

Non-linear Real Arithmetic: Virtual Substitution

Prof. Dr. Erika Ábrahám and Florian Corzilius

January 22, 2012

Non-linear real arithmetic (NRA)

Real algebra

First-order theory of $(\mathbb{R}, +, \cdot, 0, 1, <)$

Syntax:

Terms: t	$:=$	0		1		x		$t + t$		$t \cdot t$
Constraints: c	$:=$	$t < t$								
Formulas: φ	$:=$	c		$\neg\varphi$		$\varphi \wedge \varphi$		$\exists x\varphi$		

where x is a variable.

The term **non-linear real arithmetic** is mainly used in the SMT community and is the non-linear existential fragment of real algebra.

- Systems of linear real constraints:

$$\exists x (Ax \leq b)$$

- Linear real optimization:

$$\exists x (Ax \leq b \wedge x \geq 0 \wedge \forall y (Ay \leq b \wedge y \geq 0 \rightarrow y \geq x))$$

- Geometric problems: intersection, union, ... of geometric shapes e.g.

$$\exists x, y (x^2 + 4y^2 = 1 \wedge x - y = 1)$$

Real algebra: on the border of decidability

Theorem (Alfred Tarski 1948)

FO *theory of* $(\mathbb{R}, +, \cdot, 0, 1, <)$ *is decidable.*

- The proof was first published in the book [Tarski1948].
- Time-complexity of a decision procedure in the number of variables would be “greater than all finite towers of powers of 2” [Feferman2006].

Already undecidable

FO theory of $(\mathbb{R}, +, \cdot, \sin, 0, 1, <)$

Real algebra: some historic facts

- 1637 Descartes' rule of signs
- 1835 Jaques Charles François Sturm's theorem
- 1948 Alfred Tarski's "A decision method for elementary algebra and geometry"
- 1975 Cylindrical algebraic decomposition (CAD) method by George E. Collins
- 1979–80 First implementation of the CAD method by Dennis S. Arnon
- 1988 Virtual substitution by Volker Weispfenning
- 1990 First implementation of virtual substitution (Klaus-Dieter Burhenne)
- 1993 Gröbner bases approach by P. Pedersen, M.-F. Roy, A. Szpirglas, later extended by V. Weispfenning
- 1994 Implementation of the Gröbner bases approach (Andreas Dolzmann)

Real algebra: implementations

Virtual substitution

- Computer logic system Redlog (package of Reduce)

Cylindrical algebraic decomposition

- QEPCAD, Redlog, ...

Gröbner bases

- Maple, Mathematica, Singular, Maxima, CoCoA, Reduce, ...

Other methods

- Interval arithmetic (Ariadne or HySAT)

The idea of quantifier elimination

Given: φ (FO sentence over $(\mathbb{R}, +, \cdot, 0, 1, <)$ containing n quantifiers)

- 1 Transform φ into prenex normal form:

$$\varphi \equiv Q_1 x_1 \dots Q_n x_n \varphi', \text{ with } \varphi' \text{ quantifier free}$$

- 2 Eliminate iteratively the quantifiers $Q_1 \dots Q_n$ and thus the quantified variables.

The idea of quantifier elimination

What if we can only eliminate existential quantifier?

$$\begin{aligned} & \exists x_1 \exists x_2 \forall x_3 \exists x_4 \forall x_5 \forall x_6 \exists x_7 \exists x_8 \quad \varphi' \\ \equiv & \exists x_1 \exists x_2 \neg(\exists x_3 \neg(\exists x_4 \neg(\exists x_5 \neg(\neg(\exists x_6 \neg(\exists x_7 \exists x_8 \quad \varphi' \quad)))))) \\ \equiv & \exists x_1 \exists x_2 \neg(\exists x_3 \neg(\exists x_4 \neg(\exists x_5 \exists x_6 \neg(\exists x_7 \exists x_8 \quad \varphi' \quad)))) \end{aligned}$$

