

# Bisimulation

## Lecture #22 of Model Checking

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## Overview Lecture #22

⇒ Bisimulation equivalence

- Quotient transition system

# Implementation relations

- A *binary relation* on transition systems
  - when does a transition systems correctly implements another?
- Important for system *synthesis*
  - stepwise *refinement* of a system specification  $TS$  into an “implementation”  $TS'$
- Important for system *analysis*
  - use the implementation relation as a means for *abstraction*
  - replace  $TS \models \varphi$  by  $TS' \models \varphi$  where  $|TS'| \ll |TS|$  such that:

$$TS \models \varphi \text{ iff } TS' \models \varphi \quad \text{or} \quad TS' \models \varphi \Rightarrow TS \models \varphi$$

⇒ Focus on state-based *bisimulation* and *simulation*

- definition: what is bisimulation?
- logical characterization: which logical formulas are preserved by bisimulation?

## Bisimulation equivalence

Let  $TS_i = (S_i, Act_i, \rightarrow_i, I_i, AP, L_i)$ ,  $i=1, 2$ , be transition systems

A *bisimulation* for  $(TS_1, TS_2)$  is a binary relation  $\mathcal{R} \subseteq S_1 \times S_2$  such that:

1.  $\forall s_1 \in I_1 \exists s_2 \in I_2. (s_1, s_2) \in \mathcal{R}$  and  $\forall s_2 \in I_2 \exists s_1 \in I_1. (s_1, s_2) \in \mathcal{R}$
2. for all states  $s_1 \in S_1, s_2 \in S_2$  with  $(s_1, s_2) \in \mathcal{R}$  it holds:
  - (a)  $L_1(s_1) = L_2(s_2)$
  - (b) if  $s'_1 \in Post(s_1)$  then there exists  $s'_2 \in Post(s_2)$  with  $(s'_1, s'_2) \in \mathcal{R}$
  - (c) if  $s'_2 \in Post(s_2)$  then there exists  $s'_1 \in Post(s_1)$  with  $(s'_1, s'_2) \in \mathcal{R}$

$TS_1$  and  $TS_2$  are bisimilar, denoted  $TS_1 \sim TS_2$ , if there exists a bisimulation for  $(TS_1, TS_2)$

