

# Static Program Analysis

## Lecture 4: Dataflow Analysis III (The Framework)

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- 1 Repetition: Heading for a Dataflow Analysis Framework
- 2 Order-Theoretic Foundations: the Function
- 3 Application to Dataflow Analysis

# Similarities between Analysis Problems

- **Observation:** the analyses presented so far have some **similarities**

⇒ Look for underlying **framework**

- **Advantage:** possibility for designing (efficient) **generic algorithms for solving dataflow equations**
- **Overall pattern:** for  $c \in Cmd$  and  $l \in L_c$ , the **analysis information** (AI) is described by **equations** of the form

$$AI_l = \begin{cases} \iota & \text{if } l \in E \\ \bigsqcup \{ \varphi_{l'}(AI_{l'}) \mid (l', l) \in F \} & \text{otherwise} \end{cases}$$

where

- the set of **extremal labels**,  $E$ , is  $\{\text{init}(c)\}$  or  $\{\text{final}(c)\}$
- $\iota$  specifies the **extremal analysis information**
- the **combination operator**,  $\bigsqcup$ , is  $\cap$  or  $\cup$
- $\varphi_{l'}$  denotes the **transfer function** of block  $B_{l'}$
- the **flow relation**  $F$  is  $\text{flow}(c)$  or  $\text{flow}^R(c) (:= \{(l', l) \mid (l, l') \in \text{flow}(c)\})$

**Goal:** solve dataflow equation system by **fixpoint iteration**

- ① Characterize solution of equation system as **fixpoint** of a transformation
- ② Introduce **partial order** for comparing analysis results
- ③ Establish **least upper bound** as combination operator
- ④ Ensure **monotonicity** of transfer functions
- ⑤ Guarantee termination of fixpoint iteration by **ascending chain condition**
- ⑥ Optimize fixpoint iteration by **worklist algorithm**

- **Wanted:** solution of (dataflow) equation system
- **Problem:** recursive dependencies between dataflow variables
- **Idea:** characterize solution as fixpoint of transformation:

$$(AI_I = \tau_I)_{I \in L_c} \iff \Phi((AI_I)_{I \in L_c}) = (AI_I)_{I \in L_c}$$

where  $\Phi((AI_I)_{I \in L_c}) := (\tau_I)_{I \in L_c}$

- **Approach:** approximate fixpoint by iteration

# Partial Orders

The domain of analysis information usually forms a partial order where the ordering relation compares the “precision” of information.

## Definition (Partial order)

A **partial order (PO)**  $(D, \sqsubseteq)$  consists of a set  $D$ , called **domain**, and of a relation  $\sqsubseteq \subseteq D \times D$  such that, for every  $d_1, d_2, d_3 \in D$ ,

**reflexivity:**  $d_1 \sqsubseteq d_1$

**transitivity:**  $d_1 \sqsubseteq d_2$  and  $d_2 \sqsubseteq d_3 \implies d_1 \sqsubseteq d_3$

**antisymmetry:**  $d_1 \sqsubseteq d_2$  and  $d_2 \sqsubseteq d_1 \implies d_1 = d_2$

It is called **total** if, in addition, always  $d_1 \sqsubseteq d_2$  or  $d_2 \sqsubseteq d_1$ .

## Example

- ①  $(\mathbb{N}, \leq)$  is a total partial order
- ②  $(\mathbb{N}, <)$  is not a partial order (since not reflexive)
- ③ (Live Variables)  $(2^{Var_c}, \sqsubseteq)$  is a (non-total) partial order
- ④ (Available Expressions)  $(2^{AExp_c}, \supseteq)$  is a (non-total) partial order

# Upper Bounds

In the dataflow equation system, analysis information from several predecessors is combined by taking the least upper bound.

## Definition ((Least) upper bound)

Let  $(D, \sqsubseteq)$  be a partial order and  $S \subseteq D$ .

- 1 An element  $d \in D$  is called an **upper bound** of  $S$  if  $s \sqsubseteq d$  for every  $s \in S$  (notation:  $S \sqsubseteq d$ ).
- 2 An upper bound  $d$  of  $S$  is called **least upper bound (LUB)** or **supremum** of  $S$  if  $d \sqsubseteq d'$  for every upper bound  $d'$  of  $S$  (notation:  $d = \bigsqcup S$ ).