Existential quantifier elimination: Brute force

- Given: $\varphi = \exists x_1 \dots \exists x_n \varphi'$, where φ' is an quantifier-free FO sentence over $(\mathbb{R}, +, \cdot, 0, 1, <)$
- Brute force: (elimination of one quantifier)

$$\exists x_1 \dots \exists x_n \varphi' \quad \equiv \quad \exists x_1 \dots \exists x_{n-1} \bigvee_{r \in \mathbb{R}} \varphi'[r/x].$$

- But: $\mathbb{R}$ is infinite.
- Idea: Find a finite set $T \subset \mathbb{R}$ with

$$\exists t \in T : \varphi[t/x] \quad \Leftrightarrow \quad \exists r \in \mathbb{R} : \varphi[r/x].$$

Virtual substitution

- Is an **existential quantifier elimination procedure**:

$$\exists x_1 \dots \exists x_n \varphi' \rightarrow \exists x_1 \dots \exists x_{n-1} \psi',$$

where φ', ψ' quantifier free and $\exists x_1 \dots \exists x_n \varphi' \equiv \exists x_1 \dots \exists x_{n-1} \psi'$.

- **Restricted in the degree** of the variable to eliminate:

$p(x) \sim 0$ constraint of $\varphi \Rightarrow$ degree of x in $p(x)$ must be ≤ 2 .

Virtual substitution

Virtual substitution constructs a finite set $T \subset \mathbb{R}$ of **test candidates** with

$$\exists x_1 \dots \exists x_n \varphi' \equiv \exists x_1 \dots \exists x_{n-1} \bigvee_{t \in T} \varphi'[t/x].$$

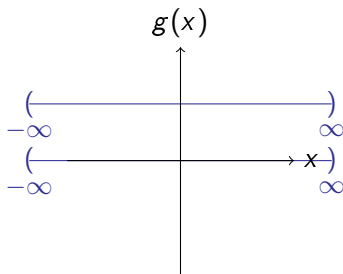
Construction of the set of test candidates T

1.) $g(x) = ax^2 + bx + c$ **constant** in x ($a = 0 \wedge b = 0$)

Consider the constraint: $g(x) = 0$ or $g(x) \leq 0$ or $g(x) < 0$
 $g(x) \geq 0$ or $g(x) > 0$ or $g(x) \neq 0$ $g(x) = 0$ or $g(x) \leq 0$ or $g(x) \geq 0$
 $g(x) < 0$ or $g(x) > 0$ or $g(x) \neq 0$

$c \geq 0$:

($c < 0$ analog)



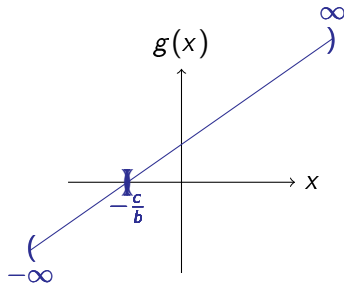
Construction of the set of test candidates T

2.) $g(x) = ax^2 + bx + c$ **linear** in x ($a = 0 \wedge b \neq 0$)

Consider the constraint: $g(x) = \leq < \geq > \neq 0$

$b > 0$:

($b < 0$ analog)



Construction of the set of test candidates T

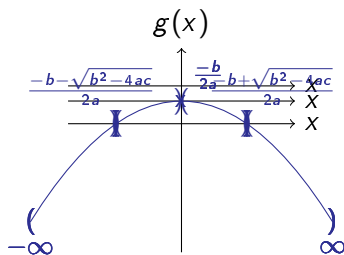
3.) $g(x) = ax^2 + bx + c$ **quadratic** in x ($a \neq 0$)

Consider the constraint: $g(x) = 0$ or $g(x) \geq 0$ or $g(x) > 0$ $g(x) \leq 0$ or
 $g(x) < 0$ or $g(x) \neq 0$ $g(x) \geq 0$ or $g(x) > 0$ $g(x) = 0$ $g(x) \leq 0$
 $g(x) < 0$ or $g(x) \neq 0$ $g(x) = 0$ $g(x) \leq 0$ $g(x) \geq 0$ $g(x) < 0$
 $g(x) > 0$ $g(x) \neq 0$

$a < 0$:

($a > 0$ analog)

$$b^2 - 4ac \geq 0$$



Construction of the set of test candidates T

Given: A constraint $p \sim 0$. $(p = ax^2 + bx + c, \sim \in \{=, <, >, \leq, \geq, \neq\})$.