## Bisimulation equivalence

$$s_1 \rightarrow s'_1$$

$$\mathcal{R}$$

$$s_2$$

can be completed to

$$s_1 \rightarrow s'_1$$

$$\mathcal{R}$$

$$s_2 \rightarrow s'_2$$

and

$$s_1$$

$$\mathcal{R}$$

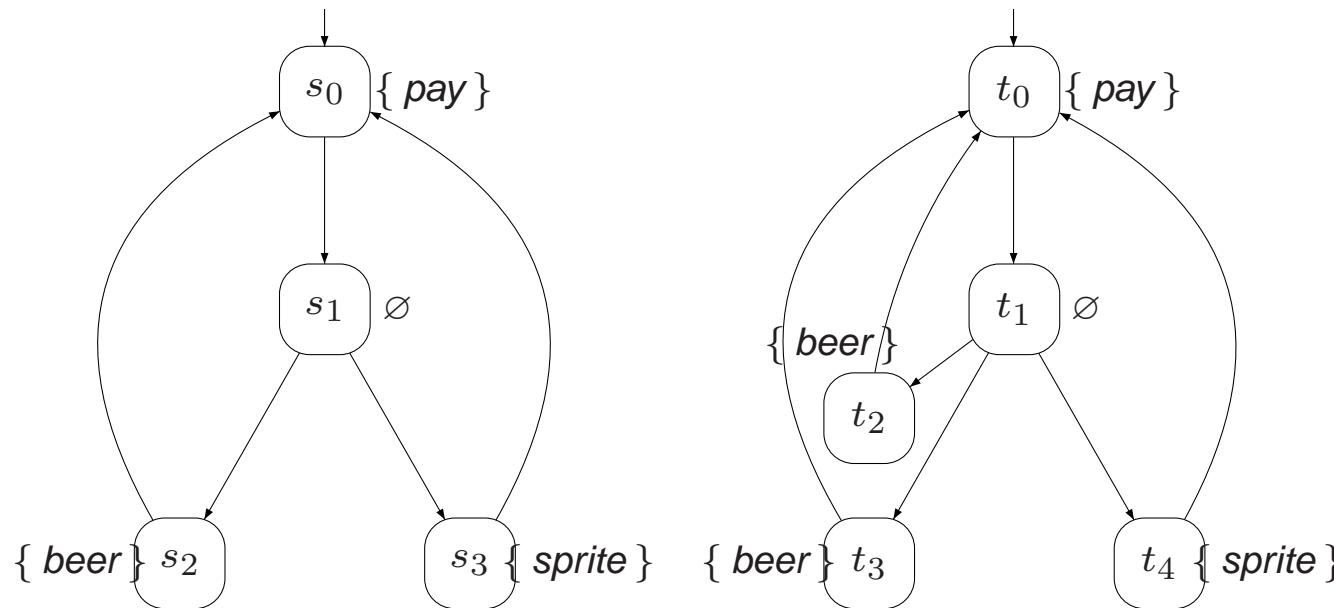
$$s_2 \rightarrow s'_2$$

$$s_1 \rightarrow s'_1$$

$$\mathcal{R}$$

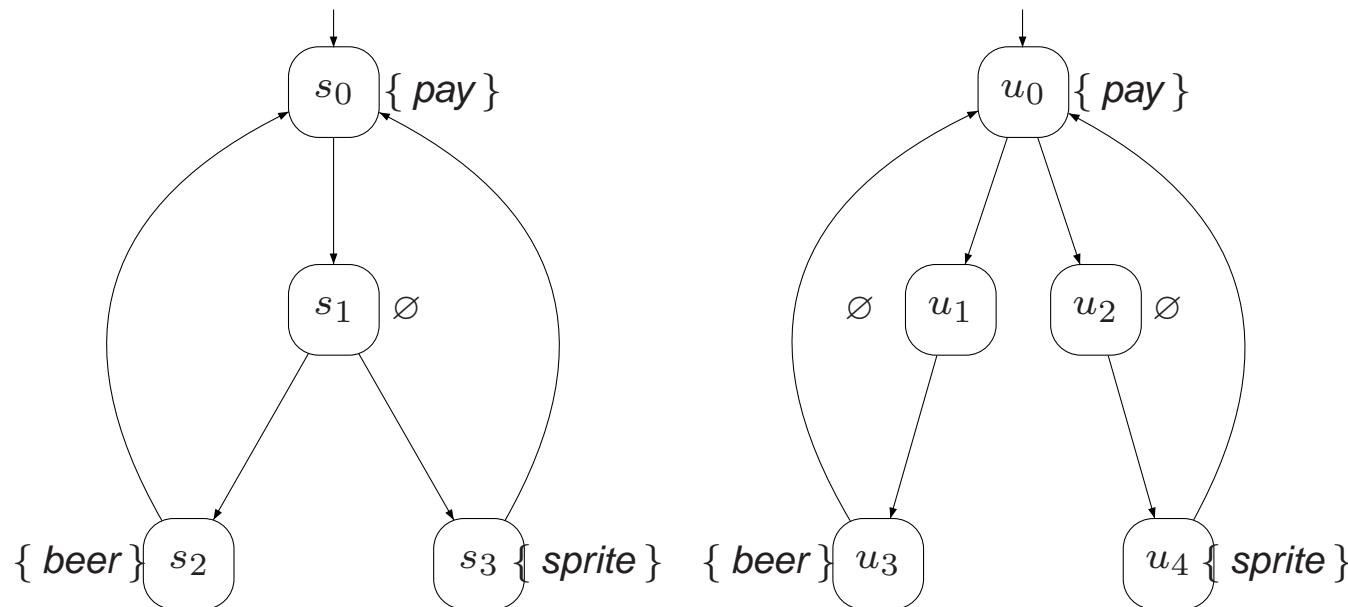
$$s_2 \rightarrow s'_2$$

## Example (1)



is a bisimulation for  $(TS_1, TS_2)$  where  $AP = \{ pay, beer, sprite \}$

## Example (2)



$TS_1 \not\sim TS_3$  for  $AP = \{ pay, beer, sprite \}$

But:  $\{ (s_0, u_0), (s_1, u_1), (s_1, u_2), (s_2, u_3), (s_2, u_4), (s_3, u_3), (s_3, u_4) \}$

is a bisimulation for  $(TS_1, TS_3)$  for  $AP = \{ pay, drink \}$

## $\sim$ is an equivalence

For any transition systems  $TS$ ,  $TS_1$ ,  $TS_2$  and  $TS_3$  over  $AP$ :

