

Static Program Analysis

Lecture 8: Dataflow Analysis VII (Interval Analysis & Widening)

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Summer Semester 2011

- 1 Repetition: Dataflow Analysis with Non-ACC Domains
- 2 Formalizing Interval Analysis
- 3 Applying Widening to Interval Analysis

- **Reminder:** $(D, \sqsubseteq)$ satisfies **ACC** if each ascending chain $d_1 \sqsubseteq d_2 \sqsubseteq \dots$ eventually stabilizes, i.e., there exists $n \in \mathbb{N}$ such that $d_n = d_{n+1} = \dots$
- If **height** (= maximal chain length) of $(D, \sqsubseteq)$ is m , then fixpoint computation terminates after $\leq |L| \cdot m$ iterations
- **But:** if $(D, \sqsubseteq)$ has **infinite ascending chains**
 $\implies$ algorithm may not terminate
- **Solution:** use **widening operators** to enforce termination

Definition (Widening operator)

Let $(D, \sqsubseteq)$ be a complete lattice. A mapping $\nabla : D \times D \rightarrow D$ is called **widening operator** if

- for every $d_1, d_2 \in D$,

$$d_1 \sqcup d_2 \sqsubseteq d_1 \nabla d_2$$

and

- for all ascending chains $d_0 \sqsubseteq d_1 \sqsubseteq \dots$, the ascending chain $d_0^\nabla \sqsubseteq d_1^\nabla \sqsubseteq \dots$ eventually stabilizes where

$$d_0^\nabla := d_0 \text{ and } d_{i+1}^\nabla := d_i^\nabla \nabla d_{i+1} \text{ for } i \in \mathbb{N}$$

Remarks:

- $(d_i^\nabla)_{i \in \mathbb{N}}$ is clearly an ascending chain as

$$d_{i+1}^\nabla = d_i^\nabla \nabla d_{i+1} \sqsupseteq d_i^\nabla \sqcup d_{i+1} \sqsupseteq d_i^\nabla$$

- In contrast to $\sqcup$, ∇ does not have to be commutative, associative, monotonic, nor absorptive ($d \nabla d = d$)
- The requirement $d_1 \sqcup d_2 \sqsubseteq d_1 \nabla d_2$ guarantees **soundness** of widening

The Domain of Interval Analysis

- The domain $(Int, \subseteq)$ of **intervals over $\mathbb{Z}$** is defined by

$$Int := \{[z_1, z_2] \mid z_1 \in \mathbb{Z} \cup \{-\infty\}, z_2 \in \mathbb{Z} \cup \{+\infty\}, z_1 \leq z_2\} \cup \{\emptyset\}$$

where

- $-\infty \leq z, z \leq +\infty$, and $-\infty \leq +\infty$ (for all $z \in \mathbb{Z}$)
 - $\emptyset \subseteq I$ (for all $I \in Int$)
 - $[y_1, y_2] \subseteq [z_1, z_2]$ iff $z_1 \leq y_1$ and $y_2 \leq z_2$
- $(Int, \subseteq)$ is a **complete lattice** with (for every $\mathcal{I} \subseteq Int$)

$$\bigsqcup \mathcal{I} = \begin{cases} \emptyset & \text{if } \mathcal{I} = \emptyset \text{ or } \mathcal{I} = \{\emptyset\} \\ [Z_1, Z_2] & \text{otherwise} \end{cases}$$

where

$$Z_1 := \bigsqcap_{\mathbb{Z} \cup \{-\infty\}} \{z_1 \mid [z_1, z_2] \in \mathcal{I}\}$$
$$Z_2 := \bigsqcap_{\mathbb{Z} \cup \{+\infty\}} \{z_2 \mid [z_1, z_2] \in \mathcal{I}\}$$

