

### Exercise 1 (CSP Semantics):

(4 Points)

Consider the following CSP program  $c$ :

```
c :=
  y := 4; if (y > 0) → ((x := y) || (x := 3)) fi
  do (x == 3 ∧ α?x → β!x) □ (x == 3 → α!y) od
```

Provide all "meanings" of  $c$  using the formal semantics of CSP as given in the lecture.

### Exercise 2 (LTS and Deadlocks):

(2+1 Points)

The aim of this exercise is to develop a (simplified) model of a car's central locking system. Assume the following components:

- a door which is either open or closed
- a locker for the door which can be activated if the door is not open (otherwise an alarm should be issued), and
- a key which controls the whole mechanism.

- a) Design a corresponding process definition and give its transition system!
- b) Check if the car locking system you developed in part a.) has a deadlock. If this is the case, provide a deadlock free specification of the system.

### Exercise 3 (Parallel Composition of CCS):

(2+3 Points)

An engineer is charged with developing an elevator control for a building with five floors, starting with a CCS model. His subspecification for requesting the elevator and selecting the target floor looks as follows:

$$Elevator(req, f_1, \dots, f_5) = req.f_1.Elevator(req, f_1, \dots, f_5) + \dots + req.f_5.Elevator(req, f_1, \dots, f_5).$$

A computer scientist who was called for supporting the engineer suggests the following solution instead:

$$Elevator(req, f_1, \dots, f_5) = req.(f_1.Elevator(req, f_1, \dots, f_5) + \dots + f_5.Elevator(req, f_1, \dots, f_5)).$$

- a) Are both systems trace equivalent?
- b) Test the elevator subsystem together with the specification of a user who would like to reach the fourth floor:

$$User(req, f_4) = \overline{req}.f_4.nil.$$

Do both specifications of the elevator guarantee that the user is satisfied?