

Principles of Model Checking

Solutions to exercise class 6

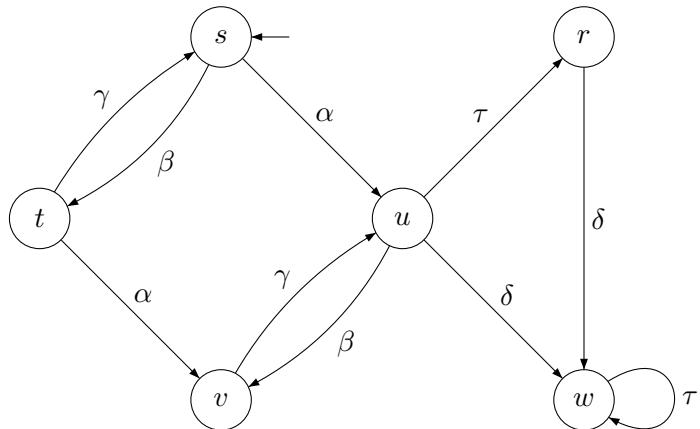
Partial Order Reduction

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Problem 1

Consider the transition system TS below, with action set $Act = \{\alpha, \beta, \gamma, \delta, \tau\}$. Determine the pairs of independent actions.



Solution:

Recall that actions α_1 and α_2 are independent if for any $s \in S$ with $\alpha_1, \alpha_2 \in Act(s)$ it holds that

$$\alpha_1 \in Act(\alpha_2(s)) \quad \wedge \quad \alpha_2 \in Act(\alpha_1(s)) \quad \wedge \quad \alpha_1(\alpha_2(s)) = \alpha_2(\alpha_1(s)).$$

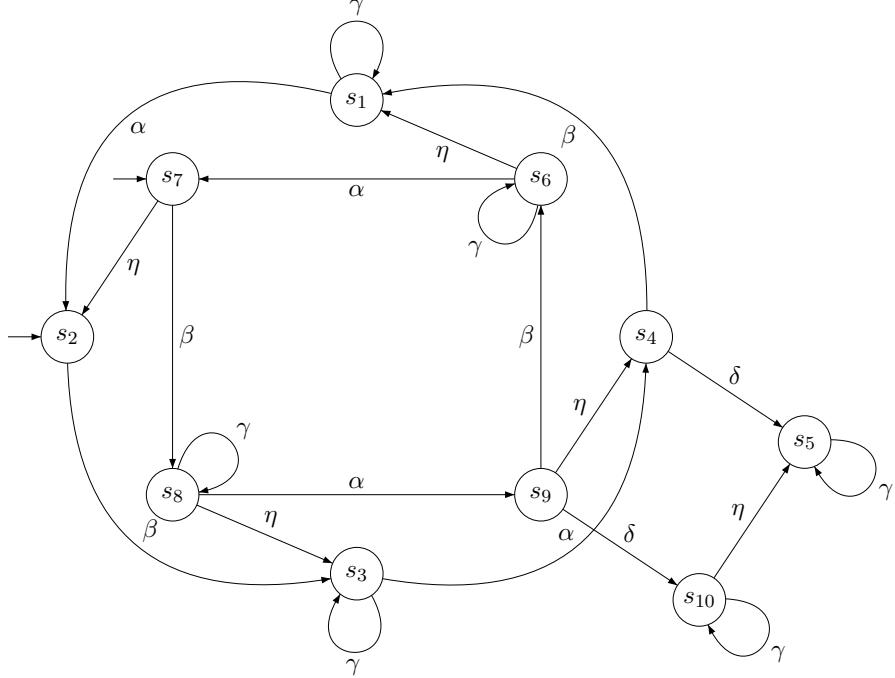
Note that if α_1 and α_2 are never enabled in the same state, it is obvious that they are independent (indicated below by $+$ *).

action pair	$\alpha\beta$	$\alpha\gamma$	$\alpha\delta$	$\alpha\tau$	$\beta\gamma$	$\beta\delta$	$\beta\tau$	$\gamma\delta$	$\gamma\tau$	$\delta\tau$
independent	+	+	+	*	+	*	-	-	+	*

The reason for the two minuses can be explored in state u .

Problem 2

Consider the transition system below:



The states labeling is as follows:

- $L(s_{10}) = \emptyset$
- $L(s_6) = L(s_7) = \{a\}$
- $L(s_3) = L(s_4) = L(s_5) = L(s_8) = L(s_9) = \{b\}$
- $L(s_1) = L(s_2) = \{a, b\}$

Prove or disprove that each of the following *ample sets* satisfy requirements *A1* through *A3*. Also check whether the requirement *A4* holds.