$TS \sim TS$  (reflexivity)

$TS_1 \sim TS_2$  implies  $TS_2 \sim TS_1$  (symmetry)

$TS_1 \sim TS_2$  and  $TS_2 \sim TS_3$  implies  $TS_1 \sim TS_3$  (transitivity)

## Bisimulation on paths

Whenever we have:

$$\begin{array}{ccccccc} s_0 & \rightarrow & s_1 & \rightarrow & s_2 & \rightarrow & s_3 \rightarrow s_4 \dots \dots \\ & & \mathcal{R} & & & & \\ t_0 & & & & & & \end{array}$$

this can be completed to

$$\begin{array}{ccccccc} s_0 & \rightarrow & s_1 & \rightarrow & s_2 & \rightarrow & s_3 \rightarrow s_4 \dots \dots \\ \mathcal{R} & & \mathcal{R} & & \mathcal{R} & & \mathcal{R} \\ t_0 & \rightarrow & t_1 & \rightarrow & t_2 & \rightarrow & t_3 \rightarrow t_4 \dots \dots \end{array}$$

proof: by induction on index  $i$  of state  $s_i$

## Bisimulation vs. trace equivalence

$TS_1 \sim TS_2$  implies  $Traces(TS_1) = Traces(TS_2)$

bisimilar transition systems thus satisfy the same LT properties!

## Overview Lecture #22

- Bisimulation equivalence

⇒ Quotient transition system

## Bisimulation on states

$\mathcal{R} \subseteq S \times S$  is a *bisimulation* on  $TS$  if for any  $(s_1, s_2) \in \mathcal{R}$ :

- $L(s_1) = L(s_2)$
- if  $s'_1 \in Post(s_1)$  then there exists an  $s'_2 \in Post(s_2)$  with  $(s'_1, s'_2) \in \mathcal{R}$
- if  $s'_2 \in Post(s_2)$  then there exists an  $s'_1 \in Post(s_1)$  with  $(s'_1, s'_2) \in \mathcal{R}$

$s_1$  and  $s_2$  are *bisimilar*,  $s_1 \sim_{TS} s_2$ , if  $(s_1, s_2) \in \mathcal{R}$  for some bisimulation  $\mathcal{R}$  for  $TS$

$s_1 \sim_{TS} s_2 \quad \text{if and only if} \quad TS_{s_1} \sim TS_{s_2}$

## Coarsest bisimulation

$\sim_{TS}$  is an equivalence and the coarsest bisimulation for  $TS$

## Quotient transition system

For  $TS = (S, Act, \rightarrow, I, AP, L)$  and bisimulation  $\sim_{TS} \subseteq S \times S$  on  $TS$  let