## Example

- 1  $S \subseteq \mathbb{N}$  has a LUB in  $(\mathbb{N}, \leq)$  iff it is finite
- 2 (Live Variables)  $(D, \sqsubseteq) = (2^{Var_c}, \subseteq)$ . Given  $V_1, \dots, V_n \subseteq Var_c$ ,  
$$\bigsqcup \{V_1, \dots, V_n\} = \bigcup \{V_1, \dots, V_n\}$$
- 3 (Avail. Expr.)  $(D, \sqsubseteq) = (2^{AExp_c}, \supseteq)$ . Given  $A_1, \dots, A_n \subseteq AExp_c$ ,  
$$\bigsqcup \{A_1, \dots, A_n\} = \bigcap \{A_1, \dots, A_n\}$$

# Complete Lattices

Since  $\{\varphi_{I'}(AI_{I'}) \mid (I', I) \in F\}$  can contain arbitrary elements, the existence of least upper bounds must be ensured for arbitrary subsets.

## Definition (Complete lattice)

A **complete lattice** is a partial order  $(D, \sqsubseteq)$  such that all subsets of  $D$  have least upper bounds. In this case,

$$\perp := \bigsqcup \emptyset$$

denotes the **least element** of  $D$ .

## Example

- ①  $(\mathbb{N}, \leq)$  is not a complete lattice as, e.g.,  $\mathbb{N}$  does not have a LUB
- ② (Live Variables)  
 $(D, \sqsubseteq) = (2^{Var_c}, \sqsubseteq)$  is a complete lattice with  $\perp = \emptyset$
- ③ (Available Expressions)  
 $(D, \sqsubseteq) = (2^{AExp_c}, \supseteq)$  is a complete lattice with  $\perp = AExp_c$



Chains are generated by the approximation of the analysis information in the fixpoint iteration.

## Definition (Chain)

Let  $(D, \sqsubseteq)$  be a partial order. A subset  $S \subseteq D$  is called an **(ascending) chain** in  $D$  if, for every  $s_1, s_2 \in S$ ,

$$s_1 \sqsubseteq s_2 \text{ or } s_2 \sqsubseteq s_1$$

(that is,  $S$  is a totally ordered subset of  $D$ ).

## Example

- 1 Every  $S \subseteq \mathbb{N}$  is a chain in  $(\mathbb{N}, \leq)$
- 2  $\{\emptyset, \{0\}, \{0, 1\}, \{0, 1, 2\}, \dots\}$  is a chain in  $(2^{\mathbb{N}}, \subseteq)$
- 3  $\{\emptyset, \{0\}, \{1\}\}$  is not a chain in  $(2^{\mathbb{N}}, \subseteq)$

# The Ascending Chain Condition

Termination of fixpoint iteration is guaranteed by the Ascending Chain Condition.

## Definition (Ascending Chain Condition)

A partial order  $(D, \sqsubseteq)$  satisfies the **Ascending Chain Condition (ACC)** if each ascending chain  $d_1 \sqsubseteq d_2 \sqsubseteq \dots$  eventually stabilizes, i.e., there exists  $n \in \mathbb{N}$  such that  $d_n = d_{n+1} = \dots$

## Example

- ①  $(\mathbb{N}, \leq)$  does not satisfy ACC
- ② (Live Variables)  $(D, \sqsubseteq) = (2^{Var_c}, \subseteq)$  satisfies ACC since  $Var_c$  (unlike  $Var$ ) is finite
- ③ (Available Expressions)  $(D, \sqsubseteq) = (2^{AExp_c}, \supseteq)$  satisfies ACC since  $AExp_c$  (unlike  $AExp$ ) is finite

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# Monotonicity of Functions

The monotonicity of transfer functions excludes “oscillating behavior” in fixpoint iteration.

## Definition 4.1 (Monotonicity)

Let  $(D, \sqsubseteq)$  and  $(D', \sqsubseteq')$  be partial orders, and let  $\Phi : D \rightarrow D'$ .  $\Phi$  is called **monotonic (w.r.t.  $(D, \sqsubseteq)$  and  $(D', \sqsubseteq')$ )** if, for every  $d_1, d_2 \in D$ ,

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## Example 4.2

- 1 Let  $T := \{S \subseteq \mathbb{N} \mid S \text{ finite}\}$ . Then  $\Phi_1 : T \rightarrow \mathbb{N} : S \mapsto \sum_{n \in S} n$  is monotonic w.r.t.  $(2^{\mathbb{N}}, \subseteq)$  and  $(\mathbb{N}, \leq)$ .