- $ample(s_6) = \{\alpha, \gamma\}$
- $ample(s_7) = \{\beta\}$
- $ample(s_8) = \{\alpha\}$
- $ample(s_9) = \{\alpha, \beta, \delta\}$
- $ample(s_{10}) = \{\gamma, \eta\}$

In case some of the conditions *A1* through *A4* do not hold, modify the *ample sets* in an appropriate way to fix it. Clarify your changes.

Solution:

- Let us first indicate dependent and independent actions which we might need:
 - Action η is independent of $\alpha, \beta, \gamma, \delta$.
 - Action α and γ are dependent, and so are δ and β .

- Now let's indicate the stutter actions:
 - Clearly α, γ are stutter actions.

- Considering all given *ample sets*, and the condition (A4), we realize that for the cycle s_6, s_7, s_8, s_9, s_6 , $\eta \in Act(s_6)$, but $\eta \notin ample(s_6) \cup ample(s_7) \cup ample(s_8) \cup ample(s_9)$. Thus, condition (A4) is violated. In order to fix it we have to add η for example to *ample*(s_7). Later, we will see that η has to be added to *ample*(s_7) anyway.

On the cycle s_2, s_3, s_4, s_1, s_2 all states are fully-expanded, so they clearly satisfy the cycle condition.

- Consider each of the given *ample sets* (+ stands for satisfied, – for not satisfied):
 - $ample(s_6) = \{\alpha, \gamma\}$:
 - (A1) +: $ample(s_6) \neq \emptyset$.
 - (A2) +: All paths starting from s_6 either start with an ample action α, γ , or with η . Since η is independent of both α and γ , this is fine. After η , either γ or α is observed. Hence, every path from s_6 at some point reaches an ample action while beforehand only containing actions independent of *ample*(s_6).
 - (A3) +: as α and γ are stutter actions, (A3) clearly holds.
 - $ample(s_7) = \{\beta\}$:
 - (A1) +: $ample(s_7) \neq \emptyset$.
 - (A2) +: All paths from s_7 start by either β or $\eta\beta$. Since β is in the ample set, and η is independent of β , (A2) is satisfied.
 - (A3) –: $ample(s_7) \neq Act(s_7)$ and β is not a stutter action, so we should have $ample(s_7) = \{\beta, \eta\}$.

- $ample(s_8) = \{\alpha\}$:
 - (A1) +: $ample(s_8) \neq \emptyset$.
 - (A2) -: For the execution $s_8 \xrightarrow{\gamma} s_8$ we find that $ample(s_8)$ and γ are dependent, so we have to have $ample(s_8) = \{\alpha, \gamma\}$. Then, (A2) indeed holds, as all paths starting from s_8 either start with ample action γ or α , or by $\eta\alpha$ (which is also fine since η is independent of $ample(s_8)$ and α is an ample action).
 - (A3) +: as α is a stutter action (for $ample(s_8) = \{\alpha, \gamma\}$ the condition holds as well, since γ is also a stutter action).

- $ample(s_9) = \{\alpha, \beta, \delta\}$:
 - (A1) -: $ample(s_9) \neq \emptyset$ but $ample(s_9) \setminus Act(s_9) = \{\alpha\}$, thus it should be $ample(s_9) = \{\beta, \delta\}$.
 - (A2) +: All paths starting from s_9 begin with an ample action, or with the independent action η followed by an ample action.
 - (A3) -: As $ample(s_9) \neq Act(s_9)$ and β, δ are not stutter actions, (A3) is violated. Thus to fix it, we are obliged to set $ample(s_9) = \{\beta, \delta, \eta\}$, note that (A1), (A2), (A3) then hold, because $ample(s_9) = Act(s_9)$.

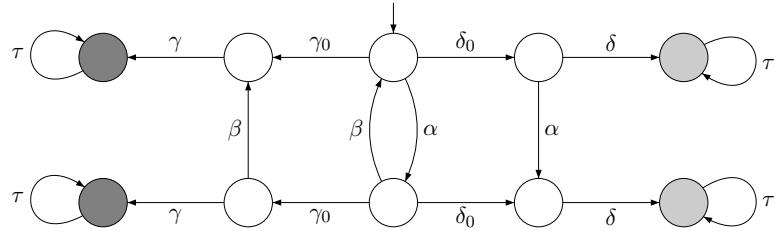
- $ample(s_{10}) = \{\gamma, \eta\}$:
 - (A1) +: $ample(s_{10}) \neq \emptyset$.
 - (A2) +: $ample(s_{10}) = Act(s_{10})$.
 - (A3) +: $ample(s_{10}) = Act(s_{10})$.

Note that we can not have $ample(s_{10}) = \{\gamma\}$, because it will violate (A4).