The **finite endpoints** of its non-empty solution intervals are the zeros of p :

$$\text{Linear in } x : \quad x_0 = -\frac{c}{b} \quad , \text{ if } a = 0 \wedge b \neq 0$$

$$\text{Quadratic in } x, \text{ first solution: } \quad x_1 = \frac{-b + \sqrt{b^2 - 4ac}}{2a} \quad , \text{ if } a \neq 0 \wedge b^2 - 4ac \geq 0$$

$$\text{Quadratic in } x, \text{ second solution: } \quad x_2 = \frac{-b - \sqrt{b^2 - 4ac}}{2a} \quad , \text{ if } a \neq 0 \wedge b^2 - 4ac > 0$$

All possible **non-empty solution intervals** for x in $p \sim 0$:

constraints	possible solution intervals ($0 \leq i, j \leq 2, i \neq j$)				
$p = 0$	$[x_i, x_i] \quad (-\infty, \infty)$				
$p < 0 \quad p > 0$	$(-\infty, x_i)$	(x_i, x_j)	(x_i, ∞)	$(-\infty, \infty)$	
$p \neq 0$	$(-\infty, x_i)$		(x_i, ∞)	$(-\infty, \infty)$	
$p \leq 0 \quad p \geq 0$	$(-\infty, x_i]$	$[x_i, x_i]$	$[x_i, x_j]$	$[x_i, \infty)$	$(-\infty, \infty)$

Construction of the set of test candidates T

- Consider we have two constraints:

$$p^1 \sim^1 0 \quad \text{and} \quad p^2 \sim^2 0.$$

- When do they both hold?
- If the **intersection** of their solution intervals is **not empty**!
- Then the intersection consists of **at least one non-empty interval**.
- The interval's endpoints are **endpoints of the intersected intervals**.

Construction of the set of test candidates T

We search for a value fulfilling several constraints.

Idea: We search for the '**smallest value**' fulfilling the constraints.

- We know ..
 - .. that the solution space of the constraints is a set of intervals.
 - .. **the endpoints** of these intervals.
- Hence, the 'smallest value' fulfilling the constraints is
 - either a left endpoint of an left closed interval
 - or a left endpoint of an left opened interval plus an infinitesimal.

Construction of the set of test candidates T

Idea: We search for the '**smallest value**' fulfilling the constraints.

The constraints provide finitely many **test candidates**:

- $p = 0$

- 1 Zeros of the polynomial p

- $p \leq 0, p \geq 0$

- 1 Zeros of the polynomial p

- 2 $-\infty$ ($:=$ sufficient small value)

- $p < 0, p > 0, p \neq 0$

- 1 Zeros of the polynomial p plus an infinitesimal ϵ

- 2 $-\infty$

- Example: $xy + 1 < 0 \rightarrow \begin{cases} \frac{1}{y} + \epsilon & \text{if } y \neq 0 \\ -\infty \end{cases}$

Construction of the set of test candidates T

Example: $y \cdot x^2 + z \cdot x \geq 0$

- The finite endpoints are: $x_0 = x_1 = 0$ and $x_2 = -\frac{z}{y}$.
- The possible solution intervals are:

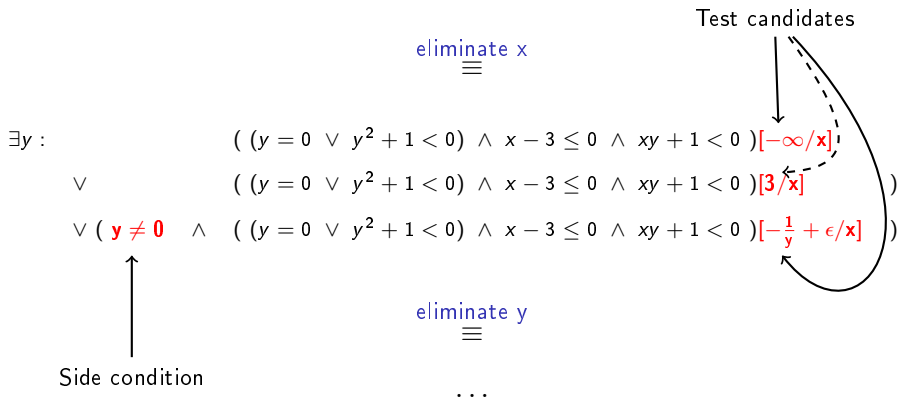
Case	Solution interval	Side condition
Constant	$(-\infty, \infty)$	$y = z = 0$
Linear	$(-\infty, 0]$ or $[0, \infty)$	$y = 0 \wedge z \neq 0$
Quadratic	$(-\infty, 0]$ or $[0, \infty)$	$y \neq 0 \wedge z^2 \geq 0$
Quadratic	$(-\infty, -\frac{z}{y}]$ or $[-\frac{z}{y}, \infty)$	$y \neq 0 \wedge z^2 > 0$

- The test candidates are:

Test candidate	Side condition
$-\infty$	none
0	$y = 0 \wedge z \neq 0$
0	$y \neq 0$
$-\frac{z}{y}$	$y \neq 0$

Construction of the set of test candidates T

Example: $\exists y \exists x : (y = 0 \vee y^2 + 1 < 0) \wedge x - 3 \leq 0 \wedge xy + 1 < 0$



How to substitute a variable by a test candidate in a constraint

- Standard substitution $\rightarrow$ expressions with ϵ , ∞ , $\sqrt{}$ or division.
- Virtual Substitution defines rules, which give an equivalent FO sentence over $(\mathbb{R}, +, \cdot, 0, 1, <)$ to the expression resulting by the above standard substitution.
- The substitution rules distinguish between
 - the constraint's relation symbol
 - the test candidate's type $(-\infty, +\epsilon, \text{contains } \sqrt{})$

Substitution of a variable by a test candidate in a constraint

Example: $(g(x) = 0)[\frac{q+r\sqrt{t}}{s}/x]$

Result: $(\hat{r} = 0 \wedge \hat{q} = 0) \vee (\hat{r} \neq 0 \wedge \hat{q}\hat{r} \leq 0 \wedge \hat{q}^2 - \hat{r}^2 t = 0)$,
where $\hat{q}$, $\hat{r}$, and $\hat{s}$ are polynomials.

Explanation:

- 1 Substitute x by $\frac{q+r\sqrt{t}}{s}$ in $g = 0$ in the common way.
- 2 Transform the result to $\frac{\hat{q}+\hat{r}\sqrt{t}}{\hat{s}} = 0$ where $\hat{q}$, $\hat{r}$, and $\hat{s}$ are polynomials (always possible, proof exercise)
- 3 Compare:

$$1 \quad \hat{r} = 0 \wedge \frac{\hat{q}+\hat{r}\sqrt{t}}{\hat{s}} = 0 \Leftrightarrow \hat{r} = 0 \wedge \frac{\hat{q}}{\hat{s}} = 0 \Leftrightarrow \hat{r} = 0 \wedge \hat{q} = 0$$

$$2 \quad \hat{r} \neq 0 \wedge \frac{\hat{q}+\hat{r}\sqrt{t}}{\hat{s}} = 0 \Leftrightarrow \hat{r} \neq 0 \wedge \hat{q} + \hat{r}\sqrt{t} = 0 \\ \Leftrightarrow \hat{r} \neq 0 \wedge \hat{r}\hat{q} \leq 0 \wedge \|\hat{q}\| = \|\hat{r}\sqrt{t}\|$$