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- 2  $\Phi_2 : 2^{\mathbb{N}} \rightarrow 2^{\mathbb{N}} : S \mapsto \mathbb{N} \setminus S$  is not monotonic w.r.t.  $(2^{\mathbb{N}}, \subseteq)$  (since, e.g.,  $\emptyset \subseteq \mathbb{N}$  but  $\Phi_2(\emptyset) = \mathbb{N} \not\subseteq \Phi_2(\mathbb{N}) = \emptyset$ ).

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- 3 (Live Variables)  $(D, \sqsubseteq) = (D', \sqsubseteq') = (2^{\text{Var}_c}, \subseteq)$   
Each transfer function  $\varphi_{l'}(V) := (V \setminus \text{kill}_{\text{LV}}(B'')) \cup \text{gen}_{\text{LV}}(B'')$  is obviously monotonic

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Each transfer function  $\varphi_{l'}(V) := (V \setminus \text{kill}_{\text{LV}}(B'')) \cup \text{gen}_{\text{LV}}(B'')$  is obviously monotonic
- 4 (Available Expressions)  $(D, \sqsubseteq) = (D', \sqsubseteq') = (2^{\text{AExp}_c}, \supseteq)$  ditto



## Definition 4.3 (Fixpoint)

Let  $D$  be some domain,  $d \in D$ , and  $\Phi : D \rightarrow D$ . If

$$\Phi(d) = d$$

then  $d$  is called a **fixpoint** of  $\Phi$ .

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## Example 4.4

The (only) fixpoints of  $\Phi : \mathbb{N} \rightarrow \mathbb{N} : n \mapsto n^2$  are 0 and 1

# The Fixpoint Theorem I



Alfred Tarski (1901–1983)



Bronislaw Knaster (1893–1990)

## Theorem 4.5 (Fixpoint Theorem by Tarski and Knaster)

Let  $(D, \sqsubseteq)$  be a complete lattice satisfying ACC and  $\Phi : D \rightarrow D$  monotonic. Then

$$\text{fix}(\Phi) := \bigsqcup \{ \Phi^k(\perp) \mid k \in \mathbb{N} \}$$

is the *least fixpoint of  $\Phi$*  where

$$\Phi^0(d) := d \text{ and } \Phi^{k+1}(d) := \Phi(\Phi^k(d)).$$

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is the **least fixpoint of  $\Phi$**  where

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**Remark:**  $\text{ACC} \implies (\Phi^k(\perp) \mid k \in \mathbb{N})$  stabilizes at some  $k_0 \in \mathbb{N}$  with  $\text{fix}(\Phi) = \Phi^{k_0}(\perp)$  (where  $k_0$  bounded by maximal chain length in  $(D, \sqsubseteq)$ )

# The Fixpoint Theorem II

The proof of Theorem 4.5 requires the following lemma.

## Lemma 4.6

*Let  $(D, \sqsubseteq)$  be a complete lattice satisfying ACC,  $S \subseteq D$  a chain, and  $\Phi : D \rightarrow D$  monotonic. Then*

$$\Phi(\bigsqcup S) = \bigsqcup \Phi(S)$$

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## Definition 4.7 (Dataflow system)

A **dataflow system**  $S = (L, E, F, (D, \sqsubseteq), \iota, \varphi)$  consists of

- a finite set of (program) **labels**  $L$  (here:  $L_c$ ),
- a set of **extremal labels**  $E \subseteq L$  (here:  $\{\text{init}(c)\}$  or  $\text{final}(c)$ ),
- a **flow relation**  $F \subseteq L \times L$  (here:  $\text{flow}(c)$  or  $\text{flow}^R(c)$ ),
- a **complete lattice**  $(D, \sqsubseteq)$  satisfying ACC (with LUB operator  $\sqcup$  and least element  $\perp$ ),
- an **extremal value**  $\iota \in D$  (for the extremal labels), and
- a collection of **monotonic transfer functions**  $\{\varphi_l \mid l \in L\}$  of type  $\varphi_l : D \rightarrow D$ .