- After fixing all the problems with the given *ample sets* we have:
 - $ample(s_6) = \{\alpha, \gamma\}$
 - $ample(s_7) = \{\beta, \eta\}$
 - $ample(s_8) = \{\alpha, \gamma\}$
 - $ample(s_9) = \{\beta, \delta, \eta\}$
 - $ample(s_{10}) = \{\gamma, \eta\}$

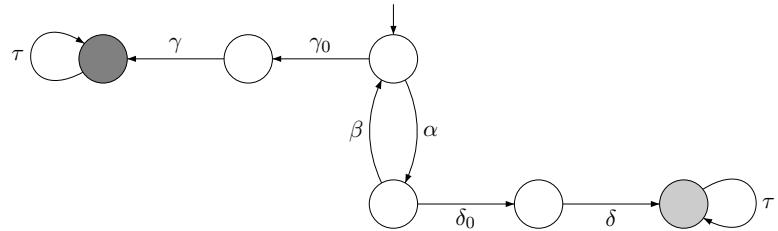
Problem 3

Consider the transition system TS shown in the following figure. Show that the ample set conditions (A1)-(A4) do not allow for any state reduction, although there is a smaller subsystem \widehat{TS} that is stutter-trace equivalent to TS .



Solution:

The reduced system shown in the following picture is easily seen to be stutter-trace equivalent to TS :



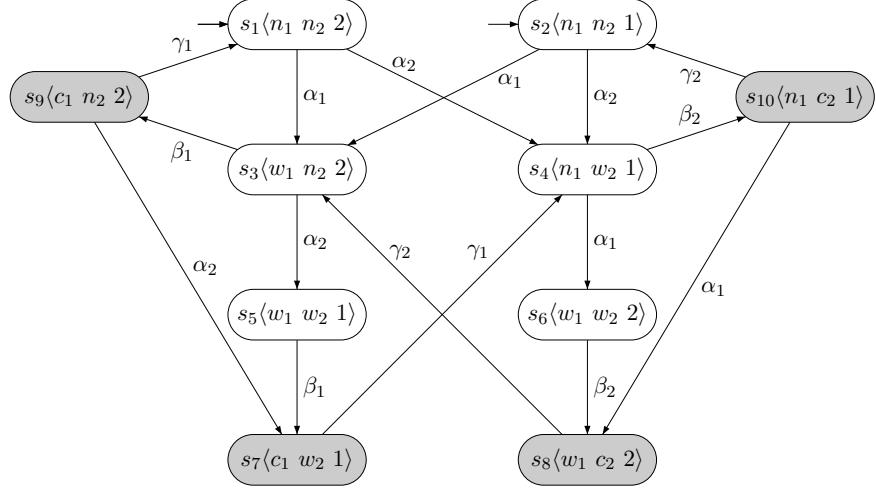
Conditions (A1)-(A4) do not allow for any state reduction, though, since the following pairs of actions are dependent:

$$(\alpha, \gamma_0), (\beta, \delta_0), (\gamma_0, \delta_0), (\gamma, \beta), (\alpha, \delta).$$

Thus, the initial state s_0 has to be fully expanded by the dependency condition (A2). The same argument applies to $\alpha(s_0)$ which has to be fully expanded too. Since β and γ are dependent, the γ_0 -successor of $\alpha(s_0)$ has to be fully expanded. The same holds for the δ_0 -successor of s_0 , since α and δ are dependent. The nonemptiness condition (A1) then yields that all states are fully expanded.

Problem 4

Consider the transition system TS_{Pet} below, which is for the Peterson mutual exclusion algorithm.



Questions:

- (a) Which actions are independent?
- (b) Apply the partial order reduction approach to get a reduced system equivalent to TS_{Pet} .

Solution:

- (a) In state s_1 and s_2 it can be seen that α_1 and α_2 are dependent. It is easy to verify that in no other state any dependent actions occur, so except for (α_1, α_2) all action pairs are independent.
- (b) In s_1 and s_2 no reduction is possible, since α_1 and α_2 are dependent. In s_3 it is not possible to take $ample(s_3) = \{\beta_1\}$ since β_1 is not a stutter action, and it is also not possible to take $ample(s_3) = \{\alpha_2\}$ since in that case there would be a path $s_3 \xrightarrow{\beta_1} s_9 \xrightarrow{\gamma_1} s_1 \xrightarrow{\alpha_1} s_3$ violating (A2), since α_1 depends on α_2 . Hence, also s_3 should be fully expanded. For s_4, s_9 and s_{10} similar arguments can be made. In s_5, s_6, s_7 and s_8 there is only one transition, so also there no reduction is possible.

Hence, $ample(s_i) = Act(s_i)$ for every state s_i , and the reduced system equals the original system.