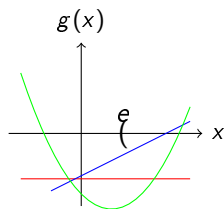
Substitution of a variable by a test candidate in a constraint

Example: $(g(x) < 0)[e + \epsilon/x]$

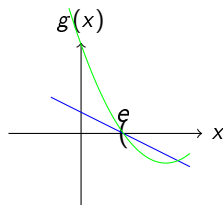
Result:

$$\underbrace{g[e/x] < 0}_{\text{Case 1}} \vee \underbrace{g[e/x] = 0 \wedge g'[e/x] < 0}_{\text{Case 2}} \vee \underbrace{g[e/x] = 0 \wedge g'[e/x] = 0 \wedge g''[e/x] < 0}_{\text{Case 3}}$$

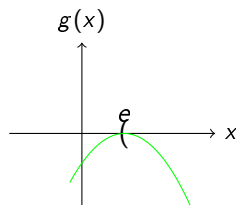
Explanation:



Case 1



Case 2



Case 3

Virtual Substitution: Example

$$\exists x, y ((xy - 1 = 0 \vee y - x \geq 0) \wedge y^2 - 1 < 0)$$

Eliminate y :

1. Test candidate: $-\infty$

$$\begin{aligned} \exists x(& ((xy - 1 = 0)[-\infty/y] \\ & \vee (y - x \geq 0)[-\infty/y]) \\ & \wedge (y^2 - 1 < 0)[-\infty/y]) \end{aligned}$$

1. Test candidate: $-\infty$

$$\begin{aligned} \exists x(& ((y = 0 \wedge -1 = 0) \\ & \vee (1 < 0 \vee (1 = 0 \wedge -x > 0)) \end{aligned}$$

Virtual Substitution: Example

$$\exists x (((x > 0 \text{False} \wedge x - x^2 \geq 0) \vee (x < 0 \text{True} \wedge x - x^2 \leq 0 \text{True})) \wedge 1 - x^2 < 0 \text{True} \wedge x \neq 0 \text{True})$$

Eliminate x :

1. Test candidate: $-\infty$

$$\begin{aligned} & (x > 0)[- \infty / x] \\ &= (1 < 0 \vee (1 = 0 \wedge 0 > 0)) \\ &= \text{False} \end{aligned}$$

1. Test candidate: $-\infty$

$$(x < 0)[- \infty / x]$$

We consider in the following the elimination of one existential quantifier (existentially quantified variable):

$$\exists x_1 \dots \exists x_n \varphi' \quad \equiv \quad \exists x_1 \dots \exists x_{n-1} \bigvee_{t \in T} \varphi'[t/x].$$

- Degree of a remaining variable x_i , $1 \leq i < n$, in φ' , i.e. $D(x_i, \varphi')$:

$$D(x_i, \bigvee_{t \in T} \varphi'[t/x]) \in \mathcal{O}(6D(x_i, \varphi') - 8)$$

- Number of atoms in φ' , i.e. $at(\varphi')$:

$$at(\bigvee_{t \in T} \varphi'[t/x]) \in \mathcal{O}(8at(\varphi') + at(\varphi')(8 + 63at(\varphi')))$$

References

-  S. Feferman. *Tarski's influence on computer science*. Logical Methods in Computer Science, 2006.
-  A. Dolzmann, T. Sturm, V. Weispfenning. *Real Quantifier Elimination in Practice*. 1997.
-  Alfred Tarski. *A Decision Method for Elementary Algebra and Geometry*. University of California Press, 1948.
-  Christopher W. Brown and James H. Davenport. The complexity of quantifier elimination and cylindrical algebraic decomposition. In Dongming Wang, editor, *ISSAC*, pages 54–60. ACM, 2007.
-  M. O. Rabin. *A simple method for undecidability proofs and some applications*. Logic, Methodology and Philosophy of Science II, 1965.