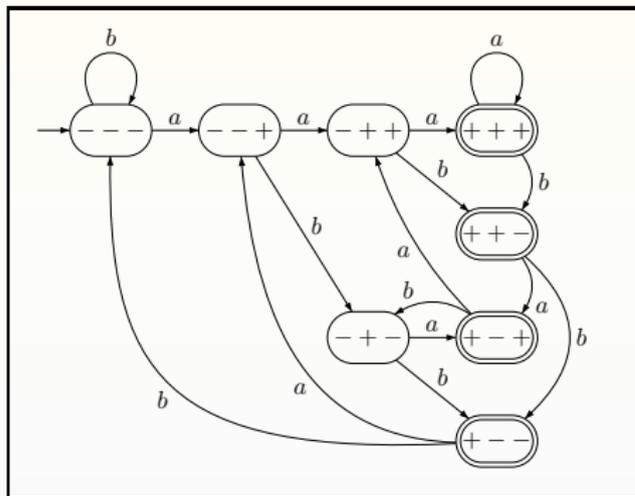
\mathcal{T}_3 is not closed:
 $\text{row}(ab) \notin \text{Primes}_{\text{upp}}$

\mathcal{T}_1	ϵ
*	ϵ -
*	a -
*	b -

\mathcal{T}_2	ϵ	aaa	aa	a
*	ϵ -	+	-	-
*	a -	+	+	-
*	b -	+	-	-

\mathcal{T}_3	ϵ	aaa	aa	a
*	ϵ -	+	-	-
*	a -	+	+	-
*	b -	-	+	-
*	aa -	+	+	+
*	ab -	-	+	-

The algorithm in action



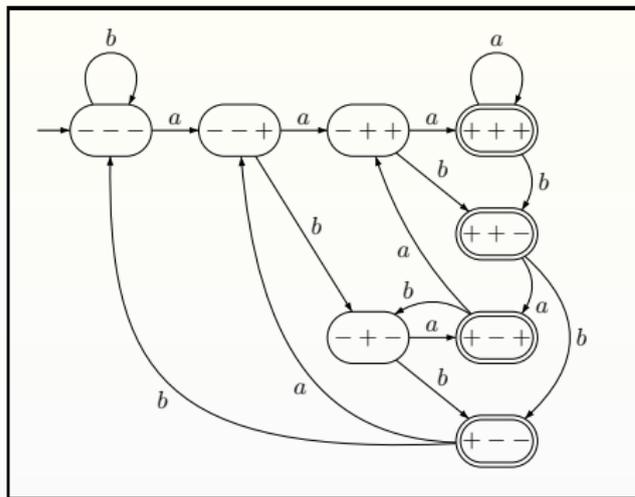
\mathcal{T}_1	ϵ
* ϵ	-
* a	-
* b	-

\mathcal{T}_2	ϵ	aaa	aa	a
* ϵ	-	+	-	-
* a	-	+	+	-
* b	-	+	-	-

\mathcal{T}_3	ϵ	aaa	aa	a
* ϵ	-	+	-	-
* a	-	+	+	-
* b	-	+	-	-
aa	-	+	+	+
* ab	-	+	-	+

\mathcal{T}_4	ϵ	aaa	aa	a
* ϵ	-	+	-	-
* a	-	+	+	-
* ab	-	+	-	+
* b	-	+	-	-
aa	-	+	+	+
aba	+	+	+	-
* abb	+	+	-	-

The algorithm in action



\mathcal{T}_4 is not closed:
 $row(abb) \notin Primes_{\text{upp}}$

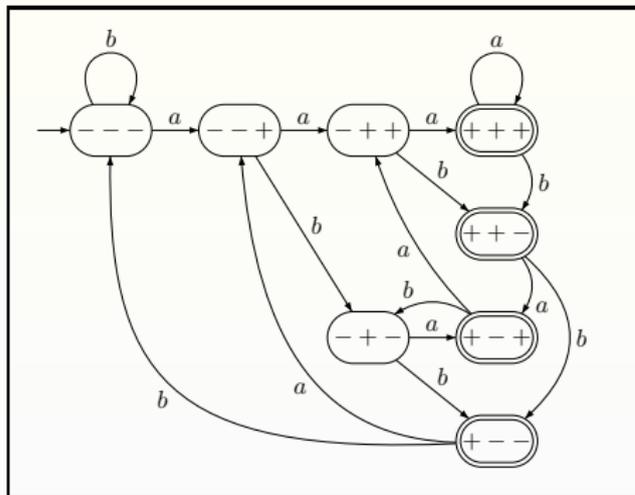
\mathcal{T}_1	ϵ
*	ϵ -
*	a -
*	b -

\mathcal{T}_2	ϵ	aaa	aa	a
*	ϵ -	+	-	-
*	a -	+	+	-
*	b -	+	-	-

\mathcal{T}_3	ϵ	aaa	aa	a
*	ϵ -	+	-	-
*	a -	+	+	-
*	b -	+	-	-
	aa -	+	+	+
*	ab -	+	-	+

\mathcal{T}_4	ϵ	aaa	aa	a
*	ϵ -	+	-	-
*	a -	+	+	-
*	ab -	+	-	+
*	b -	-	+	-
	aa -	+	+	+
	aba +	+	+	-
*	abb +	+	-	-

