

Modeling Concurrent and Probabilistic Systems

Lecture 3: Equivalence of CCS Processes

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Summer Semester 2009

- 1 Repetition: Syntax and Semantics of CCS
- 2 Recursive Processes
- 3 Equivalence of CCS Processes

Definition (Syntax of CCS)

- Let N be a set of (action) names.
- $\overline{N} := \{\overline{a} \mid a \in N\}$ denotes the set of co-names.
- $Act := N \cup \overline{N} \cup \{\tau\}$ is the set of actions where τ denotes the silent (or: unobservable) action.
- Let Pid be a set of process identifiers.
- The set Prc of process expressions is defined by the following syntax:

$P ::= \text{nil}$	(inaction)
$\quad \alpha.P$	(prefixing)
$\quad P_1 + P_2$	(choice)
$\quad P_1 \parallel P_2$	(parallel composition)
$\quad \text{new } a P$	(restriction)
$\quad A(a_1, \dots, a_n)$	(process call)

where $\alpha \in Act$, $a, a_i \in N$, and $A \in Pid$.

Definition (continued)

- A **(recursive) process definition** is an equation system of the form

$$(A_i(a_{i1}, \dots, a_{in_i}) = P_i \mid 1 \leq i \leq k)$$

where $k \geq 1$, $A_i \in Pid$ (pairwise different), $a_{ij} \in N$ (a_{i1}, \dots, a_{in_i} pairwise different), and $P_i \in Proc$ (with process identifiers from $\{A_1, \dots, A_k\}$).

Repetition: Labeled Transition Systems

Goal: represent behavior of system by (infinite) graph

- nodes = system states
- edges = transitions between states

Definition (Labeled transition system)

A (*Act*-)labeled transition system (LTS) is a triple $(S, Act, \longrightarrow)$ consisting of

- a set S of **states**
- a set Act of (**action**) **labels**
- a **transition relation** $\longrightarrow \subseteq S \times Act \times S$

For $(s, \alpha, s') \in \longrightarrow$ we write $s \xrightarrow{\alpha} s'$. An LTS is called **finite** if S is so.

Remarks:

- sometimes an **initial state** $s_0 \in S$ is distinguished
- (finite) LTSs correspond to (finite) **automata** without final states

Repetition: Semantics of CCS I

Definition (Semantics of CCS)

A process definition $(A_i(a_{i1}, \dots, a_{in_i}) = P_i \mid 1 \leq i \leq k)$ determines the LTS $(Prc, Act, \longrightarrow)$ whose transitions can be inferred from the following rules ($P, P', Q, Q' \in Prc$, $\alpha \in Act$, $\lambda \in N \cup \overline{N}$, $a \in N$):

$$(Act) \frac{}{\alpha.P \xrightarrow{\alpha} P}$$

$$(Com) \frac{P \xrightarrow{\lambda} P' \quad Q \xrightarrow{\overline{\lambda}} Q'}{P \parallel Q \xrightarrow{\tau} P' \parallel Q'}$$

$$(Sum_1) \frac{P \xrightarrow{\alpha} P'}{P + Q \xrightarrow{\alpha} P'}$$

$$(Sum_2) \frac{Q \xrightarrow{\alpha} Q'}{P + Q \xrightarrow{\alpha} Q'}$$

$$(Par_1) \frac{P \xrightarrow{\alpha} P'}{P \parallel Q \xrightarrow{\alpha} P' \parallel Q}$$

$$(Par_2) \frac{Q \xrightarrow{\alpha} Q'}{P \parallel Q \xrightarrow{\alpha} P \parallel Q'}$$

$$(New) \frac{P \xrightarrow{\alpha} P' \quad (\alpha \notin \{a, \overline{a}\})}{\text{new } a \, P \xrightarrow{\alpha} \text{new } a \, P'}$$

$$(Call) \frac{P[\vec{a} \mapsto \vec{b}] \xrightarrow{\alpha} P'}{A(\vec{b}) \xrightarrow{\alpha} P'} \text{ if } A(\vec{a}) = P$$

(Here $P[\vec{a} \mapsto \vec{b}]$ denotes the replacement of every a_i by b_i in P .)