## Example 4.8

| Problem       | Available Expressions  | Live Variables     |
|---------------|--|--------------------|
| $E$           | $\{\text{init}(c)\}$   | $\text{final}(c)$  |
| $F$           | $\text{flow}(c)$   | $\text{flow}^R(c)$ |
| $D$           | $2^{AExp_c}$   | $2^{Var_c}$        |
| $\sqsubseteq$ | $\supseteq$  | $\subseteq$        |
| $\sqcup$      | $\bigcap$  | $\bigcup$          |
| $\perp$       | $AExp_c$   | $\emptyset$        |
| $\iota$       | $\emptyset$  | $Var_c$            |
| $\varphi_I$   | $\varphi_I(d) = (d \setminus \text{kill}(B^I)) \cup \text{gen}(B^I)$ |                    |

## Definition 4.9 (Dataflow equation system)

Given: dataflow system  $S = (L, E, F, (D, \sqsubseteq), \iota, \varphi)$ ,  $L = \{1, \dots, n\}$  (w.l.o.g.)

- $S$  determines the **equation system** (where  $I \in L$ )

$$AI_I = \begin{cases} \iota & \text{if } I \in E \\ \bigsqcup \{ \varphi_{I'}(AI_{I'}) \mid (I', I) \in F \} & \text{otherwise} \end{cases}$$

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- $(d_1, \dots, d_n) \in D^n$  is called a **solution** if

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- $S$  determines the **transformation**

$$\Phi_S : D^n \rightarrow D^n : (d_1, \dots, d_n) \mapsto (d'_1, \dots, d'_n)$$

where

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## Corollary 4.10

$(d_1, \dots, d_n) \in D^n$  **solves** the equation system iff it is a **fixpoint** of  $\Phi_S$

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(where  $(d_1, \dots, d_n) \sqsubseteq^n (d'_1, \dots, d'_n)$  iff  $d_i \sqsubseteq d'_i$  for every  $1 \leq i \leq n$ )



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- Monotonicity of transfer functions  $\varphi_l$  in  $(D, \sqsubseteq)$  implies **monotonicity of  $\Phi_S$**  in  $(D^n, \sqsubseteq^n)$  (since  $\sqcup$  also monotonic)

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- Thus the **(least) fixpoint is effectively computable** by iteration:

$$\text{fix}(\Phi_S) = \sqcup \{ \Phi_S^k(\perp_{D^n}) \mid k \in \mathbb{N} \}$$

$$\text{where } \perp_{D^n} = \underbrace{(\perp_D, \dots, \perp_D)}_{n \text{ times}}$$

# Solving Dataflow Problems by Fixpoint Iteration

## Remarks:

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- If maximal length of chains in  $(D, \sqsubseteq)$  (= **height** of  $(D, \sqsubseteq)$ ) is  $m$   
 $\implies$  maximal length of chains in  $(D^n, \sqsubseteq^n)$  is  $m \cdot n$   
 $\implies$  **fixpoint iteration requires at most  $m \cdot n$  steps**

## Example 4.11 (Available Expressions; cf. Example 2.9)

Program:

```
c = [x := a+b]1;  
    [y := a*b]2;  
    while [y > a+b]3 do  
        [a := a+1]4;  
        [x := a+b]5
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# Example: Available Expressions

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Equation system:

$$AE_1 = \emptyset$$

$$AE_2 = AE_1 \cup \{a+b\}$$

$$AE_3 = (AE_2 \cup \{a*b\}) \cap (AE_5 \cup \{a+b\})$$

$$AE_4 = AE_3 \cup \{a+b\}$$

$$AE_5 = AE_4 \setminus \{a+b, a*b, a+1\}$$

# Example: Available Expressions

## Example 4.11 (Available Expressions; cf. Example 2.9)

Program:

```
c = [x := a+b]1;  
    [y := a*b]2;  
    while [y > a+b]3 do  
        [a := a+1]4;  
        [x := a+b]5
```

Equation system:

$$AE_1 = \emptyset$$

$$AE_2 = AE_1 \cup \{a+b\}$$

$$AE_3 = (AE_2 \cup \{a*b\}) \cap (AE_5 \cup \{a+b\})$$

$$AE_4 = AE_3 \cup \{a+b\}$$

$$AE_5 = AE_4 \setminus \{a+b, a*b, a+1\}$$

Fixpoint iteration:

| $i$ | 1        | 2        | 3        | 4        | 5        |
|-----|----------|----------|----------|----------|----------|
| 0   | $AExp_c$ | $AExp_c$ | $AExp_c$ | $AExp_c$ | $AExp_c$ |

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Fixpoint iteration:

| $i$ | 1           | 2        | 3        | 4        | 5           |
|-----|-------------|----------|----------|----------|-------------|
| 0   | $AExp_c$    | $AExp_c$ | $AExp_c$ | $AExp_c$ | $AExp_c$    |
| 1   | $\emptyset$ | $AExp_c$ | $AExp_c$ | $AExp_c$ | $\emptyset$ |

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|----------|-------------|-----------|-----------|----------|-------------|
| 0        | $AExp_c$    | $AExp_c$  | $AExp_c$  | $AExp_c$ | $AExp_c$    |
| 1        | $\emptyset$ | $AExp_c$  | $AExp_c$  | $AExp_c$ | $\emptyset$ |
| 2        | $\emptyset$ | $\{a+b\}$ | $\{a+b\}$ | $AExp_c$ | $\emptyset$ |



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| 1   | $\emptyset$ | $AExp_c$  | $AExp_c$  | $AExp_c$  | $\emptyset$ |
| 2   | $\emptyset$ | $\{a+b\}$ | $\{a+b\}$ | $AExp_c$  | $\emptyset$ |
| 3   | $\emptyset$ | $\{a+b\}$ | $\{a+b\}$ | $\{a+b\}$ | $\emptyset$ |

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| 0   | $AExp_c$    | $AExp_c$  | $AExp_c$  | $AExp_c$  | $AExp_c$    |
| 1   | $\emptyset$ | $AExp_c$  | $AExp_c$  | $AExp_c$  | $\emptyset$ |
| 2   | $\emptyset$ | $\{a+b\}$ | $\{a+b\}$ | $AExp_c$  | $\emptyset$ |
| 3   | $\emptyset$ | $\{a+b\}$ | $\{a+b\}$ | $\{a+b\}$ | $\emptyset$ |
| 4   | $\emptyset$ | $\{a+b\}$ | $\{a+b\}$ | $\{a+b\}$ | $\emptyset$ |

# Example: Live Variables

## Example 4.12 (Live Variables; cf. Example 3.3)

Program:

```
[x := 2]1; [y := 4]2;  
[x := 1]3;  
if [y > 0]4 then  
  [z := x]5  
else  
  [z := y*y]6;  
[x := z]7
```

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[x := z]7
```

Equation system:

```
LV1 = LV2 \ {y}  
LV2 = LV3 \ {x}  
LV3 = LV4 ∪ {y}  
LV4 = ((LV5 \ {z}) ∪ {x}) ∪ ((LV6 \ {z}) ∪ {y})  
LV5 = (LV7 \ {x}) ∪ {z}  
LV6 = (LV7 \ {x}) ∪ {z}  
LV7 = {x, y, z}
```

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LV5 = (LV7 \ {x}) ∪ {z}
LV6 = (LV7 \ {x}) ∪ {z}
LV7 = {x, y, z}
```

Fixpoint iteration:

| <i>i</i> | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|----------|---|---|---|---|---|---|---|
| 0        | ∅ | ∅ | ∅ | ∅ | ∅ | ∅ | ∅ |

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Fixpoint iteration:

| <i>i</i> | 1 | 2 | 3   | 4      | 5   | 6   | 7         |
|----------|---|---|-----|--------|-----|-----|-----------|
| 0        | ∅ | ∅ | ∅   | ∅      | ∅   | ∅   | ∅         |
| 1        | ∅ | ∅ | {y} | {x, y} | {z} | {z} | {x, y, z} |

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Fixpoint iteration:

| <i>i</i> | 1 | 2   | 3      | 4      | 5      | 6      | 7         |
|----------|---|-----|--------|--------|--------|--------|-----------|
| 0        | ∅ | ∅   | ∅      | ∅      | ∅      | ∅      | ∅         |
| 1        | ∅ | ∅   | {y}    | {x, y} | {z}    | {z}    | {x, y, z} |
| 2        | ∅ | {y} | {x, y} | {x, y} | {y, z} | {y, z} | {x, y, z} |

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| <i>i</i> | 1 | 2   | 3      | 4      | 5      | 6      | 7         |
|----------|---|-----|--------|--------|--------|--------|-----------|
| 0        | ∅ | ∅   | ∅      | ∅      | ∅      | ∅      | ∅         |
| 1        | ∅ | ∅   | {y}    | {x, y} | {z}    | {z}    | {x, y, z} |
| 2        | ∅ | {y} | {x, y} | {x, y} | {y, z} | {y, z} | {x, y, z} |
| 3        | ∅ | {y} | {x, y} | {x, y} | {y, z} | {y, z} | {x, y, z} |