The algorithm in action



T_1	ϵ
*	ϵ -
*	a -
*	b -

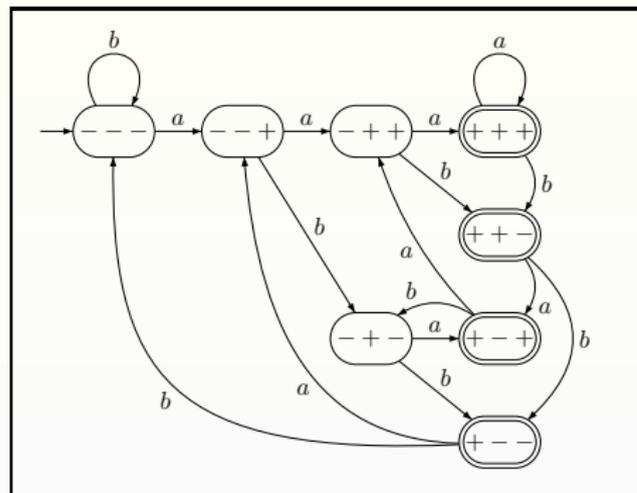
T_2	ϵ	aaa	aa	a
*	ϵ -	-	-	-
*	a -	-	+	-
*	b -	-	+	-

T_3	ϵ	aaa	aa	a
*	ϵ -	-	+	-
*	a -	-	+	-
*	b -	-	+	-
*	aa -	-	+	+
*	ab -	-	+	+

T_4	ϵ	aaa	aa	a
*	ϵ -	-	+	-
*	a -	-	+	-
*	ab -	-	+	-
*	b -	-	+	-
*	aa -	-	+	+
*	aba -	-	+	+
*	abb -	-	+	+

T_5	ϵ	aaa	aa	a
*	ϵ -	-	+	-
*	a -	-	+	-
*	ab -	-	+	-
*	abb -	-	+	-
*	b -	-	+	-
*	aa -	-	+	+
*	aba -	-	+	+
*	abba -	-	+	+
*	abbb -	-	+	+

The algorithm in action



\mathcal{T}_5 is closed and consistent:
 $\Rightarrow \mathcal{R}_{\mathcal{T}_5}$ can be derived.

	\mathcal{T}_1	ϵ
*	ϵ	-
*	a	-
*	b	-

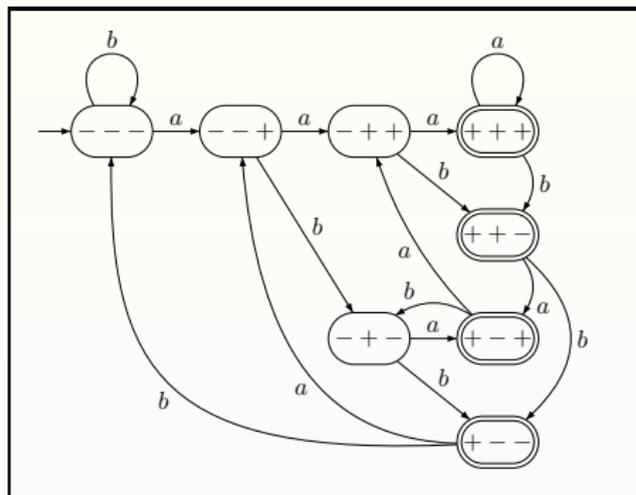
	\mathcal{T}_2	ϵ	aaa	aa	a
*	ϵ	-	+	-	-
*	a	-	+	+	-
*	b	-	+	-	-

	\mathcal{T}_3	ϵ	aaa	aa	a
*	ϵ	-	+	-	-
*	a	-	+	+	-
*	b	-	+	-	-
*	aa	-	+	+	+
*	ab	-	+	-	+

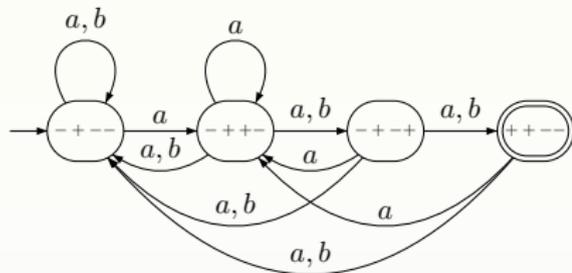
	\mathcal{T}_4	ϵ	aaa	aa	a
*	ϵ	-	+	-	-
*	a	-	+	+	-
*	ab	-	+	-	+
*	b	-	+	-	-
*	aa	-	+	+	+
*	aba	+	+	+	-
*	abb	+	+	-	-

	\mathcal{T}_5	ϵ	aaa	aa	a
*	ϵ	-	+	-	-
*	a	-	+	+	-
*	ab	-	+	-	+
*	abb	+	+	-	-
*	b	-	+	-	-
*	aa	-	+	+	+
*	aba	+	+	+	-
*	abba	-	+	+	-
*	abbb	-	+	-	-

The algorithm in action



\mathcal{T}_5 is closed and consistent:
 $\Rightarrow \mathcal{R}_{\mathcal{T}_5}$ can be derived.



\mathcal{T}_1	ϵ
*	ϵ
*	a
*	b

\mathcal{T}_2	ϵ	aaa	aa	a
*	ϵ	-	+	-
*	a	-	+	-
*	b	-	+	-

\mathcal{T}_3	ϵ	aaa	aa	a
*	ϵ	-	+	-
*	a	-	+	-
*	ab	-	+	-
*	b	-	+	-
	aa	-	+	+
	aba	+	+	+
	abb	+	+	-

\mathcal{T}_4	ϵ	aaa	aa	a
*	ϵ	-	+	-
*	a	-	+	-
*	ab	-	+	-
*	b	-	+	-
	aa	-	+	+
	aba	+	+	+
	abb	+	+	-

\mathcal{T}_5	ϵ	aaa	aa	a
*	ϵ	-	+	-
*	a	-	+	-
*	ab	-	+	-
*	abb	+	+	-
*	b	-	+	-
	aa	-	+	+
	aba	+	+	+
	abba	-	+	+
	abbb	-	+	+