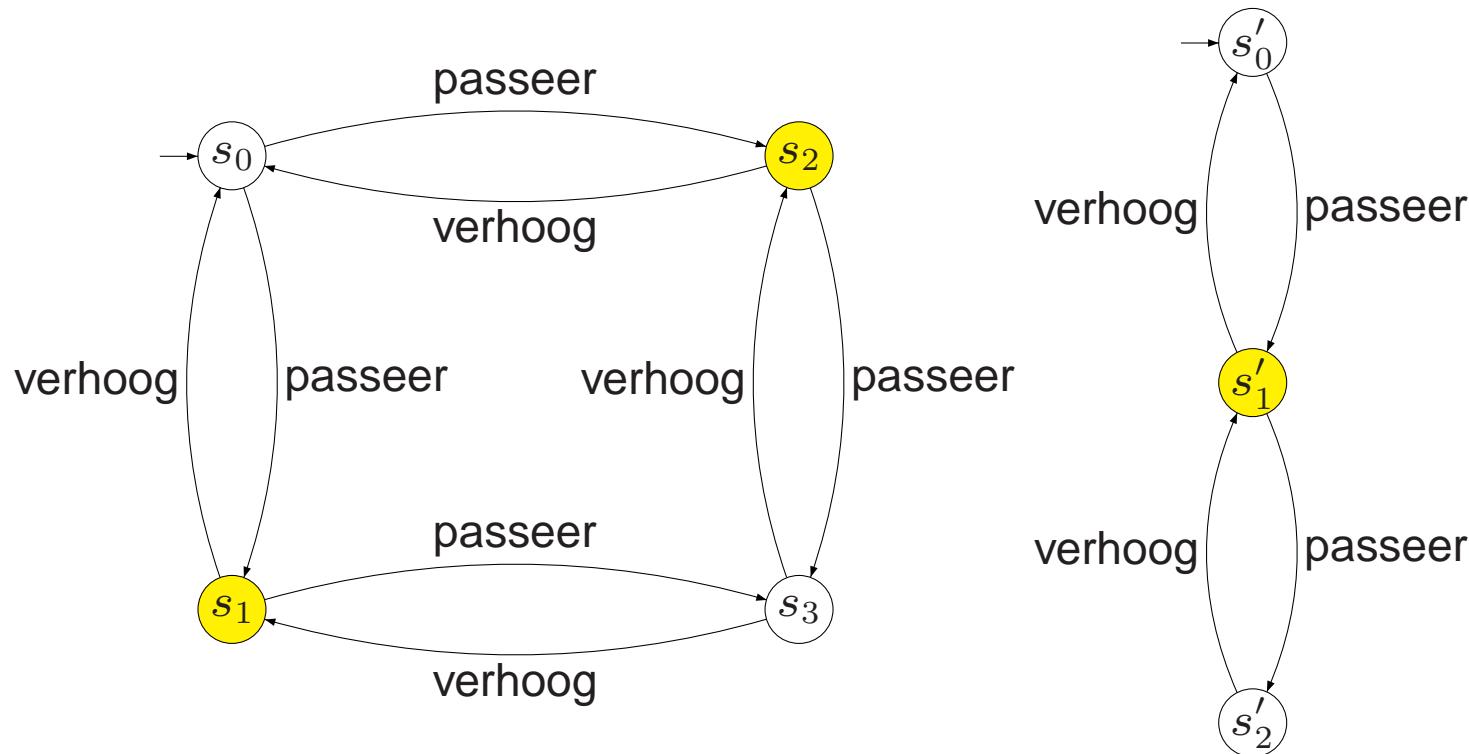
$TS/\sim_{TS} = (S', \{\tau\}, \rightarrow', I', AP, L')$ , the *quotient* of  $TS$  under  $\sim_{TS}$

where

- $S' = S/\sim_{TS} = \{[s]_{\sim} \mid s \in S\}$  with  $[s]_{\sim} = \{s' \in S \mid s \sim_{TS} s'\}$
- $\rightarrow'$  is defined by: 
$$\frac{s \xrightarrow{\alpha} s'}{[s]_{\sim} \xrightarrow{\tau'} [s']_{\sim}}$$
- $I' = \{[s]_{\sim} \mid s \in I\}$
- $L'([s]_{\sim}) = L(s)$

note that  $TS \sim TS/\sim_{TS}$  Why?

## A ternary semaphore and its quotient



# The Bakery algorithm

Process 1:

```
.....
while true {  
    .....
    n1 :  $x_1 := x_2 + 1;$   

    w1 : wait until( $x_2 = 0 \mid\mid x_1 < x_2$ ) {  

    c1 : ... critical section ...}  

     $x_1 := 0;$   

    .....
}  

while true {  
    .....
    n2 :  $x_2 := x_1 + 1;$   

    w2 : wait until( $x_1 = 0 \mid\mid x_2 < x_1$ ) {  

    c2 : ... critical section ...}  

     $x_2 := 0;$   

    .....
}
```