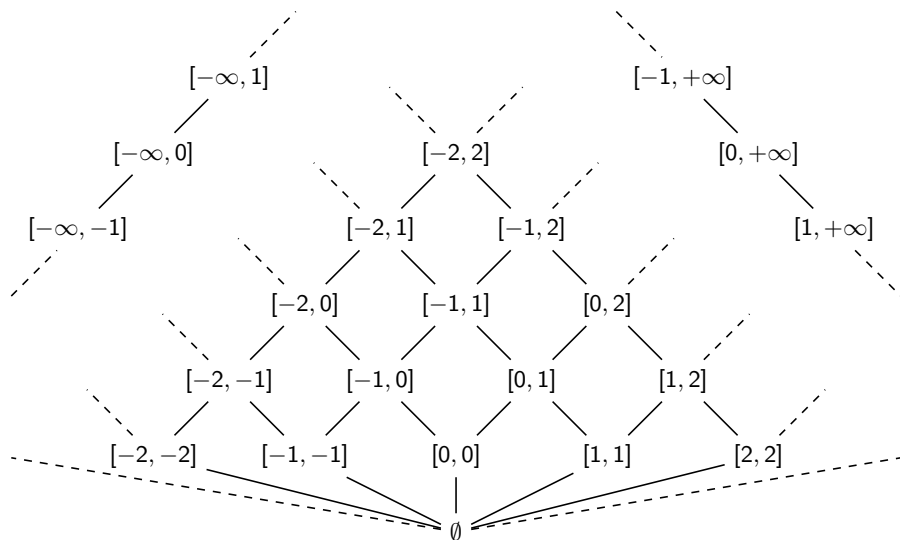
(and thus $\perp = \emptyset$, $\top = [-\infty, +\infty]$)

- Clearly $(Int, \subseteq)$ has **infinite ascending chains**, such as

$$\emptyset \subseteq [1, 1] \subseteq [1, 2] \subseteq [1, 3] \subseteq \dots$$

The Complete Lattice of Interval Analysis

$[-\infty, +\infty]$



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The **dataflow system** $S = (L, E, F, (D, \sqsubseteq), \iota, \varphi)$ is given by

- set of labels $L := L_c$,
- extremal labels $E := \{\text{init}(c)\}$ (forward problem),
- flow relation $F := \text{flow}(c)$ (forward problem),
- complete lattice $(D, \sqsubseteq)$ where
 - $D := \{\delta \mid \delta : \text{Var}_c \rightarrow \text{Int}\}$
 - $\delta_1 \sqsubseteq \delta_2$ iff $\delta_1(x) \subseteq \delta_2(x)$ for every $x \in \text{Var}_c$
- $\iota := \top_D : \text{Var}_c \rightarrow \text{Int} : x \mapsto \top_{\text{Int}} = [-\infty, +\infty]$
- φ : see next slide

Formalizing Interval Analysis II

Transfer functions $\{\varphi_I \mid I \in L\}$ are defined by

$$\varphi_I(\delta) := \begin{cases} \delta & \text{if } B^I = \text{skip} \text{ or } B^I \in BExp \\ \delta[x \mapsto \text{val}_\delta(a)] & \text{if } B^I = (x := a) \end{cases}$$

where

$$\begin{aligned} \text{val}_\delta(x) &:= \delta(x) & \text{val}_\delta(a_1 + a_2) &:= \text{val}_\delta(a_1) \oplus \text{val}_\delta(a_2) \\ \text{val}_\delta(z) &:= [z, z] & \text{val}_\delta(a_1 - a_2) &:= \text{val}_\delta(a_1) \ominus \text{val}_\delta(a_2) \\ & & \text{val}_\delta(a_1 * a_2) &:= \text{val}_\delta(a_1) \odot \text{val}_\delta(a_2) \end{aligned}$$

with

$$\begin{aligned} \emptyset \oplus I &:= I \oplus \emptyset := \emptyset \ominus I := \dots := \emptyset \\ [y_1, y_2] \oplus [z_1, z_2] &:= [y_1 + z_1, y_2 + z_2] \\ [y_1, y_2] \ominus [z_1, z_2] &:= [y_1 - z_2, y_2 - z_1] \\ [y_1, y_2] \odot [z_1, z_2] &:= [\min_{y \in [y_1, y_2], z \in [z_1, z_2]} y \cdot z, \max_{y \in [y_1, y_2], z \in [z_1, z_2]} y \cdot z] \end{aligned}$$

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Remarks:

- Possible **refinement of DFA** to take conditional blocks b^I into account
 - essentially: b as edge label, $\varphi_I(\delta)(x) = \delta(x) \setminus \{z \in \mathbb{Z} \mid x = z \implies \neg b\}$ (cf. “Conditions and Assertions” later)
- Important: **soundness and optimality** of abstract operations
 - soundness: $z_1 \in l_1, z_2 \in l_2 \implies z_1 + z_2 \in l_1 \oplus l_2$
 - optimality: $l_1 \oplus l_2$ as small as possible

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Applying Widening to Interval Analysis

- A **widening operator**: $\nabla : Int \times Int \rightarrow Int$ with
$$\emptyset \nabla I := I \nabla \emptyset := I$$
$$[x_1, x_2] \nabla [y_1, y_2] := [z_1, z_2] \quad \text{where}$$
$$z_1 := \begin{cases} x_1 & \text{if } x_1 \leq y_1 \\ -\infty & \text{otherwise} \end{cases}$$
$$z_2 := \begin{cases} x_2 & \text{if } y_2 \leq x_2 \\ +\infty & \text{otherwise} \end{cases}$$