Example

- ❶ One-place buffer:

$$B(in, out) = in.\overline{out}.B(in, out)$$

- ❷ Sequential two-place buffer:

$$B_0(in, out) = in.B_1(in, out)$$

$$B_1(in, out) = \overline{out}.B_0(in, out) + in.B_2(in, out)$$

$$B_2(in, out) = \overline{out}.B_1(in, out)$$

- ❸ Parallel two-place buffer:

$$B_{\parallel}(in, out) = \text{new } com (B(in, com) \parallel B(com, out))$$

$$B(in, out) = in.\overline{out}.B(in, out)$$

(on the board)

Example (continued)

Complete LTS of parallel two-place buffer:

$$\begin{array}{ccc}
 B_{\parallel}(in, out) & & \text{new } com(B(in, com) \parallel B(com, out)) \\
 \downarrow in \quad \swarrow in \quad \uparrow \overline{out} & & \\
 \text{new } com(\overline{com}.B(in, com) \parallel & \xrightarrow{\tau} & \text{new } com(B(in, com) \parallel \\
 B(com, out)) & & \overline{out}.B(com, out)) \\
 \nwarrow \overline{out} \quad \swarrow in & & \\
 \text{new } com(\overline{com}.B(in, com) \parallel & & \overline{out}.B(com, out))
 \end{array}$$

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Recursive Processes

Here: recursive processes defined using **equations** such as

$$B(in, out) = in.\overline{out}.B(in, out)$$

(simultaneous recursion)

Alternative: explicit **fixpoint operator**

- syntax: $P ::= \text{nil} \mid \dots \mid \text{fix } A P \in \text{Prec}$ (where $A \in \text{Pid}$)

- semantics: $(\text{Fix}) \frac{P[A \mapsto P] \xrightarrow{\alpha} P'}{\text{fix } A P \xrightarrow{\alpha} \text{fix } A P'}$

- example: $(\text{Act}) \frac{\text{in}.\overline{out}.\text{in}.\overline{out}.B \xrightarrow{\text{in}} \overline{out}.\text{in}.\overline{out}.B}{\text{fix } B \text{ in}.\overline{out}.B \xrightarrow{\text{in}} \text{fix } B \overline{out}.\text{in}.\overline{out}.B}$

(nested scalar recursion)

Advantage: only process term level required (no equations)
 \implies simplification of theory

Disadvantage: bad readability of process definitions

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Goal: identify process expressions which have the same “meaning” but differ in their syntax

Definition 3.1 (Equivalence relation)

Let $\cong \subseteq S \times S$ be a binary relation over some set S . Then \cong is called an **equivalence relation** if it is

- **reflexive**, i.e., $s \cong s$ for every $s \in S$,
- **symmetric**, i.e., $s \cong t$ implies $t \cong s$ for every $s, t \in S$, and
- **transitive**, i.e., $s \cong t$ and $t \cong u$ implies $s \cong u$ for every $s, t, u \in S$.

Equivalence of CCS Processes

- **Generally:** two syntactic objects are equivalent if they have the same “meaning”
- **Here:** two processes are equivalent if they have the same “behavior” (i.e., communication potential)
- Communication potential described by **LTS**
- **Idea:** define (for processes P, Q)
$$P \cong Q \text{ iff } LTS(P) = LTS(Q)$$
- **But:** yields too many distinctions:

Example 3.2

$$X(a) = a.X(a) \quad Y(a) = a.a.Y(a)$$



although both processes can (only) execute infinitely many a -actions, and should be considered **equivalent** therefore

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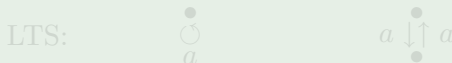
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$$\begin{array}{ccc} X(a) = a.X(a) & Y(a) = a.a.Y(a) \\ \text{LTS:} & \begin{array}{c} \bullet \\ \circlearrowleft \\ a \end{array} & \begin{array}{c} \bullet \\ a \downarrow \uparrow a \\ \bullet \end{array} \end{array}$$

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Desired Properties of Equivalence

Wanted: a “feasible” (i.e., efficiently decidable) semantic equivalence between CCS processes which

- 1 identifies processes whose **LTSs coincide**,
- 2 **implies trace equivalence**, i.e., considers two processes equivalent only if both can execute the same actions sequences (formal definition later), and
- 3 is a **congruence**, i.e., allows to replace a subprocess by an equivalent counterpart without changing the overall semantics of the system (formal definition later).

Formally: we are looking for a congruence relation $\cong \subseteq Proc \times Proc$ such that

$$LTS(P) = LTS(Q) \implies P \cong Q \implies Tr(P) = Tr(Q)$$

where $Tr(P)$ is the set of all traces of P (see Def. 4.1)

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Goal: replacing a subcomponent of a system by an equivalent process should yield an equivalent systems
 \implies modular system development

Definition 3.3 (CCS congruence)

An equivalence relation $\cong \subseteq \text{Prc} \times \text{Prc}$ is said to be a **CCS congruence** if it is preserved by the CCS constructs; that is, if $P, Q, R \in \text{Prc}$ such that $P \cong Q$ then

$$\begin{aligned}\alpha.P &\cong \alpha.Q \\ P + R &\cong Q + R \\ R + P &\cong R + Q \\ P \parallel R &\cong Q \parallel R \\ R \parallel P &\cong R \parallel Q \\ \text{new } a P &\cong \text{new } a Q\end{aligned}$$

for every $\alpha \in \text{Act}$ and $a \in N$.

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