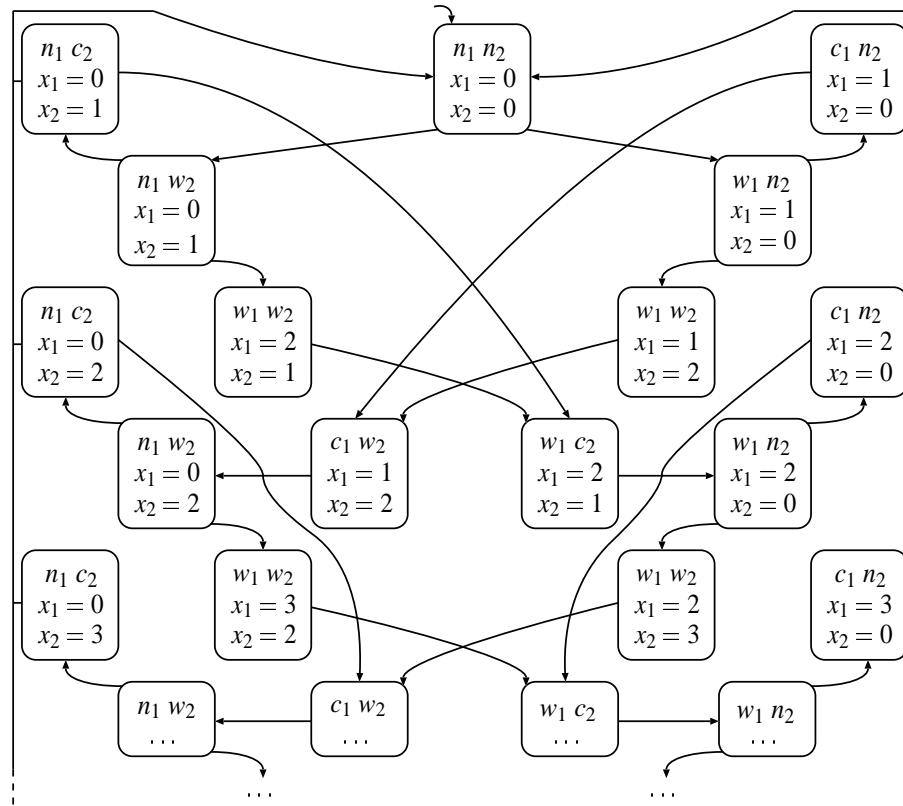
Process 2:

this algorithm can be applied to arbitrary many processes

## Example path fragment

process $P_1$	process $P_2$	$x_1$	$x_2$	effect
$n_1$	$n_2$	0	0	$P_1$ requests access to critical section
$w_1$	$n_2$	1	0	$P_2$ requests access to critical section
$w_1$	$w_2$	1	2	$P_1$ enters the critical section
$c_1$	$w_2$	1	2	$P_1$ leaves the critical section
$n_1$	$w_2$	0	2	$P_1$ requests access to critical section
$w_1$	$w_2$	3	2	$P_2$ enters the critical section
$w_1$	$c_2$	3	2	$P_2$ leaves the critical section
$w_1$	$n_2$	3	0	$P_2$ requests access to critical section
$w_1$	$w_2$	3	4	$P_2$ enters the critical section
...	...	..	..	...

## Bakery algorithm transition system



infinite state space due to possible unbounded increase of counters

## Data abstraction

Function  $f$  maps a reachable state of  $TS_{Bak}$  onto an abstract one in  $TS_{Bak}^{abs}$

Let  $s = \langle \ell_1, \ell_2, x_1 = b_1, x_2 = b_2 \rangle$  be a state of  $TS_{Bak}$  with  $\ell_i \in \{ n_i, w_i, c_i \}$  and  $b_i \in \mathbb{N}$