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- Widening turns infinite ascending chain

$$I_0 = \emptyset \subseteq I_1 = [1, 1] \subseteq I_2 = [1, 2] \subseteq I_3 = [1, 3] \subseteq \dots$$

into a finite one:

$$I_0^\nabla = I_0 = \emptyset$$

$$I_1^\nabla = I_0^\nabla \nabla I_1 = \emptyset \nabla [1, 1] = [1, 1]$$

$$I_2^\nabla = I_1^\nabla \nabla I_2 = [1, 1] \nabla [1, 2] = [1, +\infty]$$

$$I_3^\nabla = I_2^\nabla \nabla I_3 = [1, +\infty] \nabla [1, 3] = [1, +\infty]$$

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$$\emptyset \nabla I := I \nabla \emptyset := I$$

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into a finite one:

$$I_0^\nabla = I_0 = \emptyset$$

$$I_1^\nabla = I_0^\nabla \nabla I_1 = \emptyset \nabla [1, 1] = [1, 1]$$

$$I_2^\nabla = I_1^\nabla \nabla I_2 = [1, 1] \nabla [1, 2] = [1, +\infty]$$

$$I_3^\nabla = I_2^\nabla \nabla I_3 = [1, +\infty] \nabla [1, 3] = [1, +\infty]$$

- In fact, the maximal chain length arising with this operator is 4:

$$\emptyset \subseteq [3, 7] \subseteq [3, +\infty] \subseteq [-\infty, +\infty]$$

Worklist Algorithm with Widening I

Goal: extend Algorithm 5.2 by widening to ensure termination

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Variables: $W \in (L \times L)^*$, $\{AI_I \in D \mid I \in L\}$

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Procedure: $W := \varepsilon$; **for** $(l, l') \in F$ **do** $W := W \cdot (l, l')$; % Initialize W
for $l \in L$ **do** % Initialize AI
 if $l \in E$ **then** $AI_l := \iota$ **else** $AI_l := \perp_D$;

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for $I \in L$ **do** % Initialize AI
 if $I \in E$ **then** $AI_I := \iota$ **else** $AI_I := \perp_D$;
while $W \neq \varepsilon$ **do**
 $(I, I') := \text{head}(W)$; $W := \text{tail}(W)$;
 if $\varphi_I(AI_I) \not\sqsubseteq AI_{I'}$ **then** % Fixpoint not yet reached
 $AI_{I'} := AI_{I'} \nabla \varphi_I(AI_I)$;
 for $(I', I'') \in F$ **do**
 if (I', I'') not in W **then** $W := (I', I'') \cdot W$;

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Output: $\{AI_I \mid I \in L\}$, denoted by $\text{fix}^\nabla(\Phi_S)$

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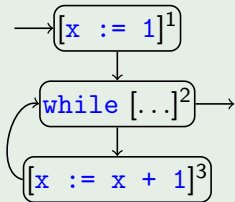
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 if (I', I'') not in W **then** $W := (I', I'') \cdot W$;

Output: $\{AI_I \mid I \in L\}$, denoted by $\text{fix}^\nabla(\Phi_S)$

Remark: due to widening, only $\text{fix}(\Phi_S) \sqsubseteq \text{fix}^\nabla(\Phi_S)$ is guaranteed (cf. Thm. 5.4)

Example 8.2



Transfer functions (for $\delta(\mathbf{x}) = I$):

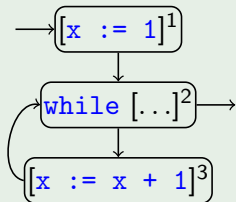
$$\varphi_1(I) = [1, 1]$$

$$\varphi_2(I) = I$$

$$\varphi_3(\emptyset) = \emptyset$$

$$\varphi_3([x_1, x_2]) = [x_1 + 1, x_2 + 1]$$

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Transfer functions (for $\delta(\mathbf{x}) = I$):

$$\varphi_1(I) = [1, 1]$$

$$\varphi_2(I) = I$$

$$\varphi_3(\emptyset) = \emptyset$$

$$\varphi_3([x_1, x_2]) = [x_1 + 1, x_2 + 1]$$

Application of worklist algorithm (on the board)

- ① without widening: does not terminate
- ② with widening: terminates with expected result for AI_2 ($[1, +\infty]$)