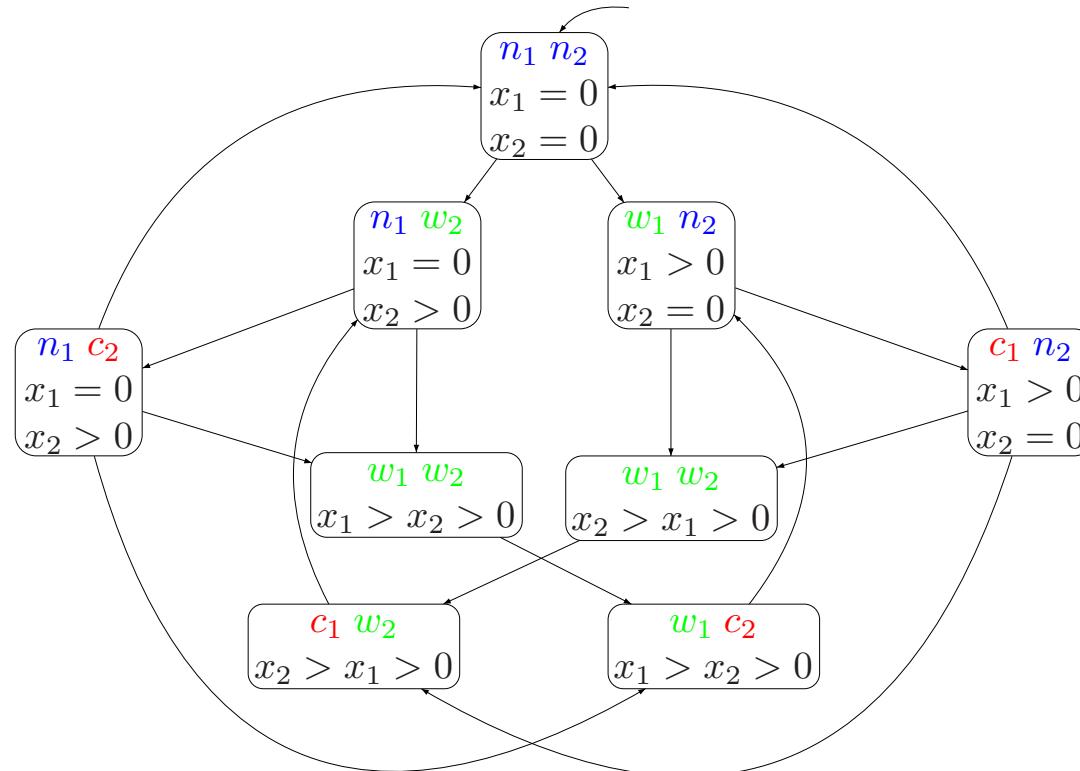
Then:

$$f(s) = \begin{cases} \langle \ell_1, \ell_2, x_1 = 0, x_2 = 0 \rangle & \text{if } b_1 = b_2 = 0 \\ \langle \ell_1, \ell_2, x_1 = 0, x_2 > 0 \rangle & \text{if } b_1 = 0 \text{ and } b_2 > 0 \\ \langle \ell_1, \ell_2, x_1 > 0, x_2 = 0 \rangle & \text{if } b_1 > 0 \text{ and } b_2 = 0 \\ \langle \ell_1, \ell_2, x_1 > x_2 > 0 \rangle & \text{if } b_1 > b_2 > 0 \\ \langle \ell_1, \ell_2, x_2 > x_1 > 0 \rangle & \text{if } b_2 > b_1 > 0 \end{cases}$$

It follows:  $\mathcal{R} = \{ (s, f(s)) \mid s \in S \}$  is a bisimulation for  $(TS_{Bak}, TS_{Bak}^{abs})$

for any subset of  $AP = \{ \text{noncrit}_i, \text{wait}_i, \text{crit}_i \mid i = 1, 2 \}$

## Bisimulation quotient



$$TS_{Bak}^{abs} = TS_{Bak} / \sim \quad \text{for} \quad AP = \{ crit_1, crit_2 \}$$

## Remarks

- Data abstraction yields a bisimulation relation
  - in this example; typically a simulation relation is obtained
- $TS_{Bak}^{abs} \models \varphi$  with, e.g.,:
  - $\square(\neg crit_1 \vee \neg crit_2)$  and  $(\square\lozenge wait_1 \Rightarrow \square\lozenge crit_1) \wedge (\square\lozenge wait_2 \Rightarrow \square\lozenge crit_2)$
- Since  $TS_{Bak}^{abs} \sim TS_{Bak}$ , it follows  $TS_{Bak} \models \varphi$
- Note:  $Traces(TS_{Bak}^{abs}) = Traces(TS_{Bak})$ 
  - but checking trace equivalence is **PSPACE-complete**
  - while checking bisimulation equivalence is in poly-time